Ocean Observer STATIONARY PLATFORM ADCP

Remotely Monitor Ocean Currents throughout the Water Column



Frequency	Range (m)	Cell Size (m) 24		
38kHz	>1000			
75kHz	700	16		
150kHz	400	8		



The only platform-mounted ADCP to provide:

- The deepest current profiling available to assist in production and rig safety.
- Two forms of signal processing: patented Broadband for high precision; standard Narrowband for extended range.
- Field-proven technology that operates in the high-noise environment of oil platform production.
- A track record second to none; the Ocean Observer has been adopted by all the major oil companies on every type of platform.
- Patented phased-array transducer, for extended range in a powerful yet compact package.



a service of

A Teledyne Technologies Company

RD INSTRUMENTS

Ocean Observer

STATIONARY PLATFORM ADCP

Technical Specifications

Water Profiling						
Long Range Mode	38kHz		75kHz		150kHz	
Vertical Resolution Cell Size ¹ (m)	Max Range ² (m)	Precision ³ (cm/s)	Max Range² (m)	Precision ³ (cm/s)	Max Range² (m)	Precision ³ (cm/s)
4					350	30
8			650	30	400	19
16	>1000	30	700	17		
24	>1000	20				
High Precision Mode	38kHz		75kHz		150kHz	
Vertical Resolution Cell Size ¹ (m)	Max Range ² (m)	Precision ³ (cm/s)	Max Range² (m)	Precision ³ (cm/s)	Max Range² (m)	Precision ³ (cm/s)
4					250	12
8			430	12	275	8
16	730	12	450	8		
24	780	9				

¹User's choice of depth cell size is not limited to the typical values specified. ²Ranges are typical and vary with situation. ³Single-ping standard deviation.

Profile Parameters

 Velocity accuracy (typical):

 ±1.0% ± 0.5cm/s

 Velocity range: ±7m/s

 Number of depth cells: 1–128

 Maximum ping rate (Hz):

 38kHz
 75kHz

 0.4
 0.7

Bottom Track

Maximum altitude (precision <2cm/s):</th>38kHz75kHz150kHz1700m950m600mRange accuracy = <±2% actual range*</td>

Echo Intensity Profile

Dynamic range: 80dB **Precision:** ± 1.5dB

* Excludes errors introduced by changes in speed of sound profile, by tilting of transducer, and by slope of bottom.

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Transducer and Hardware

Beam angle: 30° Configuration: 4-beam, phased array Communications: RS-232 or RS-422 at 1200-115,200 baud Hex-ASCII or binary.

System Power

AC input: 90–250VAC, 47–63Hz Power: 1400W

Software

Use Teledyne RDI's Windows[™]-based software for the best results; VMDAS— Vessel Mount Data Acquisition System; WinADCP—Data Display and Export

Environmental

Operating temperature: -5° to 45°C **Storage temperature*:** -30° to 60°C **Standard depth rating:** 100m * *Without batteries*

* Without batteries

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Standard Sensors

- Temperature (mounted on transducer): Range: -5° to 45°C Precision: ±0.1°C Resolution: 0.03°
- Tilt: Range: ±50° Accuracy: ±1.0° Precision: ±0.1° Resolution: 0.1°
- Compass (fluxgate type): Accuracy: ±5° (up to ±20° tilt) Precision: ±0.3° Resolution: 0.01° Maximum tilt: ±50°

System Components

- 38, 75, or 150kHz transducer
- 19" rack-mount electronic chassis
- 100m long transducer underwater cable (300m long cable optional)

User may supply external compass input or GPS navigation data and NMEA tilt information.



Dimensions







Free 24/7 emergency support

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480mm