SBE 19plus
SEACAT Profiler

Conductivity, Temperature, and Pressure Recorder with RS-232 Interface

User’s Manual
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Manual Version #009, 11/15/02
Firmware Version 1.4B and later
Limited Liability Statement

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Section 1: Introduction

This section includes contact information, Quick Start procedure, and photos of a standard SBE 19plus shipment.

About this Manual

This manual is to be used with the SBE 19plus SEACAT Profiler Conductivity, Temperature, and Pressure Recorder.

It is organized to guide the user from installation through operation and data collection. We’ve included detailed specifications, command descriptions, maintenance and calibration information, and helpful notes throughout the manual.

Sea-Bird welcomes suggestions for new features and enhancements of our products and/or documentation. Please e-mail any comments or suggestions to seabird@seabird.com.

How to Contact Sea-Bird

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(1600 to 0100 Universal Time)
Except from April to October, when we are on summer time
(1500 to 0000 Universal Time)

Quick Start

Follow these steps to get a Quick Start using the SBE 19plus.
The manual provides step-by-step details for performing each task:

1. Install batteries and test power and communications (see Section 3: Power and Communications Test).

2. Deploy the SBE 19plus (see Section 4: Deploying and Operating SBE 19plus):
   A. Install new batteries if necessary.
   B. Ensure all data has been uploaded, and then send INITLOGGING to make entire memory available for recording if desired.
   C. Set date and time and establish setup and logging parameters.
   D. Moored mode - Set SBE 19plus to start logging now or in the future.
   E. Install dummy plugs and/or cable connectors, and locking sleeves.
   F. Remove Tygon tubing that was looped end-to-end around conductivity cell for storage. Reconnect tubing from pump to conductivity cell.
   G. Profiling mode - Put magnetic switch in On position, send commands to start logging now or in the future, or apply external power, as appropriate for your instrument’s setup.
   H. Deploy SBE 19plus.
Unpacking SBE 19plus

Shown below is a typical SBE 19plus shipment.

SBE 19plus SEACAT with SBE 5M pump

I/O Cable

9-pin adapter

Spare parts kit

Cell cleaning solution (Triton-X)

Cell filling and storage kit

SBE 19plus Manual

Software and Software Manuals
Section 2: Description of SBE 19plus

This section describes the functions and features of the SBE 19plus SEACAT Profiler, including specifications and dimensions.

System Description

The SBE 19plus SEACAT Profiler is designed to measure conductivity, temperature, and pressure in marine or fresh-water environments at depths up to 7000 meters (22,900 feet). The SBE 19plus operates in two modes:

- **Profiling mode** for acquiring vertical profiles of parameters. The SBE 19plus runs continuously, and samples at four scans per second (4 Hz). The SBE 19plus can be set to average up to 32,767 samples, storing and transmitting only the averaged data.

- **Moored mode** for acquiring time series measurements at sample rates of once every 10 seconds to once every 4 hours, adjustable in 1-second increments. Between samples, the SBE 19plus powers down, drawing only 30 microamps of current.

Self-powered and self-contained, the SBE 19plus features the proven Sea-Bird conductivity and temperature sensors and a precision, semiconductor, strain-gauge pressure sensor. Nine D-size alkaline batteries provide 60 hours operation in profiling mode; the 8 Mbyte FLASH RAM records 50 hours of conductivity, temperature, and pressure data while sampling at four scans per second (other configurations/setups vary). The SBE 19plus’ three-wire RS-232C interface provides simultaneous, real-time monitoring. Setup, diagnostics, and data extraction are performed without opening the housing. The SBE 19plus can power and acquire the outputs of external sensors.

SBE 19plus logging is started by sliding the On/Off switch, by command via the RS-232 interface, or by applying external power, depending on your setup of the instrument.

A standard SBE 19plus is supplied with:

- Plastic housing for depths to 600 meters (1950 feet)
- Strain-gauge pressure sensor
- 8 Mbyte FLASH RAM memory
- 9 D-size alkaline batteries
- Impulse glass-reinforced epoxy bulkhead connectors: one 4-pin I/O connector; one 2-pin pump connector; and two 6-pin connectors (for two differential auxiliary A/D inputs each)
- T-C Duct, which ensures that Temperature and Conductivity measurements are made on the same parcel of water
- SBE 5M miniature submersible pump for pumped conductivity; by fixing the flow to a constant rate, the pump ensures a constant conductivity time response. *The duct and pump combination results in dramatically lower salinity spiking.*
SBE 19\textit{plus} options include:

- Titanium housing for use to 7000 meters (22,900 feet)
- SBE 5T submersible pump for use with dissolved oxygen and/or other pumped sensors
- Sensors for dissolved oxygen, pH, fluorescence, light (PAR), light transmission, and turbidity
- Bulkhead connector for use with PAR sensor
- Stainless steel cage
- Wet-pluggable (MCBH) connectors in place of standard glass-reinforced epoxy connectors
- Ni-Cad batteries and charger
- Moored mode conversion kit with anti-foulant device fittings, for when SBE 19\textit{plus} used on moorings

The SBE 19\textit{plus} can be used with the following Sea-Bird equipment:

- **SBE 32 Carousel Water Sampler and SBE 33 Carousel Deck Unit** - The SBE 32 provides +15 VDC power to the SBE 19\textit{plus} and has ample power for auxiliary sensors not normally supported by battery-powered CTDs. The CTD data from the SBE 19\textit{plus} is converted into single-wire telemetry for transmission over long (10,000 meter [32,800 feet]) sea cables. Bottles may be closed at any depth without interrupting CTD data via software control using the SEASAVE program or from the front panel of the SBE 33 Deck Unit. See the SBE 33 manual for system operating details.
Section 2: Description of SBE 19plus

- **SBE 36 CTD Deck Unit and PN 90227 Power Data Interface Module (PDIM)** - These items provide power and real-time data handling capability over single-conductor sea cables using the same method employed in the SBE 32/SBE 33. The PDIM is a small pressure housing that is mounted on or near the SBE 19plus. It provides +15 VDC power to the SBE 19plus and interfaces two-way RS-232 communications from the SBE 19plus to the telemetry used on the sea cable. See the SBE 36/PDIM manual for system operating details.

- **SBE 32 Carousel Water Sampler and 90208 Auto Fire Module (AFM)** - The AFM, mounted on or near the SBE 19plus, allows the SBE 32 to operate autonomously on non-conducting cables. The AFM supplies the power, logic, and control commands to operate the SBE 32. The AFM monitors the pressure data recorded by the SBE 19plus in real-time, closing water sampler bottles at predefined pressures (depths) or whenever the system is stationary for a specified period of time. Bottle number, firing confirmation, and five scans of CTD data are recorded in the AFM memory for each bottle fired. See the AFM manual for system operating details.
User-selectable output format is raw data or engineering units, in either hexadecimal or decimal form. Additionally, the SBE 19 plus can be factory-configured to emulate the older SEACAT data output format, providing compatibility with existing customer SEACAT data processing software.

The SBE 19 plus is supplied with a powerful Win 95/98/NT/2000/XP software package, SEASOFT-Win32, which includes:

- **SEATERM** – terminal program for easy communication and data retrieval.
- **SEASAVE** – program for acquiring, converting, and displaying real-time or archived raw data.
- **SBE Data Processing** - program for calculation and plotting of conductivity, temperature, pressure, auxiliary sensor data, and derived variables such as salinity and sound velocity.

**Notes:**
- Help files provide detailed information on the use of SEATERM, SEASAVE, and SBE Data Processing.
- Separate software manuals on CD-ROM contain detailed information on the setup and use of SEASAVE and SBE Data Processing.
- Sea-Bird also supplies a DOS software package, SEASOFT-DOS. However, SEASOFT-DOS’ data processing modules cannot process SBE 19 plus data because of data output format incompatibility.
### Specifications

<table>
<thead>
<tr>
<th>Measurement Range</th>
<th>Temperature (°C)</th>
<th>Conductivity (S/m)</th>
<th>Strain Gauge Pressure</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>-5 to +35</td>
<td>0 to 9</td>
<td>0 to full scale range: 20 / 100 / 350 / 1000 / 2000 / 3500 / 7000 meters</td>
</tr>
<tr>
<td>Initial Accuracy</td>
<td>0.005</td>
<td>0.0005</td>
<td>0.1% of full scale range</td>
</tr>
<tr>
<td>Typical Stability (per month)</td>
<td>0.0002</td>
<td>0.0003</td>
<td>0.004% of full scale range</td>
</tr>
<tr>
<td>Resolution</td>
<td>0.0001</td>
<td>0.00005 (most oceanic waters: resolves 0.4 ppm in salinity)</td>
<td>0.002% of full scale range</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0.00007 (high salinity waters: resolves 0.4 ppm in salinity)</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>0.00001 (fresh waters: resolves 0.1 ppm in salinity)</td>
<td></td>
</tr>
<tr>
<td>Sensor Calibration</td>
<td>+1 to +32</td>
<td>0 to 9; physical calibration over range 1.4 to 6 S/m, plus zero conductivity (air)</td>
<td>Ambient pressure to full scale range in 5 steps</td>
</tr>
<tr>
<td>(measurement outside these ranges may be at slightly reduced accuracy due to extrapolation errors)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Memory</td>
<td>8 Mbyte non-volatile FLASH memory</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Data Storage</td>
<td>Recorded Parameter</td>
<td>Bytes/sample</td>
<td></td>
</tr>
<tr>
<td></td>
<td>temperature + conductivity</td>
<td>6 (3 each)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>strain-gauge pressure</td>
<td>5</td>
<td></td>
</tr>
<tr>
<td></td>
<td>each external voltage</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>date and time (Moored mode only)</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>Real-Time Clock</td>
<td>32,768 Hz TCXO accurate to ±1 minute/year</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Internal Batteries</td>
<td>Nine alkaline D-cells provide 60 hours continuous CTD operation. Optional Ni-Cad battery pack provides approximately 24 hours operation per charge.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>External Power Supply</td>
<td>9 - 28 VDC</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Power Requirements</td>
<td>Sampling</td>
<td>65 mA</td>
<td></td>
</tr>
<tr>
<td></td>
<td>SBE 5M pump</td>
<td>95 mA</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Quiescent</td>
<td>30 µA</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Actual sampling (non-quiescent) time in Moored mode is 3.0 seconds/sample (if configured with no delays and 1 measurement per sample).</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Auxiliary Voltage Sensors</td>
<td>Auxiliary power out: up to 500 mA at 10.5 - 11 VDC A/D resolution: 14 bits</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Housing Materials</td>
<td>Input range: 0 - 5 VDC</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>600 meter (1950 ft) - acetal copolymer (plastic)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>7000 meter (22,900 ft) - 3AL-2.5V titanium</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Weight</td>
<td>With plastic housing: 7.3 kg (16 lbs)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>With titanium housing: 13.7 kg (30 lbs)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Dimensions and End Cap Connectors

Dimensions in millimeters (inches)
Section 2: Description of SBE 19plus

Magnetic Reed Switch

Profiling Mode

A magnetic switch, mounted on the conductivity cell guard, can be used to start and stop logging in Profiling mode. Sliding the switch to the On position wakes up the SBE 19plus and starts logging. Sliding the switch to the Off position stops logging. The magnetic switch should be Off (towards the sensor end cap) when the SBE 19plus is not logging data; i.e., during setup, diagnostics, and data extraction.

The SBE 19plus can be set up to ignore the position of the magnetic switch:

- **When IGNORESWITCH=Y**: logging is started and stopped with commands sent through the terminal program. The position of the magnetic switch has no effect on logging.

- **When AUTORUN=Y**: logging is started and stopped when external power is applied and removed. The position of the magnetic switch has no effect on logging.

Moored Mode

Operation of the magnetic switch while in Moored mode has no effect on logging. Logging is started and stopped with commands sent through the terminal program.

Data I/O

The SBE 19plus receives setup instructions and outputs diagnostic information or previously recorded data via a three-wire RS-232C link, and is factory-configured for 9600 baud, 8 data bits, 1 stop bit, and no parity. SBE 19plus RS-232 levels are directly compatible with standard serial interface cards (IBM Asynchronous Communications Adapter or equal). The communications baud rate can be changed using the `BAUD=` command (see Section 4: Deploying and Operating SBE 19plus).

Batteries and Auxiliary Power

A standard SBE 19plus uses nine D-cell alkaline batteries or rechargeable, nickel-cadmium batteries. If necessary, carbon-zinc or mercury cells can also be used. On-board lithium batteries (non-hazardous units which are unrestricted for shipping purposes) are provided to back-up the buffer and the real-time clock in the event of main battery failure or exhaustion. An auxiliary power source (9 - 28 volts DC) may be connected to the I/O bulkhead connector on the sensor end cap to permit testing and data retrieval without affecting battery capacity. The main batteries can be replaced without affecting either the real-time clock or memory.
Power Endurance

Shown below is a calculation of power endurance for Profiling mode. (See Specifications in this section for power requirements.)

Assume standard 9-battery configuration (nominal 14 amp-hours).

Example: Profiling mode; includes SBE 5M pump; no auxiliary sensors
Operating current = 65 mA
Pump current = 95 mA
Maximum sampling time $\approx \frac{14}{0.065 + 0.095} \approx 87$ hours
Say 60 hours to be conservative

Data Storage

The SBE 19plus has an 8 Mbyte memory. Shown below are calculations of available data storage for several configurations. (See Specifications above for storage space required for each parameter.)

Example 1: Profiling mode, no auxiliary sensors
T & C = 6 bytes/sample
Strain-gauge P = 5 bytes/sample
Storage space $\approx \frac{8,000,000}{6 + 5} \approx 727,000$ samples

Example 2: Profiling mode, 4 external voltages
T & C = 6 bytes/sample
Strain-gauge P = 5 bytes/sample
External voltages = 2 bytes/sample x 4 voltages = 8 bytes/sample
Storage space $\approx \frac{8,000,000}{6 + 5 + 8} \approx 421,000$ samples

Example 3: Moored mode (causes SBE 19plus to store date and time),
4 external voltages
T & C = 6 bytes/sample
Strain-gauge P = 5 bytes/sample
External voltages = 2 bytes/sample x 4 voltages = 8 bytes/sample
Date/Time = 4 bytes/sample
Storage space $\approx \frac{8,000,000}{6 + 5 + 8 + 4} \approx 347,000$ samples

Configuration Options and Plumbing

The SBE 19plus' standard configuration includes an externally mounted SBE 5M submersible pump, used to provide a constant flow rate through the conductivity cell, regardless of descent rate. Optionally, if configured with a dissolved oxygen sensor or pumped fluorometer, the more powerful SBE 5T pump is used. In either case, the pump is powered via a cable connected to the 2-pin Pump bulkhead connector on the sensor end cap.

The SBE 19plus can be configured with a wide range of auxiliary sensors. Two standard 6-pin bulkhead connectors on the sensor end cap serve as the input ports for the auxiliary sensor signal voltages and provide power to the sensors. Additionally, an optional connector can be provided for interfacing with a PAR sensor.
Shown below is the plumbing arrangement of an SBE 19plus equipped with the standard SBE 5M pump. See Section 4: Deploying and Operating SBE 19plus for pump setup and operation details.
Shown below is the SBE 19 plus configured with the optional SBE 5T pump, SBE 43 dissolved oxygen (DO) sensor, and SBE 18 pH sensor. Note that the SBE 43 is plumbed into the system between the conductivity cell outlet and the Y-fitting. The SBE 18 is not connected to the plumbing.
Section 3:
Power and Communications Test

This section describes the pre-check procedure for preparing the SBE 19plus for deployment. The power and communications test will verify that the system works, prior to deployment.

Test Setup

1. If not already installed, install SEATERM and other Sea-Bird software programs on your computer using the supplied software CD:
   A. Insert the CD in your CD drive.
   B. Double click on Seasoft-Win32.exe.
   C. Follow the dialog box directions to install the software.
   The default location for the software is c:/Program Files/Sea-Bird. Within that folder is a sub-directory for each program.

2. Remove the dummy plug and install the I/O cable:
   A. By hand, unscrew the locking sleeve from the SBE 19plus’ I/O (4-pin) connector. If you must use a wrench or pliers, be careful not to loosen the I/O connector instead of the locking sleeve.
   B. Remove the dummy plug from the SBE 19plus’ I/O connector by pulling the plug firmly away from the connector.
   C. Standard Connector - Install the I/O cable connector, aligning the raised bump on the side of the connector with the large pin (pin 1 - ground) on the SBE 19plus. OR MCBH Connector - Install the I/O cable connector, aligning the pins.

3. Connect the I/O cable connector to your computer’s serial port.
   A 25-to-9 pin adapter is supplied for use if your computer has a 9-pin serial port.

Note: It is possible to use the SBE 19plus without SEATERM by sending direct commands from a dumb terminal or terminal emulator, such as Windows HyperTerminal.
Test

Proceed as follows:

1. Double click on SeaTerm.exe. If this is the first time the program is used, the setup dialog box appears:

   Select the instrument type (SBE 19plus) and the computer COM port for communication with the SBE 19plus. Click OK.

2. The main screen looks like this:

   - **Menus** – Contains tasks and frequently executed instrument commands.
   - **Toolbar** – Contains buttons for frequently executed tasks and instrument commands. All tasks and commands accessed through the Toolbar are also available in the Menus. To display or hide the Toolbar, select View Toolbar in the View menu. Grayed out Toolbar buttons are not applicable.
   - **Command/Data Echo Area** – Echoes a command executed using a Menu or Toolbar button, as well as the instrument’s response. Additionally, a command can be manually typed in this area, from the available commands for the instrument. Note that the instrument must be awake for it to respond to a command (use the Connect button on the Toolbar to wake up the instrument).
   - **Status bar** – Provides status information. To display or hide the Status bar, select View Status bar in the View menu.

   - **Instrument**
   - **Computer COM port**
   - **Upload parameter**
   - **Capture to file status – grayed out if not capturing**
   - **Instrument EPROM version**
   - **Baud rate, data bits, stop bits, and parity**

   **Note:**
   See SEATERM’s help files for detailed information on the use of the program.

   **Note:**
   There is at least one way, and as many as three ways, to enter a command:
   - Manually type a command in Command/Data Echo Area
   - Use a menu to automatically generate a command
   - Use a Toolbar button to automatically generate a command

   **Note:**
   Once the system is configured and connected (Steps 3 and 4 below), to update the Status bar:
   - on the Toolbar, click Status; or
   - from the Utilities menu, select Instrument Status.
   SEATERM sends the status command, which displays in the Command/Data Echo Area, and updates the Status bar.
Following are the Toolbar buttons applicable to the SBE 19plus:

<table>
<thead>
<tr>
<th>Toolbar Buttons</th>
<th>Description</th>
<th>Equivalent Command*</th>
</tr>
</thead>
<tbody>
<tr>
<td>Connect</td>
<td>Re-establish communications with SBE 19plus. Computer responds with <code>&gt;</code> prompt. SBE 19plus goes to sleep after two minutes without communication from computer have elapsed.</td>
<td>(press Enter key)</td>
</tr>
<tr>
<td>Status</td>
<td>Display instrument setup and status (logging, samples in memory, etc.).</td>
<td>DS</td>
</tr>
<tr>
<td>Headers</td>
<td>View data headers (cast/header number, date and time, first and last sample in cast/header, and number of measurements to average or interval between samples). In Profiling mode, a new header is generated for each CTD cast. In Moored mode, a new header is generated at start of logging and every subsequent 1000 scans.</td>
<td>DH</td>
</tr>
<tr>
<td>Coefficients</td>
<td>Display calibration coefficients.</td>
<td>DCAL</td>
</tr>
<tr>
<td>Init Log</td>
<td>Reset data pointers and cast numbers. This should be performed after existing data has been uploaded from SBE 19plus and prior to recording new data.</td>
<td>INITLOGGING</td>
</tr>
<tr>
<td>Capture</td>
<td>Capture instrument responses on screen to file; may be useful for diagnostics. File has .cap extension. Press Capture again to turn off capture. Capture status displays in Status bar.</td>
<td>—</td>
</tr>
<tr>
<td>Upload</td>
<td>Upload data stored in memory, in format Sea-Bird’s data processing software can use (raw Hex). Uploaded data has .hex extension. Before using Upload: • Configure upload and header parameters in Configure menu • <strong>Stop logging</strong> (Profiling mode - slide switch off, use STOP button, or send STOP command; Moored mode - use STOP button or send STOP command)</td>
<td>DD (use Upload button if you will be processing data with SBE Data Processing)</td>
</tr>
<tr>
<td>Diagnostics</td>
<td>Perform one or more diagnostic tests on SBE 19plus. Diagnostic test(s) accessed in this manner are non-destructive – they do not write over any existing instrument settings.</td>
<td>DS, DCAL, TS, and TSR</td>
</tr>
<tr>
<td>Stop</td>
<td>Interrupt and end current activity, such as logging, uploading, or diagnostic test.</td>
<td>(press Esc key or Ctrl C)</td>
</tr>
<tr>
<td>Disconnect</td>
<td>Free computer COM port used to communicate with SBE 19plus. COM port can then be used by another program.</td>
<td>—</td>
</tr>
</tbody>
</table>

*See Command Descriptions in Section 4: Deploying and Operating SBE 19plus.*
3. In the Configure menu, select *SBE 19plus*. The dialog box looks like this:

Make the selections in the Configuration Options dialog box:
- **COMM Port**: COM 1 through COM 10, as applicable
- **Baud Rate**: 9600 (documented on Configuration Sheet)
- **Data Bits**: 8
- **Parity**: None
- **Mode**: RS-232 (Full Duplex)

Click OK to overwrite an existing COM/Upload/Header Settings file, or click Save As to save the settings as a new filename.

4. Click the Connect button on the Toolbar. The display looks like this:

```
S>
```

This shows that correct communications between the computer and the SBE 19plus has been established.

If the system does not respond with the `S>` prompt:
- Click the Connect button again.
- Verify the correct instrument was selected in the Configure menu and the settings were entered correctly in the Configuration Options dialog box. Note that the baud rate is documented on the Configuration Sheet.
- Check cabling between the computer and SBE 19plus.
5. Display SBE 19\textit{plus} status information by clicking the Status button on the Toolbar. The display looks like this:

SeacatPlus V 1.3 SERIAL NO. 4000 25 Jun 2001 14:02:13
vbatt = 9.6, vlith = 8.6, ioper = 61.2 ma, ipump = 25.5 ma,
next01 = 76.2 ma
status = not logging
number of scans to average = 1
samples = 0, free = 381300, casts = 0
mode = profile, minimum cond freq = 3000, pump delay = 60 sec
autorun = no, ignore magnetic switch = no
battery type = ALKALINE, battery cutoff = 7.5 volts
pressure sensor = strain gauge, range = 1000.0
SBE 38 = no, Gas Tension Device = no
Ext Volt 0 = yes, Ext Volt 1 = yes, Ext Volt 2 = no, Ext Volt 3 = no
echo commands = yes
output format = converted decimal
output salinity = no, output sound velocity = no

6. Command the SBE 19\textit{plus} to take a sample by typing TS and pressing the Enter key. The display looks like this (if in Profiling mode, with converted decimal output format, no output salinity or sound velocity, and auxiliary sensors on channels 0 and 1):

23.7658, 0.00019, 0.062, 0.5632, 2.3748

where 23.7658 = temperature in degrees Celsius
0.00019 = conductivity in S/m
0.062 = pressure in dbars
0.5632 = voltage for auxiliary sensor channel 0
2.3748 = voltage for auxiliary sensor channel 1

These numbers should be reasonable; e.g., room temperature, zero conductivity, barometric pressure (gauge pressure).

7. Command the SBE 19\textit{plus} to go to sleep (quiescent state) by typing QS and pressing the Enter key.

The SBE 19\textit{plus} is ready for programming and deployment.
Section 4: Deploying and Operating SBE 19plus

This section includes discussions of:

- Sampling modes (Profiling and Moored), including example sets of commands
- Pump operation
- Real-time setup
- Timeout description
- Command descriptions
- Data output formats
- Optimizing data quality in Profiling applications
- Deployment
- Acquiring real-time data
- Recovery - physical handling and uploading data
- Processing data

Note: Separate software manuals on CD-ROM and Help files contain detailed information on installation, setup, and use of Sea-Bird’s real-time data acquisition software and data processing software.

Sampling Modes

The SBE 19plus has two sampling modes for obtaining data:

- Profiling mode
- Moored mode

Descriptions and examples of the sampling modes follow. Note that the SBE 19plus’ response to each command is not shown in the examples. Review the operation of the sampling modes and the commands described in Command Descriptions before setting up your system.
Profiling Mode

The SBE 19 plus samples data at 4 Hz (one sample every 0.25 seconds), averages the data at pre-programmed intervals, stores the averaged data in its FLASH memory, and transmits the averaged data real-time. The SBE 19 plus provides several methods for starting and stopping logging, depending on the settings for the IGNORESWITCH= and AUTORUN= commands:

<table>
<thead>
<tr>
<th>IGNORESWITCH=</th>
<th>AUTORUN=</th>
<th>To Start Logging:</th>
<th>To Stop Logging:</th>
</tr>
</thead>
<tbody>
<tr>
<td>N</td>
<td>N</td>
<td>Slide magnetic switch on.</td>
<td>Slide magnetic switch off, send STOP, or click Stop on SEATERM’s Toolbar.</td>
</tr>
<tr>
<td>Y</td>
<td>N</td>
<td>Send STARTNOW, or STARTMMDDYY=, STARTHHMMSS=, and STARTLATER.</td>
<td>Send STOP or click Stop on SEATERM’s Toolbar.</td>
</tr>
<tr>
<td>Y or N</td>
<td>Y</td>
<td>Turn on external power.</td>
<td>• Turn off external power, or • (if you want to send commands to check or modify setup) Send STOP, click Stop on SEATERM’s Toolbar, or type Ctrl Z.</td>
</tr>
</tbody>
</table>

**Example:** SBE 19 plus in Profiling mode

Wake up SBE 19 plus. Initialize logging to overwrite previous data in memory. Set up with strain-gauge pressure sensor and 1 voltage sensor, average every 4 samples, and output data in raw hex format. Set up with a 60-second pump turn-on delay after pump enters water, to ensure pump is primed before turning on. Set up to initiate logging with the magnetic switch. After all parameters are entered, verify setup with status command. Send power-off command.

(click Connect on Toolbar to wake up)

S>INITLOGGING
S>PType=1
S>VOLT0=Y
S>NAV=4
S>OUTPUTFORMAT=0
S>PUMPDELAY=60
S>IGNORESWITCH=N
S>DS (to verify setup)
S>QS

Start logging by putting magnetic switch in On position. Put SBE 19 plus in the water, and allow to soak for at least time required for pump turn-on (PUMPDELAY=60) before beginning downcast. If desired, use SEASAVE to view real-time data. When cast is complete, stop logging by putting magnetic switch in Off position.

Upload data in memory, in format SBE Data Processing can use. Send power-off command.

(click Connect on Toolbar to wake up)
(click Upload on Toolbar – program leads you through screens to define data to be uploaded and where to store it)

S>QS

**Notes:**

- The SBE 19 plus automatically enters quiescent state after 2 minutes without receiving a command.
- Set OUTPUTFORMAT=0 if you will be using Sea-Bird’s real-time data acquisition software (SEASAVE) or data processing software (SBE Data Processing).
Moored Mode

At pre-programmed intervals, the SBE 19plus wakes up, samples data, stores the data in its FLASH memory, and enters quiescent (sleep) state. The SBE 19plus goes to sleep for a minimum of 3 seconds between each sample. Logging is started with STARTNOW or STARTLATER, and is stopped with STOP. If real-time data is to be transmitted (MOOREDTXREALTIME=Y), data is transmitted after measurements are complete for that sample and before sampling begins for the next sample.

Example: SBE 19plus in Moored mode

Wake up SBE 19plus. Initialize logging to overwrite previous data in memory. Set up with strain-gauge pressure sensor and 1 voltage sensor, take a sample every 120 seconds, take and average 4 measurements for each sample, do not transmit real-time data, and output data in raw hex format. Set up pump to run for 0.5 seconds before each sample. Set up to start logging on April 15, 2001 at 11 am. Send command to start logging at designated date and time. After all parameters are entered, verify setup with status command. Send power-off command.

(click Connect on Toolbar to wake up)

S>INITLOGGING
S>PTYPE=1
S>VOLT0=Y
S>SAMPLEINTERVAL=120
S>NCYCLES=4
S>MOOREDTXREALTIME=N
S>OUTPUTFORMAT=0
S>MOOREDPUMPMODE=1
S>STARTMMDDYY=041501
S>STARTHHMMSS=110000
S>STARTLATER
S>DS (to verify setup)
S>QS

Deploy SBE 19plus. Logging will start automatically at designated date and time.

Upon recovering instrument, stop logging. Upload data in memory, in format SBE Data Processing can use. Send power-off command.

(click Connect on Toolbar to wake up)

S>STOP

(click Upload on Toolbar – program leads you through screens to define data to be uploaded and where to store it)

S>QS

Notes:

• The SBE 19plus automatically enters quiescent state after 2 minutes without receiving a command.
• Set OUTPUTFORMAT=0 if you will be using Sea-Bird’s real-time data acquisition software (SEASAVE).
Pump Operation

Profile Mode

After the conductivity cell enters the water, there is a user-programmable delay before pump turn-on so that all the air in the pump tubing can escape. If the pump motor turns on when there is air in the impeller housing, priming is uncertain and a proper flow rate cannot be ensured. The tubing extending above the air-bleed hole will contain a small reserve of water. This maintains the pump prime (for up to one minute, depending on the length of tubing above the air-bleed), even if the SBE 19 plus is lifted up so that the cell inlet and pump outlet are just below the water surface. This allows beginning the actual profile very near the top of the water. The cell inlet and pump outlet must not come above the water surface or the prime will be lost.

- If prime is lost: Stop logging. Wait at least 5 seconds, then start logging, submerge the SBE 19 plus completely, and wait for the pump delay time before beginning the profile. (Start and stop logging with the magnetic switch, commands, or external power, depending on your setup.)

Pump turn-on occurs when two user-programmable conditions have been met:

- **Raw conductivity frequency exceeds the minimum conductivity frequency** (MINCONDFREQ=)
  Set the minimum conductivity frequency for pump turn-on above the instrument’s zero conductivity raw frequency (shown on the SBE 19 plus Configuration Sheet), to prevent the pump from turning on when the SBE 19 plus is in air.
  - For salt water and estuarine applications:
    typical value = zero conductivity raw frequency + 500 Hz
  - For fresh/nearly fresh water:
    typical value = zero conductivity raw frequency + 5 Hz
  If the minimum conductivity frequency is too close to the zero conductivity raw frequency, the pump may turn on when the SBE 19 plus is in air, as a result of small drifts in the electronics. Some experimentation may be required, and in some cases it may be necessary to rely only on the pump turn-on delay time to control the pump. If so, set a minimum conductivity frequency lower than the zero conductivity raw frequency.

- **Pump turn-on delay time has elapsed** (PUMPDELAY=)
  Set the pump turn-on delay time to allow time for the Tygon tubing and pump to fill with water after the SBE 19 plus is submerged. Determine the turn-on delay by immersing the SBE 19 plus (switch off, not running) just below the air-bleed hole at the top of the Tygon tubing. Measure the time needed to completely fill the tubing (30 seconds is typical) and set the delay to approximately 1.5 times longer. When actually using the SBE 19 plus, be sure to soak the instrument just under the surface for at least the time required for pump turn-on.

Pump turn-off occurs when the conductivity frequency drops below MINCONDFREQ.
Moored Mode

Pump operation is governed by two user-programmable parameters:

- **MOOREDPUMPMODE**: 0, 1, or 2
  The SBE 19plus can be set up to operate with no pump (0), with a pump running for 0.5 second before each sample (1), or the pump running during each sample (2).

- **DELAYBEFORESAMPLING**
  The SBE 19plus can be set up to delay sampling after turning on external voltage sensors. Some instruments, such as a Sea Tech fluorometer or a Beckman- or YSI-type oxygen sensor, require time to stabilize after power is applied, to provide good quality data.

**MOOREDPUMPMODE** and **DELAYBEFORESAMPLING** interact in the operation of the pump, as shown in the diagram below.

---

**Note:**
When using an oxygen sensor with the SBE 19plus, set **MOOREDPUMPMODE=2** and set **DELAYBEFORESAMPLING** as follows:
- **SBE 43** oxygen sensor - 15 seconds, to get fresh water into the plenum for the sample
- **Beckman- or YSI-type** oxygen sensor - 120 to 180 seconds, to allow instrument to polarize

**Note:**
Sampling time includes time for the instrument to warm up as well as time to actually measure the parameters. The 2.7-3.0 second sampling time is for 1 measurement / sample (**NCYCLES=1**). Each additional measurement / sample requires an additional 0.25 seconds.
Real-Time Setup

**Baud Rate and Cable Length**

**Without a Sea-Bird Deck Unit**

The rate that real-time data can be transmitted from the SBE 19plus is dependent on the amount of data to be transmitted per scan and the serial data baud rate:

\[
\text{Time required to transmit data} = \left( \text{number of characters} \times 10 \text{ bits/character} \right) \div \text{baud rate}
\]

*where*

Number of characters is dependent on the included data and output format (see Data Output Formats in this section). Add 2 to the number of characters shown in the output format, to account for the carriage return and line feed at the end of each scan. For decimal output (OUTPUTFORMAT=2 or 3), include decimal points, commas, and spaces when counting the number of characters.

Time required to transmit data must be less than the real-time output rate.

The length of cable that the SBE 19plus can drive is also dependent on the baud rate. The allowable combinations are:

<table>
<thead>
<tr>
<th>Maximum Cable Length (meters)</th>
<th>Maximum Baud Rate</th>
</tr>
</thead>
<tbody>
<tr>
<td>1600</td>
<td>600</td>
</tr>
<tr>
<td>800</td>
<td>1200</td>
</tr>
<tr>
<td>400</td>
<td>2400</td>
</tr>
<tr>
<td>200</td>
<td>4800</td>
</tr>
<tr>
<td>100</td>
<td>9600</td>
</tr>
<tr>
<td>50</td>
<td>19200</td>
</tr>
<tr>
<td>25</td>
<td>38400</td>
</tr>
</tbody>
</table>

**Example 1** - SBE 19plus without a Deck Unit. **Profiling** Mode, configured with 2 external voltages. What is the fastest rate you can transmit real-time data over 800 m with OUTPUTFORMAT=0 (raw hexadecimal data)?

With 800 meters of cable and no Deck Unit, the SBE 19plus requires a baud rate of 1200 or less.

Number of characters for OUTPUTFORMAT=0 (from Data Output Formats) =

\[6 \times (T) + 6 \times (C) + 6 \times (P) + 4 \times (P \text{ temperature compensation}) + 2 \times 4 \times (\text{external voltages}) + 2 \times (\text{carriage return & line feed}) = 32\]

Time required to transmit data = \(32 \text{ characters} \times 10 \text{ bits/character} \div 1200 = 0.267 \text{ seconds}\) > 0.25 seconds (4 Hz, maximum sampling rate).

Therefore, set NAVG=2, averaging 2 measurements/sample and storing and transmitting 1 sample every 0.5 seconds.

**Example 2** - SBE 19plus without a Deck Unit. **Moored** Mode, configured with 4 external voltages, 10 measurements/sample (NCYCLES=10), and a 15 second delay before sampling (DELAYBEFORESAMPLING=15). What is the smallest sample interval you can use if you want to transmit real-time data over 800 m with OUTPUTFORMAT=0 (raw hexadecimal data)?

With 800 meters of cable, the SBE 19plus requires a baud rate of 1200 or less.

Number of characters for OUTPUTFORMAT=0 (from Data Output Formats) =

\[6 \times (T) + 6 \times (C) + 6 \times (P) + 4 \times (P \text{ temperature compensation}) + 4 \times 4 \times (\text{external voltages}) + 8 \times (\text{time}) + 2 \times (\text{carriage return & line feed}) = 48\]

Time required to transmit data = \(48 \text{ characters} \times 10 \text{ bits/character} \div 1200 = 0.4 \text{ seconds}\)

Minimum time required for each sample =

15 seconds (delay after turning on power) + 3 second warm-up & sampling time + \(10-1 \times 0.25 \text{ seconds}\) + 0.4 seconds to transmit real-time + 3 seconds to go to sleep between samples = 23.65 seconds, round up to 24

Therefore, set SAMPLEINTERVAL=24, storing and transmitting one sample every 24 seconds.
Section 4: Deploying and Operating SBE 19plus

With a Sea-Bird Deck Unit

Set the SBE 19plus’ baud rate to 4800 if using the SBE 19plus with either of the following real-time data acquisition systems:

- SBE 36 CTD Deck Unit and Power and Data Interface Module (PDIM)
- SBE 33 Carousel Deck Unit and SBE 32 Carousel Water Sampler

The data telemetry link can drive 10,000 meters of cable while accepting 4800 baud serial data. The relationship between rate of transmission, amount of data to be transmitted, and baud rate is as described above for an SBE 19plus without a Deck Unit.

Example - SBE 19plus with an SBE 33 or 36 Deck Unit. Profiling Mode, configured with 2 external voltages. What is the fastest rate you can transmit data over 800 m with OUTPUTFORMAT=0 (raw hexadecimal data)?

With a Deck Unit, the SBE 19plus requires a baud rate of 4800.

Number of characters (from Data Output Formats) =
6 (T) + 6 (C) + 6 (P) + 4 (P temperature compensation) + 2*4 (external voltages) + 2 (carriage return & line feed) = 32

Time required to transmit data = (32 characters * 10 bits/character) / 4800 = 0.067 seconds < 0.25 seconds (4 Hz, maximum sampling rate).

Therefore, set NAVG=1, providing 4 Hz data (one sample every 0.25 seconds) for this configuration.

Real-Time Data Acquisition

Real-time data can be acquired in either of the following ways:

- With SEASAVE (typical method) – Data can be viewed in SEASAVE in tabular form or as plots, as raw data or as converted (engineering units) data. Data acquired with SEASAVE can be processed with SBE Data Processing. See SEASAVE’s Help files for details on setting up the program displays, baud rates, etc., and beginning data acquisition.

- With SEATERM – Click Capture on SEATERM’s Toolbar. Begin logging. The hex data displayed in SEATERM will be saved to the designated file. Process the data as desired. Note that this file cannot be processed by SEASAVE or SBE Data Processing, as it does not have the required headers and format for Sea-Bird’s processing software.
Timeout Description

The SBE 19plus has a timeout algorithm. If the SBE 19plus does not receive a command or sample data for 2 minutes, it powers down its main digital circuits. This places the SBE 19plus in quiescent state, drawing minimal current. To re-establish control (wake up), press Connect on the Toolbar or the Enter key. The system responds with the $>$ prompt.

Command Descriptions

This section describes commands and provides sample outputs. See Appendix III: Command Summary for a summarized command list.

When entering commands:

- Input commands to the SBE 19plus in upper or lower case letters and register commands by pressing the Enter key.
- The SBE 19plus sends ?CMD if an invalid command is entered.
- If the system does not return an $>$ prompt after executing a command, press the Enter key to get the $>$ prompt.
- If a new command is not received within 2 minutes after the completion of a command, the SBE 19plus returns to the quiescent (sleep) state.
- If in quiescent state, re-establish communications by pressing Connect on the Toolbar or the Enter key to get an $>$ prompt.
- If the SBE 19plus is transmitting data and you want to stop it, press the Esc key or Stop on the Toolbar (or type ^C). Press the Enter key to get the $>$ prompt.
- The SBE 19plus cannot have samples with different scan lengths (more or fewer data fields per sample) in memory. If the scan length is changed by commanding it to add or subtract a data field (such as an external voltage), the SBE 19plus must initialize logging. Initializing logging sets the sample number and cast number to 0, so the entire memory is available for recording data with the new scan length. Initializing logging should only be performed after all previous data has been uploaded. Therefore, commands that change the scan length (MM, MP, PTYPE=, VOLT0=, VOLT1=, VOLT2=, and VOLT3=) prompt the user for verification before executing, to prevent accidental overwriting of existing data.
- The SBE 19plus responds only to the DS, DCAL, TS, SL, SLT, QS, and STOP commands while logging. If you wake the SBE 19plus while it is logging (for example, to send DS to check on logging progress), it will temporarily stop logging. Logging resumes when it goes back to sleep again (either by sending the QS command or after the 2-minute timeout).
- The SBE 19plus responds only to the DS, DCAL, TS, SL, SLT, QS, and STOP commands while waiting to start logging (if you sent the STARTLATER command but logging has not started yet). To send any other commands, send the STOP command, send the desired commands to modify the setup, and then send the STARTLATER command again.

Entries made with the commands are permanently stored in the SBE 19plus and remain in effect until you change them.

- The only exception occurs if the electronics are removed from the housing and disconnected from the battery Molex connector (see Appendix II: Electronics Disassembly/Reassembly). Upon reassembly, reset the date and time (MMDDYY= and HHMMSS=) and initialize logging (INITLOGGING).
Display operating status and setup parameters, which vary depending on whether in Profiling or Moored mode.

Equivalent to Status button on Toolbar.

List below includes, where applicable, command used to modify parameter.

### Profiling Mode (MP)
- Firmware version, serial number, date and time \([\text{MMDDYY}= \text{and HHMMSS=}]\)
- Voltages and currents (main and lithium battery voltages, operating and pump current, and external voltage currents)
- Logging status (not logging, logging, waiting to start at ... or unknown status)
- Number of scans to average \([\text{NAV}=]\)
- Number of samples and available sample space in memory, and number of casts in memory
- Profiling mode \([\text{MP}]=]\), minimum conductivity frequency for pump turn-on \([\text{MINCONDFREQ=}]=]\), and pump turn-on delay \([\text{PUMPDELAY=}]=]\)
- Begin logging automatically when external power is applied \([\text{AUTORUN=}]=]\) ignore magnetic switch position for starting/stopping logging \([\text{IGNORESWITCH=}]=]\)
- Battery type \([\text{BATTERYTYPE=}]=]\) and battery cut-off voltage
- Pressure sensor type \([\text{PTYPE=}]=]\) and range \([\text{PRANGE=}]=]\)
- Sample SBE 38 secondary temperature sensor? Sample Gas Tension Device? (applicable only for custom applications)
- Sample external voltages 0, 1, 2, and 3? \([\text{VOLT0=} = \text{through VOLT3=}]=]\) commands
- Show entered commands on screen as you type \([\text{ECHO=}]=]\)
- Output format \([\text{OUTPUTFORMAT=}]=]\)
- Output salinity \([\text{OUTPUTSAL=}]=]\) and sound velocity \([\text{OUTPUTSV=}]=]\) with each sample? (only if output format = converted decimal)

---

**Example:** Profiling mode (user input shown in bold)

```
S>DS
SeacatPlus V 1.3 SERIAL NO. 4000 25 Jun 2001 14:02:13
vbatt = 9.6, vlith 8.6, ioper = 61.2 ma, ipump = 25.5 ma,
iext01 = 76.2 ma,
status = not logging
number of scans to average = 1
samples = 0, free = 381300, casts = 0
mode = profile, minimum cond freq = 3000, pump delay = 60 sec
autorun = no, ignore magnetic switch = no
battery type = ALKALINE, battery cutoff = 7.5 volts
pressure sensor = strain gauge, range = 1000.0
SBE 38 = no, Gas Tension Device = no
Ext Volt 0 = yes, Ext Volt 1 = yes, Ext Volt 2 = no, Ext Volt 3 = no
echo commands = yes
output format = converted decimal
output salinity = no, output sound velocity = no
```
Section 4: Deploying and Operating SBE 19plus

Moored Mode (MM)

- Firmware version, serial number, date and time [MMDDYY= and HHMMSS=]
- Voltages and currents (main and lithium battery voltages, operating and pump current, and external voltage currents)
- Logging status (not logging, logging, waiting to start at . . ., or unknown status)
- Sample interval [SAMPLEINTERVAL=] and number of measurements to take and average per sample [NCYCLES=]
- Number of samples and available sample space in memory
- Moored mode [MM], pump turn-on parameter [MOOREDPUMPMODE=], and turn-on delay [DELAYBEFORESAMPLING=]
- Transmit data real-time? [MOOREDTXREALTIME=]
- Battery type [BATTERYTYPE=] and battery cut-off voltage
- Pressure sensor type [PTYPE=] and range [PRANGE=]
- Sample SBE 38 secondary temperature sensor? Sample Gas Tension Device? (applicable only for custom applications)
- Sample external voltages 0, 1, 2, and 3? [VOLT0= through VOLT3= commands]
- Show entered commands on screen as you type [ECHO=]?
- Output format [OUTPUTFORMAT=]
- Output salinity [OUTPUTSAL=] and sound velocity [OUTPUTSV=] with each sample? (only if output format = converted decimal)

Example: Moored mode (user input shown in bold)

S>DS
SeacatPlus V 1.3 SERIAL NO. 4000 25 Jun 2001 14:02:13
vbatt = 9.4, vlith = 8.6, ioper = 61.3 ma, ipump = 26.8 ma,
iext01 = 76.2 ma,
status = not logging
sample interval = 15 seconds, number of measurements per sample = 1
samples = 0, free = 364722
mode = moored, run pump for 0.5 sec, delay before sampling = 0.0 seconds
transmit real-time = yes
battery type = ALKALINE, battery cutoff = 7.5 volts
pressure sensor = strain gauge, range = 2000.0
SBE 38 = no, Gas Tension Device = no
Ext Volt 0 = yes, Ext Volt 1 = yes, Ext Volt 2 = no, Ext Volt 3 = no
echo commands = yes
output format = converted decimal
output salinity = no, output sound velocity = no

Note:
If your SBE 19plus includes a custom RS-232 connector for an SBE 38 or GTD, see Addendum: Custom SBE 19plus SEACAT with Interface for RS-232 Sensor.
Section 4: Deploying and Operating SBE 19plus

Setup Commands

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>MMDDYY=mmdddy</td>
<td>Set real-time clock month, day, and year. This command must be followed by</td>
</tr>
<tr>
<td></td>
<td>HHMMSS= command to set time.</td>
</tr>
<tr>
<td>DDMMYY=ddmmyy</td>
<td>Set real-time clock day, month, and year. This command must be followed by</td>
</tr>
<tr>
<td></td>
<td>HHMMSS= command to set time.</td>
</tr>
<tr>
<td>HHMMSS=hhmmss</td>
<td>Set real-time clock hour, minute, and second.</td>
</tr>
</tbody>
</table>

**Example:** Set current date and time to 05 October 2000 12:00:00 (user input shown in bold).

```
S>MMDDYY=100500
S>HHMMSS=120000
```

or

```
S>DDMMYY=051000
S>HHMMSS=120000
```

**Notes:**
- DDMMYY= and MMDDYY= commands are equivalent. Either can be used to set the date.
- Always set both date and then time. If a new date is entered but not a new time, the new date will not be saved. If a new time is entered without first entering a new date, the date will reset to the last date it was set for with MMDDYY= or DDMMYY=.

**Note:**
- **BAUD=x**
  - x= baud rate (600, 1200, 2400, 4800, 9600, 19200, or 38400). Default 9600.

- **ECHO=x**
  - x= Y: Echo characters received from computer (default) - computer monitor will show entered commands as you type.
  - x= N: Do not.

- **MM**
  - Set SBE 19plus to Moored mode.

- **MP**
  - Set SBE 19plus to Profiling mode.

- **MOOREDXTXREALTIME=x**
  - **Moored mode (MM) only.** (for Profiling mode, SBE 19plus always outputs real-time data).
  - x= Y: Output real-time data.
  - x= N: Do not.

- **BATTERYTYPE=x**
  - x= 0: Alkaline (or lithium) batteries.
  - x= 1: Ni-Cad batteries.
### Setup Commands (continued)

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PTYPE=x</td>
<td>Pressure sensor type.</td>
</tr>
<tr>
<td>x=0: No pressure sensor (not applicable to SBE 19plus).</td>
<td></td>
</tr>
<tr>
<td>x=1: Strain-gauge.</td>
<td></td>
</tr>
<tr>
<td>x=2: Quartz without temperature compensation (not applicable to SBE 19plus).</td>
<td></td>
</tr>
<tr>
<td>x=3: Quartz with temperature compensation (not applicable to SBE 19plus).</td>
<td></td>
</tr>
<tr>
<td>VOLT0=x</td>
<td>External voltage 0.</td>
</tr>
<tr>
<td>x=Y: Sample external voltage 0.</td>
<td></td>
</tr>
<tr>
<td>x=N: Do not.</td>
<td></td>
</tr>
<tr>
<td>VOLT1=x</td>
<td>External voltage 1.</td>
</tr>
<tr>
<td>x=Y: Sample external voltage 1.</td>
<td></td>
</tr>
<tr>
<td>x=N: Do not.</td>
<td></td>
</tr>
<tr>
<td>VOLT2=x</td>
<td>External voltage 2.</td>
</tr>
<tr>
<td>x=Y: Sample external voltage 2.</td>
<td></td>
</tr>
<tr>
<td>x=N: Do not.</td>
<td></td>
</tr>
<tr>
<td>VOLT3=x</td>
<td>External voltage 3.</td>
</tr>
<tr>
<td>x=Y: Sample external voltage 3.</td>
<td></td>
</tr>
<tr>
<td>x=N: Do not.</td>
<td></td>
</tr>
</tbody>
</table>

*Example:* Sample data from voltage sensors wired to channels 0 and 3 on SBE 19plus' end cap (user input shown in bold).

```plaintext
S> VOLT0=Y
S> VOLT1=N
S> VOLT2=N
S> VOLT3=Y
```

With this setup, there will be 2 external sensor voltages in the data stream. In the .con file (in SBE Data Processing or SEASAVE), indicate 2 external voltage channels. Voltage 0 corresponds to the sensor wired to external voltage channel 0; voltage 1 corresponds to the sensor wired to external voltage channel 3.

### Notes:
- The SBE 19plus configuration (.con) file must match this selection of pressure sensor and external voltages when viewing real-time data in SEASAVE or processing uploaded data. View and edit the .con file in SEASAVE or SBE Data Processing. Note that these parameters are factory-set to match the ordered instrument configuration.
- External voltage numbers 0, 1, 2, and 3 correspond to wiring of sensors to a voltage channel on the SBE 19plus end cap (see Dimensions and End Cap Connectors in Section 2: Description of SBE 19plus). However, in the .con file, voltage 0 is the first external voltage in the data stream, voltage 1 is the second, etc.
- The SBE 19plus requires verification when these commands (PTYPE= through VOLT3=) are sent. Instrument responds: this command will change the scan length and initialize logging. Proceed Y/N? Press the Y and the Enter key to proceed. The SBE 19plus responds:
  - Scan length has changed, initializing logging

### Note:
If DELAYBEFORESAMPLING is too high, the SBE 19plus will not be able to take NCYCLES samples within SAMPLEINTERVAL seconds. In that case, the SBE 19plus internally increases SAMPLEINTERVAL to the smallest feasible number.

### Note:
See Pump Operation in this section for a detailed explanation of pump operation.

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>DELAYBEFORESAMPLING=x</td>
<td>Moored mode (MM) only.</td>
</tr>
<tr>
<td>x=time (seconds) to wait after switching on external voltage before sampling (0-32,000 seconds). Default 0 seconds. Typical value if a Sea Tech fluorometer is installed is 15 seconds.</td>
<td></td>
</tr>
<tr>
<td>MOOREDPUMP=</td>
<td>Moored mode (MM) only.</td>
</tr>
<tr>
<td>x=0: No pump.</td>
<td></td>
</tr>
<tr>
<td>x=1: Run pump for 0.5 seconds before each sample.</td>
<td></td>
</tr>
<tr>
<td>x=2: Run pump during each sample.</td>
<td></td>
</tr>
</tbody>
</table>
## Setup Commands (continued)

### MINCONDREQ=x

**Proiling mode (MP) only.**

- **x** = minimum conductivity frequency (Hz) to enable pump turn-on, to prevent pump from turning on before SBE 19\textit{plus} is in water. Pump stops when conductivity frequency drops below **MINCONDREQ**.

SBE 19\textit{plus} Configuration Sheet lists uncorrected (raw) frequency output at 0 conductivity. Typical value (and factory-set default) for **MINCONDREQ** for salt water and estuarine application is: (0 conductivity frequency + 500 Hz).

Typical value for **MINCONDREQ** for fresh water applications is: (0 conductivity frequency + 5 Hz).

### PUMPDELAY=x

**Proiling mode (MP) only.**

- **x** = time (seconds) to wait after minimum conductivity frequency (**MINCONDREQ**) is reached before turning pump on. Pump delay time allows time for Tygon tubing and pump to fill with water after SBE 19\textit{plus} is submerged.

Typical value is 30 - 45 seconds. Pump starts **PUMPDELAY** seconds after conductivity cell’s frequency output is greater than **MINCONDREQ**. Default 60 seconds.

### OUTPUTFORMAT=x

- **x** = 0: Output raw frequencies and voltages in Hexadecimal form. **Must use this format for acquiring and viewing real-time data in SEASAVE** and for uploading data that will be processed with SBE Data Processing. When using SEATERM’s Upload button, SEATERM sends **OUTPUTFORMAT=0** command. This causes SBE 19\textit{plus} to upload data in memory in raw hex, regardless of user-programmed **OUTPUTFORMAT**, providing data in format that SBE Data Processing can use.

- **x** = 1: Output converted (engineering units) data in Hexadecimal form.

- **x** = 2: Output raw frequencies and voltages in decimal form.

- **x** = 3: Output converted (engineering units) data in decimal form. **Must use this format to output salinity or sound velocity.**

- **x** = 4: Output pressure and scan number only, in Hexadecimal form. Typically used only for interfacing SBE 19\textit{plus} with 90208 Auto Fire Module.

---

**Note:**

See **Pump Operation** in this section for a detailed explanation of pump operation.

**Note:**

Output format does not affect how data is stored in FLASH memory. Sea-Bird’s real-time data acquisition (SEASAVE) and data processing (SBE Data Processing) software require data in raw hexadecimal (**OUTPUTFORMAT=0**).

Typical use of the output format command is:

- **Before beginning a cast:**
  - If you will be using SEASAVE to view real-time data - **You must set output format to raw hex.**
  - If you will be using SEATERM to view real-time data - Set output format to converted decimal for ease in viewing data.

- **After the cast is complete, use SEATERM’s Upload button to upload data from memory.** This automatically resets the format to raw hex (**OUTPUTFORMAT=0**), so the data is compatible with SBE Data Processing.
## Setup Commands (continued)

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>OUTPUTSAL=x</td>
<td>x = Y: Calculate and output salinity (psu). Only applies if OUTPUTFORMAT=3. x = N: Do not.</td>
</tr>
<tr>
<td>OUTPUTSV=x</td>
<td>x = Y: Calculate and output sound velocity (m/sec), using Chen and Millero formula (UNESCO Technical Papers in Marine Science #44). Only applies if OUTPUTFORMAT=3. x = N: Do not.</td>
</tr>
<tr>
<td>IGNORESWITCH=x</td>
<td>x = Y: Do not start or stop logging based on position of magnetic switch. Use STARTNOW, STARTLATER, and STOP commands to control logging. x = N: Do not ignore magnetic switch position. Logging is controlled by switch position or by commands.</td>
</tr>
<tr>
<td>AUTORUN=x</td>
<td>x = Y: Start logging automatically when external power is applied; stop logging when external power is removed. Magnetic switch position has no effect on logging. x = N: Wait for a command when external power is applied. Default.</td>
</tr>
<tr>
<td>FLASHINIT</td>
<td>Map bad blocks and erase FLASH memory, which destroys all data in SBE 19plus. SBE 19plus requires you to enter this command twice, to provide verification before it proceeds. All data bits are set to 1. Sample number, header number, and data pointers are set to 0. Allow 15 minutes to initialize entire memory. Send this command (after uploading all data) if you are encountering FLASH Read errors in the Status command (DS) response. If not encountering these errors, use of this command is optional, as SBE 19plus writes over previously recorded information when INITLOGGING command is used before beginning logging. However, knowledge of initial memory contents (i.e., all ones) can be a useful cross-check when data is retrieved.</td>
</tr>
<tr>
<td>QS</td>
<td>Quit session and place SBE 19plus in quiescent (sleep) state. Main power is turned off. Data logging and memory retention are not affected.</td>
</tr>
</tbody>
</table>

### Notes:
- For Moored mode, the SBE 19 plus ignores the AUTORUN= setting.
- To start sampling immediately after you send AUTORUN=Y (if you were performing setup on external power):
  - Send QS to put SBE 19 plus in quiescent (sleep) state, and then turn external power off and then on again. or
  - Send STARTNOW
- For Moored mode (MP) only, SBE 19 plus ignores the switch position; logging is controlled by commands only.
- To start sampling immediately after you send AUTORUN=Y (if you were performing setup on external power):
  - Send QS to put SBE 19 plus in quiescent (sleep) state, and then turn external power off and then on again. or
  - Send STARTNOW
**Logging Commands**

Logging commands direct the SBE 19plus to sample data at pre-programmed intervals. When commanded to start sampling, the SBE 19plus takes samples and stores the data in its FLASH memory. Operation is dependent on the mode and setup.

**Profiling Mode (MP)**

While logging, the SBE 19plus transmits real-time data, and does not enter quiescent (sleep) state between samples. The SBE 19plus provides several methods for starting and stopping logging, depending on the settings for **IGNORESWITCH=** and **AUTORUN=**. Logging starts approximately 5 seconds after it is commanded.

<table>
<thead>
<tr>
<th>IGNORESWITCH=</th>
<th>AUTORUN=</th>
<th>To Start Logging:</th>
<th>To Stop Logging:</th>
</tr>
</thead>
<tbody>
<tr>
<td>N</td>
<td>N</td>
<td>Slide magnetic switch on.</td>
<td>Slide magnetic switch off, send STOP, or click Stop on SEATERM’s Toolbar.</td>
</tr>
<tr>
<td>Y</td>
<td>N</td>
<td>Send STARTNOW, or STARTMMDDYY=, STARTHHMMSS=, and STARTLATER.</td>
<td>Send STOP or click Stop on SEATERM’s Toolbar.</td>
</tr>
<tr>
<td>Y or N</td>
<td>Y</td>
<td>Turn on external power.</td>
<td>• Turn off external power, or • (if you want to send commands to check or modify setup) Send STOP, click Stop on SEATERM’s Toolbar, or type Ctrl Z.</td>
</tr>
</tbody>
</table>

The first time logging is started after receipt of the initialize logging command (**INITLOGGING**), data recording starts at the beginning of memory and any previously recorded data is written over. When logging is stopped, recording stops. Each time logging is started again, recording continues, with new data stored after the previously recorded data and a new header written to indicate the incremented cast number, date, time, and sample numbers contained in the cast. The maximum number of casts that can be taken is 300.

**Moored Mode (MM)**

While logging, the SBE 19plus transmits real-time data if **MOORED TX REALTIME=Y**. The SBE 19plus enters quiescent (sleep) state between samples.

To start logging, use **STARTNOW** or **STARTLATER**. Logging starts approximately 5 seconds after the receipt of **STARTNOW**. The first time logging is started after receipt of the initialize logging command (**INITLOGGING**), data recording starts at the beginning of memory and any previously recorded data is written over. When **STOP** is sent, recording stops. Each time **STARTNOW** or **STARTLATER** is sent again, recording continues, with new data stored after the previously recorded data. A new header is written each time logging starts and every 1000 samples thereafter.
### Logging Commands (continued)

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
</table>
| **SAMPLEINTERVAL=x** | Moored mode (MM) only.  
  x = interval (seconds) between samples  
  (10 - 14,400 seconds).  
  Moored mode (MM) only.  
  x = number of measurements to take and average every SAMPLEINTERVAL  
  seconds (default = 1). SBE 19plus takes and averages NCYCLES samples  
  (each 0.25 seconds apart) each SAMPLEINTERVAL seconds; averaged data is stored in FLASH memory and  
  (if MOORED TXREALTIME=Y) transmitted real-time.  
  Example: If SAMPLEINTERVAL=10 and NCYCLES=4, every 10 seconds the SBE 19plus takes 4 samples (each 0.25 seconds apart), averages the data from the 4 samples, and stores the averaged data in FLASH memory. |
| **NCYCLES=x**     | Profiling mode (MP) only.  
  x = number of samples to average  
  (default = 1, maximum = 32,767).  
  SBE 19plus samples at 4 Hz  
  (every 0.25 seconds) and averages NAVG samples; averaged data is stored in FLASH memory and transmitted real-time.  
  Example: The SBE 19plus samples every 0.25 seconds. If NAVG=2, the SBE 19plus averages the data from 2 samples (= 1 averaged data sample per 0.5 second), stores the averaged data in FLASH memory, and transmits the averaged data real-time. |
| **NAVG=x**        | Initialize logging - after all previous data has been uploaded from SBE 19plus,  
  initialize logging before starting to log again to make entire memory available for recording. This command sets sample number (SAMPLENUMBER=) and header and cast number (HEADERNUMBER=) to 0 internally. If these are not set to 0, data will be stored after last recorded sample. Do not send INITLOGGING until all existing data has been uploaded. |

**Note:** If NCYCLES is too high, the SBE 19plus will not be able to take NCYCLES samples within SAMPLEINTERVAL seconds. In that case, the SBE 19plus internally increases SAMPLEINTERVAL to the smallest feasible number.
Logging Commands (continued)

**SAMPLENUMBER=x**  
x= sample number for first sample when logging begins. After all previous data has been uploaded from SBE 19plus, send **SAMPLENUMBER=0** (this sets sample, header, and cast number to 0 internally) before starting to log to make entire memory available for recording. If these are not set to 0, data will be stored after last recorded sample. **Do not send** **SAMPLENUMBER=0** until all existing data has been uploaded.

**HEADERNUMBER=x**  
x= header and cast number for first cast when logging begins. This command is typically only used to recover data if you accidentally initialize logging (using **INITLOGGING** or **SAMPLENUMBER=0**) before uploading all existing data.

**STARTNOW**  
Start logging now.

**STARTMMDDYY=mmddyy**  
Set delayed logging start month, day, and year. This command must be followed by **STARTHHMMSS=** command to set delayed start time.

**STARTDDMMYY=ddmmyy**  
Set delayed logging start day, month, and year. This command must be followed by **STARTHHMMSS=** command to set delayed start time.

**STARTHHMMSS=hhmmss**  
Set delayed logging start hour, minute, and second.

**STARTLATER**  
Start logging at time set with delayed start date and time commands.

**STOP**  
Stop data logging or stop waiting to start logging (if **STARTLATER** was sent but logging has not begun yet). Press Enter key to get S> prompt before entering this command.

Notes:

- **INITLOGGING** and **SAMPLENUMBER=0** have identical effects. Use either command to initialize logging.
- Initializing logging sets sample, header, and cast number to 0 internally. However, for data output, the first sample, header, and cast number is 1.
- **Do not initialize logging until all data has been uploaded.** These commands do not delete data; they reset the data pointer. **If you accidentally initialize logging before uploading**, recover data as follows:
  1. Set **SAMPLENUMBER=a** and **HEADERNUMBER=b**, where **a** and **b** are your estimate of number of samples and casts in memory.
  2. Upload data. If **a** is more than actual number of samples or **b** is more than actual number of casts in memory, data for non-existent samples/casts will be bad, random data. Review uploaded data file carefully and delete any bad data.
  3. If desired, increase **a** and/or **b** and upload data again, to see if there is additional valid data in memory.

Notes:

- **STARTDDMMYY=** and **STARTMMDDYY=** commands are equivalent. Either can be used to set the delayed start date.
- **If using **STARTNOW** or **STARTLATER** to start logging, the SBE 19plus must be set to Moored mode (MM), or if in Profiling mode (MP) must be set to ignore the magnetic switch (IGNORESWITCH=Y).
- After receiving **STARTLATER**, the 19plus displays waiting to start . . . in reply to the DS command. Once logging starts, the DS reply displays logging.
- **If the delayed start date and time has already passed when **STARTLATER** is received, the 19plus executes **STARTNOW**.

Notes:

- **You may need to send **STOP** several times to get the SBE 19plus to respond.**
- If in Profiling mode and **IGNORESWITCH=N**, slide the magnetic switch off or send **STOP** to stop logging.
- **You must stop logging before uploading data.**

Example: Program 19plus to start logging on 20 January 2001 12:00:00. (user input shown in bold)

S>STARTMMDDYY=012001  
S>STARTHHMMSS=120000  
S>STARTLATER  
or  
S>STARTDDMMYY=200101  
S>STARTHHMMSS=120000  
S>STARTLATER
## Data Upload Commands

Stop logging before uploading data.

### DDb,e

Upload data from scan \( b \) to scan \( e \).
- If \( b \) and \( e \) are omitted, all data is uploaded.
- First sample number is 1.

**Example:** Upload samples 1 - 199 to a file (user input shown in bold):

\( S > \text{DD1,199} \)

### DCn

**Profiling mode only.**

Upload data from cast \( n \). If \( n \) is omitted, data from cast 1 is uploaded.
- First cast number is 1.

**Example:** Upload all data in second cast (cast 2) to a file (user input shown in bold):

\( S > \text{DC2} \)

### DHb,e

Upload header \( b \) to header \( e \). If \( b \) and \( e \) are omitted, all headers are uploaded. First header is 1. The header includes:
- cast/header number
- month, day, hour, minute, and second when cast was started
- first and last sample in cast/header
- number of measurements to average per sample (\( \text{NAVG} \)) or interval between samples (\( \text{SAMPLEINTERVAL} \))
- reason logging was halted (\( \text{batfail} = \) battery voltage too low; \( \text{mag switch} = \) switch turned off; \( \text{stop cmd} = \) received \( \text{STOP} \) command or Home or Ctrl Z character; \( \text{timeout} = \) error condition; \( \text{unknown} = \) error condition; \( \text{???????} = \) error condition)

**Examples:**

**Profiling Mode** - Upload second header (header for cast 2) to a file:

(Click Capture on Toolbar and enter desired filename in dialog box.)

\( S > \text{DH2} \)

*SBE 19plus* responds:

\( \text{cast 2 30 Nov 2000 12:30:33 samples 35 to 87, avg = 4, stop = mag switch} \)

**Moored Mode** - Upload second header to a file:

(Click Capture on Toolbar and enter desired filename in dialog box.)

\( S > \text{DH2} \)

*SBE 19plus* responds:

\( \text{hdr 2 30 Nov 2000 12:30:33 samples 35 to 87, int = 10, stop = stop cmd} \)
### Sampling Commands

These commands request a single sample. The SBE 19plus always stores data for the most recent sample in its buffer. Some Sampling commands also store data in Flash memory - the SBE 19plus will not execute the `store data in Flash memory` portion of those commands while logging data.

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SL</td>
<td>Output last sample from buffer (sample obtained with sampling command, or latest sample from logging), and leave power on.</td>
</tr>
<tr>
<td>SLT</td>
<td>Output last sample from buffer, then take new sample and store data in buffer. Leave power on. Data is not stored in Flash memory.</td>
</tr>
<tr>
<td>TS</td>
<td>Take new sample, store data in buffer, output data, and leave power on. Data is not stored in Flash memory.</td>
</tr>
<tr>
<td>TSS</td>
<td>Take new sample, store data in buffer and Flash memory, output data, and turn power off.</td>
</tr>
<tr>
<td>TSSON</td>
<td>Take new sample, store data in buffer and Flash memory, output data, and leave power on.</td>
</tr>
</tbody>
</table>

### Testing Commands

The SBE 19plus takes and outputs 100 samples for each test (except as noted); data is not stored in Flash memory. Press the Esc key or Stop on the Toolbar to stop a test.

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TT</td>
<td>Measure temperature, output converted data.</td>
</tr>
<tr>
<td>TC</td>
<td>Measure conductivity, output converted data.</td>
</tr>
<tr>
<td>TP</td>
<td>Measure pressure, output converted data.</td>
</tr>
<tr>
<td>TV</td>
<td>Measure four external voltage channels, output converted data.</td>
</tr>
<tr>
<td>TTR</td>
<td>Measure temperature, output raw data.</td>
</tr>
<tr>
<td>TCR</td>
<td>Measure conductivity, output raw data.</td>
</tr>
<tr>
<td>TPR</td>
<td>Measure pressure, output raw data.</td>
</tr>
<tr>
<td>TVR</td>
<td>Measure four external voltage channels, output raw data.</td>
</tr>
<tr>
<td>PUMPON</td>
<td>Turn pump on for testing purposes.</td>
</tr>
<tr>
<td>PUMPOFF</td>
<td>Turn pump off for testing purposes.</td>
</tr>
</tbody>
</table>

### Notes:
- The SBE 19plus has a buffer that stores the most recent data samples. Unlike data in the Flash memory, data in the buffer is erased upon removal or failure of power.
- Leave power on in the SL, SLT, TS, and TSSON command descriptions refers to power for the SBE 19plus as well as for any auxiliary sensors.
Section 4: Deploying and Operating SBE 19plus

Calibration Coefficients Commands

**DCAL**

Display calibration coefficients. Equivalent to Coefficients button on Toolbar.

**Example:** Display coefficients for SBE 19plus (user input shown in bold).

S> dcal

SeacatPlus V 1.3 SERIAL NO. 4000 25 Jun 2001 14:46:05

temperature: 26-jul-00
TA0 = -3.178124e-06
TA1 = 2.751603e-04
TA2 = -2.215606e-06
TA3 = 1.549719e-07
TOFFSET = 0.000000e+00

conductivity: 01-aug-00
G = -9.855242e-01
H = 1.458421e-01
I = -3.290801e-04
J = 4.784952e-05
CFO = 2.584100e+03
CTCOR = -9.570000e-08
CTCOR = 3.250000e-06
CSLOPE = 1.000000e+00

pressure S/N , range = 2000 psia: 14-jul-00
PA0 = 0.000000e+00
PA1 = 0.000000e+00
PA2 = 0.000000e+00
PTCA0 = 0.000000e+00
PTCA1 = 0.000000e+00
PTCA2 = 0.000000e+00
PTCB0 = 0.000000e+00
PTCB1 = 0.000000e+00
PTCB2 = 0.000000e+00
POFFSET = 0.000000e+00

volt 0: offset = 0.000000e+00, slope = 1.000000e+00
volt 1: offset = 0.000000e+00, slope = 1.000000e+00
volt 2: offset = 0.000000e+00, slope = 1.000000e+00
volt 3: offset = 0.000000e+00, slope = 1.000000e+00

EXTFREQSF = 1.000000e+00

Notes:
- Dates shown are when calibrations were performed. Calibration coefficients are initially factory-set and should agree with Calibration Certificates shipped with 19plus.
- See individual Coefficient Commands below for definitions of the data in the example.
### Calibration Coefficients Commands (continued)

The individual Coefficient Commands listed below are used to modify a particular coefficient or date:

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Temperature</strong></td>
<td></td>
</tr>
<tr>
<td>TCALDATE=S</td>
<td>S=calibration date</td>
</tr>
<tr>
<td>TA0=F</td>
<td>F=A0</td>
</tr>
<tr>
<td>TA1=F</td>
<td>F=A1</td>
</tr>
<tr>
<td>TA2=F</td>
<td>F=A2</td>
</tr>
<tr>
<td>TA3=F</td>
<td>F=A3</td>
</tr>
<tr>
<td>TOFFSET=F</td>
<td>F=offset correction</td>
</tr>
<tr>
<td><strong>Conductivity</strong></td>
<td></td>
</tr>
<tr>
<td>CCALDATE=S</td>
<td>S=calibration date</td>
</tr>
<tr>
<td>CG=F</td>
<td>F=G</td>
</tr>
<tr>
<td>CH=F</td>
<td>F=H</td>
</tr>
<tr>
<td>CI=F</td>
<td>F=I</td>
</tr>
<tr>
<td>CJ=F</td>
<td>F=J</td>
</tr>
<tr>
<td>CPCOR=F</td>
<td>F=pcor</td>
</tr>
<tr>
<td>CTCOR=F</td>
<td>F=tcor</td>
</tr>
<tr>
<td>CSLOPE=F</td>
<td>F=slope correction</td>
</tr>
<tr>
<td>CF0=F</td>
<td>F=0 value (compatible state only)</td>
</tr>
<tr>
<td><strong>Pressure - General</strong></td>
<td></td>
</tr>
<tr>
<td>PCALDATE=S</td>
<td>S=calibration date</td>
</tr>
<tr>
<td>PRANGE=F</td>
<td>F=sensor full scale range (psi)</td>
</tr>
<tr>
<td>POFFSET=F</td>
<td>F=offset correction</td>
</tr>
<tr>
<td><strong>Strain-Gauge Pressure</strong></td>
<td></td>
</tr>
<tr>
<td>PA0=F</td>
<td>F=A0</td>
</tr>
<tr>
<td>PA1=F</td>
<td>F=A1</td>
</tr>
<tr>
<td>PA2=F</td>
<td>F=A2</td>
</tr>
<tr>
<td>PTEMPA0=F</td>
<td>F=pressure temperature A0</td>
</tr>
<tr>
<td>PTEMPA1=F</td>
<td>F=pressure temperature A1</td>
</tr>
<tr>
<td>PTEMPA2=F</td>
<td>F=pressure temperature A2</td>
</tr>
<tr>
<td>PTCA0=F</td>
<td>F=pressure temperature compensation ptca0</td>
</tr>
<tr>
<td>PTCA1=F</td>
<td>F=pressure temperature compensation ptca1</td>
</tr>
<tr>
<td>PTCA2=F</td>
<td>F=pressure temperature compensation ptca2</td>
</tr>
<tr>
<td>PTCB0=F</td>
<td>F=pressure temperature compensation ptcb0</td>
</tr>
<tr>
<td>PTCB1=F</td>
<td>F=pressure temperature compensation ptcb1</td>
</tr>
<tr>
<td>PTCB2=F</td>
<td>F=pressure temperature compensation ptcb2</td>
</tr>
</tbody>
</table>

Notes:
- **F** = floating point number
- **S** = string with no spaces
- If using auxiliary A/D sensors (VOLT0 through VOLT3), their calibration coefficients are not stored in the SBE 19plus' EEPROM, but are stored in the SBE 19plus' configuration (.con) file. View and/or modify the calibration coefficients using the Configure menu in SBE Data Processing or SEASAVE.
## Data Output Formats

**Notes:**
- If your SBE 19plus includes a custom RS-232 connector for an SBE 38 or GTD, see Addendum: Custom SBE 19plus SEACAT with Interface for RS-232 Sensor.
- See Appendix IV: Compatible State for information on commands and output format for Compatible State custom applications.

The SBE 19plus stores data in a compact machine code. Data is converted and output in the user-selected format when uploading, without affecting data in memory. Because memory data remains intact until deliberately overwritten, you can upload in one format, then choose another format and upload again.

Output format is dependent on **OUTPUTFORMAT** (=0, 1, 2, 3, or 4), as detailed below. The inclusion of some data is dependent on the system configuration - if the system does not include the specified sensor, the corresponding data is not included in the output data stream, shortening the data string.

**OUTPUTFORMAT=0** (raw frequencies and voltages in Hex)

Data is output in the order listed, with no spaces or commas between parameters. Shown with each parameter is the number of digits, and how to calculate the parameter from the data (use the decimal equivalent of the hex data in the equations).

1. **Temperature**
   
   A/D counts = tttttt
   
   Example: Profiling mode, two external voltages sampled, example scan = tttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttttt
OUTPUTFORMAT=1 (engineering units in Hex)

Data is output in the order listed, with no spaces or commas between the parameters. Shown with each parameter is the number of digits, and how to calculate the parameter from the data (use the decimal equivalent of the hex data in the equations).

1. Temperature
   temperature (°C, ITS-90) = (ttttt / 100,000) - 10
2. Conductivity
   Conductivity (S/m) = (cccccc / 1,000,000) - 1
3. Pressure
   pressure (decibars) = (pppppp / 1,000) - 100
4. External voltage 0 (if VOLT0=Y)
   external voltage 0 = vvvv / 13,107
5. External voltage 1 (if VOLT1=Y)
   external voltage 1 = vvvv / 13,107
6. External voltage 2 (if VOLT2=Y)
   external voltage 2 = vvvv / 13,107
7. External voltage 3 (if VOLT3=Y)
   external voltage 3 = vvvv / 13,107
8. Time (Moored mode [MM] only)
   seconds since January 1, 1980 = ssssssss

Example: Profiling mode, two external voltages sampled, example scan = ttttttttttttttttttttccccccppppppvvvvvvvv
   = 3385C40F42FE0186DE03050594
   - Temperature = tttttt = 3385C4 (3376580 decimal);
     temperature (°C, ITS-90) = (3376580 / 100,000) - 10 = 23.7658
   - Conductivity = cccccc = 0F42FE (1000190 decimal);
     conductivity (S/m) = (1000190 / 1,000,000) - 1 = 0.00019
   - Pressure = pppppp = 0186DE (100062 decimal);
     pressure (decibars) = (100062 / 1,000) - 100 = 0.062
   - First external voltage = vvvv = 0305 (773 decimal);
     voltage = 773 / 13,107 = 0.0590 volts
   - Second external voltage = vvvv = 0594 (1428 decimal);
     voltage = 1428 / 13,107 = 0.1089 volts
**OUTPUTFORMAT=2 (raw frequencies and voltages in decimal)**

Data is output in the order listed, with a comma followed by a space between each parameter. Shown with each parameter are the number of digits and the placement of the decimal point. Leading zeros are suppressed, except for one zero to the left of the decimal point.

1. Temperature  
   A/D counts = ttttt
2. Conductivity  
   conductivity frequency (Hz) = cccc.ccc
3. Strain-gauge pressure sensor pressure (if PTYPE=1)  
   A/D counts = pppppp
4. Strain-gauge pressure sensor pressure temperature compensation (if PTYPE=1)  
   pressure temperature compensation voltage = v.vvvv
5. External voltage 0 (if VOLT0=Y)  
   external voltage 0 = v.vvvv
6. External voltage 1 (if VOLT1=Y)  
   external voltage 1 = v.vvvv
7. External voltage 2 (if VOLT2=Y)  
   external voltage 2 = v.vvvv
8. External voltage 3 (if VOLT3=Y)  
   external voltage 3 = v.vvvv
9. Time (Moored mode [MM] only)  
   date, time = dd mmm yyyy, hh:mm:ss (day month year hour:minute:second)

**Example:** Profiling mode with two external voltages sampled, example scan = ttttt, cccc.ccc, pppppp, v.vvvv, v.vvvv, v.vvvv  
= 676721, 7111.133, 791745, 2.4514, 0.0590, 0.1089

- Temperature = ttttt = 676721;  
  temperature A/D counts = 676721
- Conductivity = cccc.ccc = 7111.133;  
  conductivity frequency = 7111.133 Hz
- Strain-gauge pressure = pppppp = 791745;  
  Strain-gauge pressure A/D counts = 791745
- Strain-gauge temperature compensation = v.vvvv = 2.4514;  
  Strain-gauge temperature = 2.4514 volts
- First external voltage = v.vvvv = 0.0590;  
  voltage = 0.0590 volts
- Second external voltage = v.vvvv = 0.1089;  
  voltage = 0.1089 volts
Data is output in the order listed, with a comma followed by a space between each parameter. Shown with each parameter are the number of digits and the placement of the decimal point. Leading zeros are suppressed, except for one zero to the left of the decimal point.

1. Temperature
   temperature (°C, ITS-90) = ttt.tt
2. Conductivity
   Conductivity (S/m) = cc.ccc
3. Pressure
   pressure (decibars) = pppp.pp
4. External voltage 0 (if VOLTO=Y)
   external voltage 0 = v.vvvv
5. External voltage 1 (if VOLT1=Y)
   external voltage 1 = v.vvvv
6. External voltage 2 (if VOLT2=Y)
   external voltage 2 = v.vvvv
7. External voltage 3 (if VOLT3=Y)
   external voltage 3 = v.vvvv
8. Salinity (if OUTPUTSAL=Y)
   salinity (psu) = sss.sss
9. Sound velocity (if OUTPUTSV=Y)
   sound velocity (meters/second) = vvvv.vv
10. Time (Moored mode [MM] only)
    date, time = dd mmm yyyy, hh:mm:ss (day month year hour:minute:second)

Example: Profiling mode with two external voltages sampled, example scan = ttt.tt, cc.ccc, pppp.ppp, v.vvvv, v.vvvv
   = 23.7658, 0.00019, 0.062, 0.0590, 0.1089

   - Temperature = ttt.tt = 23.7658;
     temperature (°C, ITS-90) = 23.7658
   - Conductivity = cc.ccc = 0.00019;
     conductivity (S/m) = 0.00019
   - Pressure = pppp.ppp = 0.062;
     pressure (decibars) = 0.062
   - First external voltage = v.vvvv = 0.0590;
     voltage = 0.0590 volts
   - Second external voltage = v.vvvv = 0.1089;
     voltage = 0.1089 volts
OUTPUTFORMAT=4 (pressure and scan number in Hex)

Data is output in the order listed, with no spaces or commas between parameters. Shown with each parameter is the number of digits, and how to calculate the parameter from the data (use the decimal equivalent of the hex data in the equations).

The SBE 19plus is automatically set to OUTPUTFORMAT=4 when communicating with the 90208 Auto Fire Module (AFM). This allows the AFM to use the SBE 19plus’ pressure data to determine when to close SBE 32 Carousel water bottles.

1. Pressure
   pressure (decibars) = pppp - 100
2. Scan number = ssssss

Example: SBE 19plus used with AFM and Carousel,
example scan = ppppssssss
   = 00C80001F0
   - Pressure = pppp = 00C8 (200 decimal);
     pressure (decibars) = 200 - 100 = 100 decibars
   - Scan number = sssss = 0001F0 (496 decimal);
     scan number = 496
Optimizing Data Quality in Profiling Applications

A profiling speed of approximately 1 meter/second usually provides good quality data. However, the amount of ship motion, and the dynamic effect it has on data quality, must be considered as operating conditions change. Slow profiling speeds (especially with an unpumped CTD) cause reduced flushing of the conductivity cell, and salinity spiking can be severe in areas of strong temperature gradients. In rough seas or other conditions (small boats) where the ship’s dynamic motion is large, increase the profiling speed to as much as 2 to 3 meters/second to reduce dynamic errors (spiking) caused by the rapidly changing descent/ascent rate of the SBE 19plus (yo-yo effect).

An SBE 19plus with the standard pump can get better data with slow descent rates than an unpumped CTD. Since the pump creates and maintains a constant and optimum flow, the SBE 19plus can be lowered more slowly to give greater vertical resolution in the data, especially on lakes or protected bays, or in other calm conditions. Adjust the descent rate for a pumped SBE 19plus according to the amount of ship motion (i.e., sea state). On a very calm lake, 10 cm/second is feasible if used with a constant winch speed.

In common with other CTDs, the SBE 19plus is intended for obtaining downcast data, and will not generally give best quality results on the upcast. If you must have good quality upcast data, invert the SBE 19plus so that the sensors are at the top (ignore the downcast data for this configuration). Position the SBE 19plus so that other instruments, sample bottles, etc. do not thermally contaminate the water that flows past the sensors.

When an SBE 19plus is installed on a water sampler, good conductivity and optional dissolved oxygen data can be collected, even when stopped to collect a water sample, because water continues to flow through the sensors. However, the manner in which the SBE 19plus is mounted on the water sampler can have a dramatic effect on data quality. Ensure that the SBE 19plus is mounted so that it is sampling undisturbed water (i.e., do not mount behind an obstruction).

Where the water temperature is very different from the temperature at which the SBE 19plus has been stored, better results are obtained if the SBE 19plus is allowed to equilibrate to the water temperature at the surface (soak) for several minutes before beginning the profile. The reason is not that the electronics are temperature sensitive - they are not - but that the thermal influence of the instrument housing on the water entering the cell will be reduced. If the difference between water and storage temperature is extreme, allow more soak time.

Spiking is sometimes seen in the derived values for salinity, density, or sound velocity. Spiking results largely from a response time mismatch of the conductivity and temperature sensors, especially when the profiling descent rate is non-uniform. The greatest reduction in spiking is found by using premium CTD equipment such as the SBE 9plus, which uses very fast sensors (0.07 second) and high speed (24 Hz) parallel signal acquisition. The SBE 19plus’ static accuracy is the same as that of the SBE 9plus, but its dynamic responses are not as ideal, as a result of its simpler, less costly, and more compact design.

The amount of spiking depends on the temperature gradient, and is much worse when coupled surface motion causes the instrument to stop - or even reverse - its descent. In the event of heavy ship motion, it may be worth letting the instrument free-fall. When very heavy seas cause severe ship motion and result in periodic reversals of the instrument descent, the data set can be greatly improved by removing scans taken when the pressure is not increasing.

Note: See the SBE Data Processing manual for information on data processing modules that can correct data for the influences of ship motion and minimize salinity spiking.
Setup for Deployment

1. Install new batteries or ensure the existing batteries have enough capacity to cover the intended deployment (see Replacing/Recharging Batteries in Section 5: Routine Maintenance and Calibration).

2. Program the SBE 19+ for the intended deployment using SEATERM (see Section 3: Power and Communications Test for connection information; see information in this section on commands and sampling modes):
   
   A. Set the date and then time (if not already done).

   B. Ensure all data has been uploaded, and then send the INITLOGGING command to make the entire memory available for recording. If INITLOGGING is not sent, data will be stored after the last recorded sample.

   C. Establish the setup and logging parameters. If you will be using SEASAVE to acquire and view real-time data, you must set OUTPUTFORMAT = 0 (raw hexadecimal).

   D. If desired, use STARTMMDDYY=, STARTHHMMSS=, and STARTLATER commands to establish delayed start date and time for Profiling mode (if IGNORESWITCH=Y) or Moored mode.

3. If you will be using SEASAVE to acquire and view real-time data, verify that the configuration (.con) file matches the instrument configuration. Sea-Bird supplies a .con file that reflects the current instrument configuration as we know it. The .con file is named with the instrument serial number, followed with the .con extension. For example, for an instrument with serial number 2375, Sea-Bird names the .con file 2375.con. You may rename the .con file if desired; this will not affect the results.

4. If you will be using SEATERM to view real-time data, press the Capture button on the Toolbar to save the data to a file.
Deployment

The SBE 19plus is available with optional mounting clamps for moored applications.

1. Install a cable or dummy plug for each connector on the SBE 19plus sensor end cap:
   A. Lightly lubricate the inside of the dummy plug/cable connector with silicone grease (DC-4 or equivalent).
   B. **Standard Connector** - Install the plug/cable connector, aligning the raised bump on the side of the plug/cable connector with the large pin (pin 1 - ground) on the SBE 19plus. Remove any trapped air by *burping* or gently squeezing the plug/connector near the top and moving your fingers toward the end cap. **OR**
      **MCBH Connector** – Install the plug/cable connector, aligning the pins.
   C. Place the locking sleeve over the plug/cable connector. Tighten the locking sleeve finger tight only. **Do not overtighten the locking sleeve and do not use a wrench or pliers.**

2. Connect the other end of the cables installed in Step 1 to the appropriate sensors.

3. Verify that the hardware and external fittings are secure.

4. If applicable, remove the Tygon tubing that was looped end-to-end around the conductivity cell for storage. Reconnect the tubing from the pump to the conductivity cell.

5. **Profiling mode** - Immediately prior to deployment:
   - (if `IGNORESWITCH=N`) Turn on the magnetic switch, **or**
   - (if `IGNORESWITCH=Y`) If not already done, send the `STARTNOW` or `STARTMMDDYY`, `STARTHHMMSS`, and `STARTLATER` commands, **or**
   - (if `AUTORUN=Y`) With the SBE 19plus in quiescent (sleep) state, apply external power.

6. **Moored mode** - If not already done, send the `STARTNOW` or `STARTMMDDYY`, `STARTHHMMSS`, and `STARTLATER` commands.

The SBE 19plus is ready to go into the water.
Acquiring Real-Time Data with SEASAVE

Notes:
- When we ship a new instrument, we include a .con file that reflects the current instrument configuration as we know it. The .con file is named with the instrument serial number, followed with the .con extension. For example, for an instrument with serial number 2375, we name the .con file 2375.con. You may rename the .con file if desired; this will not affect the results.
- In SEATERM's setup commands, external voltage numbers 0, 1, 2, and 3 correspond to wiring of sensors to a voltage channel on the end cap (see Dimensions and End Cap Connectors in Section 2: Description of SBE 19plus). However, in the .con file, voltage 0 is the first external voltage in the data stream, voltage 1 is the second, etc.

Verify Contents of .con File

SEASAVE, Sea-Bird's real-time data acquisition and display program, requires a .con file, which defines the instrument - auxiliary sensors integrated with the instrument, and channels, serial numbers, and calibration dates and coefficients for all the sensors (conductivity, temperature, and pressure as well as auxiliary sensors). SEASAVE (as well as our data processing software) uses the information in the .con file to interpret and process the raw data. If the .con file does not match the actual instrument configuration, the software will not be able to interpret and process data correctly.

1. Double click on Seasave.exe.
2. In the Configure menu, select New Style Instrument Configuration / Select Instrument Configuration. In the dialog box, select the appropriate .con file and click Open.
3. In the Configure menu, select New Style Instrument Configuration / Modify Selected Instrument Configuration. The configuration dialog box appears. Verify that the sensors match those on your SBE 19plus, and that auxiliary sensors are assigned to the correct voltage channels. Verify that the calibration coefficients for all the sensors are up-to-date.

4. Click Save or Save As to save any changes to the .con file. Click Exit when done reviewing / modifying the .con file.
**Acquiring Real-Time Data**

Instructions below are for an SBE 19plus with a conventional single-core armored cable, used without a Sea-Bird Deck Unit. If using the SBE 19plus with the SBE 33 or 36 Deck Unit, see the Deck Unit manual.

1. **Wiring** - Terminate the single-core armored cable with an RMG-4FS connector. Wire the cable armor to pin 1 (large pin) and the inner conductor to pin 3 (opposite large pin) on the SBE 19plus' data I/O connector. On deck, wire:

<table>
<thead>
<tr>
<th>Slip-ring lead</th>
<th>25-pin serial port</th>
<th>9-pin serial port</th>
</tr>
</thead>
<tbody>
<tr>
<td>from armor</td>
<td>Pin 7</td>
<td>Pin 5</td>
</tr>
<tr>
<td>from inner conductor</td>
<td>Pin 3</td>
<td>Pin 2</td>
</tr>
</tbody>
</table>

2. **Double click on Seasave.exe.**

3. **Perform any desired setup in the Configure and ScreenDisplay menus.**

4. **In the RealTime Data menu, select Start Acquisition.**

5. **Click COMM Port Configuration.**

   Make the desired selections and click OK.
6. In the Acquire and Display Real Time Data Set Up dialog box, click Start Acquire.
   A. If SEASAVE was set up to prompt for header information (Configure menu / Header Form), the Header Information dialog box appears. Fill in the desired information to be added to the real-time data file header, and click OK.
   B. SEASAVE prompts Turn on the SBE 19plus using the magnetic switch. If you have already started logging data to memory, ignore the prompt; otherwise, slide the switch to the On position. Real-time data then starts appearing in the screen display(s).

7. When done acquiring data, in the RealTime Data menu, select Stop Acquisition.

8. Stop logging:
   - (if IGNORESWITCH=N) Put the magnetic switch in the Off position, or
   - (if IGNORESWITCH=Y) Send the STOP command in SEATERM, or
   - (if AUTORUN=Y) Remove external power.

---

**Recovery**

**WARNING!**
Pressure housings may flood under pressure due to dirty or damaged o-rings, or other failed seals, causing highly compressed air to be trapped inside. If this happens, a potentially life-threatening explosion can occur when the instrument is brought to the surface. If the SBE 19plus is unresponsive to commands or shows other signs of flooding or damage, carefully secure the instrument in a location away from people until it has been determined that abnormal internal pressure does not exist. Contact Sea-Bird for assistance with procedures for safely relieving internal pressure.

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**Physical Handling**

1. Rinse the conductivity cell with fresh water. (See Section 5: Routine Maintenance and Calibration for cell cleaning and storage.)

2. If the batteries are exhausted, new batteries must be installed before the data can be extracted. Stored data will not be lost as a result of exhaustion or removal of batteries. (See Section 5: Routine Maintenance and Calibration for replacement of batteries.)

3. If immediate redeployment is not required, it is best to leave the SBE 19plus with batteries in place and in a quiescent state (QS). Because the quiescent current required is only 30 microamps, the batteries can be left in place without significant loss of capacity.
Uploading Data

1. Double click on SeaTerm.exe. The display shows the main screen.

2. In the Configure menu, select SBE 19plus. Click on the Upload Settings tab. The dialog box looks like this:

3. Click on the Header Information tab. The dialog box looks like this:

Make the selection for Upload Settings.

4. Click on the Header Information tab. The dialog box looks like this:

Select the desired header information option. Click OK to overwrite an existing COM/Upload/Header Settings file, or click Save As to save the settings as a new filename.

---

Note:
Data may be uploaded during deployment or after recovery. If uploading after recovery, connect the I/O cable as described in Section 3: Power and Communications Test.

Note:
Set up Upload Settings, Header Information, and/or Header Form (Steps 2 through 4):
• The first time you upload data, and
• If you want to change upload or header parameters.

Defines data upload type when using Upload button on Toolbar or Upload Data in Data menu:
• All as single file – All data uploaded into one file.
• All separated by cast (Profiling mode only) - All data uploaded. Separate file is written for each cast, with 3-digit cast identification number (001 to 301) appended to user-selected file name
• By scan number range – SEATERM prompts for beginning and ending scan (sample) numbers, and uploads all data within range into one file.
• From a single cast (Profiling mode only) - SEATERM prompts for cast number, and uploads all data from that cast into one file.
• By cast number range (Profiling mode only) - SEATERM prompts for beginning and ending cast numbers, and uploads data within that range. Separate file is written for each cast, with 3-digit cast identification number (001 to 301) appended to user-selected file name.

Baud rate for uploading data from SBE 19plus to computer; same as baud rate on COM Settings tab.

Defines data upload type when using Upload button on Toolbar or Upload Data in Data menu:
• All as single file – All data uploaded into one file.
• All separated by cast (Profiling mode only) - All data uploaded. Separate file is written for each cast, with 3-digit cast identification number (001 to 301) appended to user-selected file name
• By scan number range – SEATERM prompts for beginning and ending scan (sample) numbers, and uploads all data within range into one file.
• From a single cast (Profiling mode only) - SEATERM prompts for cast number, and uploads all data from that cast into one file.
• By cast number range (Profiling mode only) - SEATERM prompts for beginning and ending cast numbers, and uploads data within that range. Separate file is written for each cast, with 3-digit cast identification number (001 to 301) appended to user-selected file name.

Note:
Set up Upload Settings, Header Information, and/or Header Form (Steps 2 through 4):
• The first time you upload data, and
• If you want to change upload or header parameters.

Defines header information included with uploaded data:
• Prompt for header information – Each time data is uploaded, user is prompted to fill out user-defined header form.
• Include default header form in upload file – User-defined default header form included in upload file. User is not prompted to add any information when data is uploaded.
• Don’t include default header form in upload file – Header information not included in upload file.
4. In the Configure menu, select Header Form to customize the header. The dialog box looks like this (default prompts are shown):

The entries are free form, 0 to 12 lines long. This dialog box establishes:
- the header prompts that appear for the user to fill in when uploading data, if Prompt for header information was selected in the Configuration Options dialog box (Step 3)
- the header included with the uploaded data, if Include default header form in upload file was selected in the Configuration Options dialog box (Step 3)

Enter the desired header/header prompts. Click OK.

5. Click Connect on the Toolbar to begin communications with the SBE 19plus. The display looks like this:

S>

This shows that correct communications between the computer and the SBE 19plus has been established.

If the system does not respond as shown above:
- Click Connect again.
- Check cabling between the computer and the SBE 19plus.
- Verify the correct instrument was selected and the COM settings were entered correctly in the Configure menu.

6. Command the SBE 19plus to stop data logging by the method applicable to your instrument’s setup:
- Pressing the Enter key and sending the STOP command, or
- Moving the magnetic switch to the Off position (only applicable in Profiling mode, if IGNORESWITCH=N)
7. Display SBE 19 plus status information by clicking Status on the Toolbar. The display looks like this (if in Profiling mode):

SeacatPlus V 1.3  SERIAL NO. 4000  25 Jun 2001  14:02:13
vbatt = 9.6, vlith = 0.0, ioper = 61.2 ma, ipump = 25.5 ma,
iext01 = 76.2 ma,
status = not logging
number of scans to average = 1
samples = 5000, free = 376300, casts = 1
mode = profile, minimum cond freq = 3000, pump delay = 60 sec
autorus = no, ignore magnetic switch = no
battery type = ALKALINE, battery cutoff = 7.5 volts
pressure sensor = strain gauge, range = 1000.0
SBE 38 = no, Gas Tension Device = no
Ext Volt 0 = yes, Ext Volt 1 = no, Ext Volt 2 = no, Ext Volt 3 = no
echo commands = yes
output format = converted decimal
output salinity = no, output sound velocity = no

8. Click the Upload button on the Toolbar to upload stored data in a form that Sea-Bird’s data processing software can use. SEATERM responds as follows:

A. SEATERM sends the OUTPUTFORMAT=0 command to set the output format to raw hexadecimal.
B. SEATERM sends the status (DS), header (DH), and calibration coefficients (DCAL) commands, displays the responses, and writes the commands and responses to the upload file. These commands provide you with information regarding the number of samples in memory, mode, cast numbers, etc.
C. If you selected By scan number range, From a single cast, or By cast number range in the Configuration Options dialog box (Configure menu) – a dialog box requests the range or cast number, as applicable. Enter the desired value(s), and click OK.
D. If you selected Prompt for header information in the Configuration Options dialog box (Configure menu) – a dialog box with the header form appears. Enter the desired header information, and click OK. SEATERM writes the header information to the upload file.
E. In the Open dialog box, enter the desired upload file name and click OK. The upload file has a .hex extension. If you selected All separated by cast or By cast number range, SEATERM will automatically append the 3-digit cast identification number to the upload file name (for example, if you specify the upload file name as test and upload casts 1 and 2, SEATERM will create test001.hex and test002.hex).
F. SEATERM sends the data upload command (DCn or DD[n]e as applicable).
G. If you selected Prompt for header information in the Configuration Options dialog box (Configure menu) – SEATERM repeats Steps D and F for each cast.
H. When the data has been uploaded, SEATERM shows the S> prompt.

9. Ensure all data has been uploaded from the SBE 19 plus by reviewing and processing the data:

A. Use SEASAVE to display the raw hexadecimal data from the SBE 19 plus in engineering units (see SEASAVE’s manual/Help files).
B. Use SBE Data Processing to process and plot the data (see SBE Data Processing manual/Help files).

Notes:
To prepare for redeployment:
1. After all data has been uploaded, send INITLOGGING. If this command is not sent, new data will be stored after the last recorded sample, preventing use of the entire memory capacity.
2. Send QS to put the SBE 19 plus in quiescent (sleep) state until ready to redeploy. Quiescent current is only 30 microamps, so the batteries can be left in place without significant loss of capacity.
Processing Data

Sea-Bird provides software, SBE Data Processing, for converting the raw .hex data file into engineering units, editing (aligning, filtering, removing bad data, etc.) the data, calculating derived variables, and plotting the processed data.

However, sometimes users want to edit the raw .hex data file before beginning processing, to remove data at the beginning of the file corresponding to instrument soak time, to remove blocks of bad data, to edit the header, or to add explanatory notes about the cast. **Editing the raw .hex file can corrupt the data, making it impossible to perform further processing using Sea-Bird software.** Sea-Bird strongly recommends that you first convert the data to a .cnv file (using the DATA CONVERSION module in SBE Data Processing), and then use other SBE Data Processing modules to edit the .cnv file as desired.

The procedure for editing a .hex data file described below has been found to work correctly on computers running Windows 98, 2000, and NT. **If the editing is not performed using this technique, SBE Data Processing may reject the edited data file and give you an error message.**

1. Make a back-up copy of your .hex data file before you begin.
2. Run **WordPad.**
3. In the File menu, select Open. The Open dialog box appears. For Files of type, select All Documents (*.*). Browse to the desired .hex data file and click Open.
4. Edit the file as desired, inserting any new header lines after the System Upload Time line. Note that all header lines must begin with an asterisk (*), and *END* indicates the end of the header. An example is shown below (for an SBE 21), with the added lines in bold:

   * Sea-Bird SBE 21 Data File:
   * FileName = C:\Odis\SAT2-ODIS\oct14-19\oc15_99.hex
   * Software Version Seasave Win32 v1.10
   * Temperature SN = 2366
   * Conductivity SN = 2366
   * System UpLoad Time = Oct 15 1999  10:57:19
   * Testing adding header lines
   * Must start with an asterisk
   * Place anywhere between System Upload Time & END of header
   * NMEA Latitude = 30 59.70 N
   * NMEA Longitude = 081 37.93 W
   * NMEA UTC (Time) = Oct 15 1999  10:57:19
   * Store Lat/Lon Data = Append to Every Scan and Append to .NAV File When <Ctrl F7> is Pressed
   ** Ship:       Sea-Bird
   ** Cruise:     Sea-Bird Header Test
   ** Station:
   ** Latitude:
   ** Longitude:
   *END*

5. In the File menu, select Save (not Save As). If you are running Windows 2000, the following message displays:

   You are about to save the document in a Text-Only format, which will remove all formatting. Are you sure you want to do this?

   Ignore the message and click Yes.

6. In the File menu, select Exit.
Section 5: Routine Maintenance and Calibration

This section reviews corrosion precautions, connector mating and maintenance, plumbing maintenance, replacing/recharging batteries, conductivity cell storage and cleaning, pressure sensor maintenance, replacing optional Anti-Foulant Devices, and sensor calibration. The accuracy of the SBE 19plus is sustained by the care and calibration of the sensors and by establishing proper handling practices.

Corrosion Precautions

Rinse the SBE 19plus with fresh water after use and prior to storage.

For both the plastic and titanium housing, all exposed metal is titanium (the plastic housing has a titanium end cap). No corrosion precautions are required, but avoid direct electrical connection of the titanium to dissimilar metal hardware.

Connector Mating and Maintenance

Mated connectors do not require periodic disassembly or other attention. Inspect connectors that are unmated for signs of corrosion product around the pins. When remating:

1. Lightly lubricate the inside of the dummy plug/cable connector with silicone grease (DC-4 or equivalent).
2. **Standard Connector** - Install the plug/cable connector, aligning the raised bump on the side of the plug/cable connector with the large pin (pin 1 - ground) on the SBE 19plus. Remove any trapped air by burping or gently squeezing the plug/connector near the top and moving your fingers toward the end cap.  **OR**  
   **MCBH Connector** – Install the plug/cable connector, aligning the pins.
3. Place the locking sleeve over the plug/cable connector. Tighten the locking sleeve finger tight only. **Do not overtighten the locking sleeve and do not use a wrench or pliers.**

Verify that a cable or dummy plug is installed for each connector on the system before deployment.

Plumbing Maintenance

Periodically clean the air release valve with a fine wire. A clogged air release valve can trap air, preventing the pump from functioning properly; this will affect the data quality.
Revising / Recharging Batteries

**Note:**
If changing from alkaline to Ni-Cad batteries, or vice versa, use the BATTERYTYPE= command to indicate the new battery type.

Leave the batteries in place when storing the SBE 19plus to prevent depletion of the back-up lithium batteries by the real-time clock. Even exhausted main batteries will power the clock (30 microamperes) almost indefinitely. If the SBE 19plus is to be stored for long periods, leave the batteries in place and replace them yearly.

**Replacing Alkaline Batteries**

1. Remove the battery end cap (end cap without connectors):
   A. Wipe the outside of the end cap and housing dry, being careful to remove any water at the seam between them.
   B. Unthread the end cap by rotating counter-clockwise (use a wrench on the white plastic bar if necessary).
   C. Remove any water from the O-ring mating surfaces inside the housing with a lint-free cloth or tissue.
   D. Put the end cap aside, being careful to protect the O-ring from damage or contamination.

2. Remove the battery cover plate from the housing:
   A. Remove the three Phillips-head screws and washers from the battery cover plate inside the housing.
   B. The battery cover plate will pop out. Put it aside.

3. Turn the SBE 19plus over and remove the batteries.

4. Install the new batteries, with the + terminals against the flat battery contacts and the - terminals against the spring contacts.

5. Reinstall the battery cover plate in the housing:
   A. Align the battery cover plate with the housing. The posts inside the housing are not placed symmetrically, so the cover plate fits into the housing only one way. Looking at the cover plate, note that one screw hole is closer to the edge than the others, corresponding to the post that is closest to the housing.
   B. Reinstall the three Phillips-head screws and washers, while pushing hard on the battery cover plate to depress the spring contacts at the bottom of the battery compartment. **The screws must be fully tightened, or battery power to the circuitry will be intermittent.**

6. Check the battery voltage at BAT + and BAT - on the battery cover plate. It should be approximately 13.5 volts.

7. Reinstall the battery end cap:
   A. Remove any water from the O-rings and mating surfaces with a lint-free cloth or tissue. Inspect the O-rings and mating surfaces for dirt, nicks, and cuts. Clean or replace as necessary. Apply a light coat of o-ring lubricant (Parker Super O Lube) to O-rings and mating surfaces.
   B. Carefully fit the end cap into the housing and rethread the end cap into place. Use a wrench on the white plastic bar to ensure the end cap is tightly secured.

Verify that the magnetic switch on the conductivity cell guard is in the Off position, so the SBE 19plus will be in quiescent (sleep) state.
Section 5: Routine Maintenance and Calibration

Recharging Optional Nickel-Cadmium Batteries

1. Remove the battery end cap (end cap without connectors):
   A. Wipe the outside of the end cap and housing dry, being careful to remove any water at the seam between them.
   B. Unthread the end cap by rotating counter-clockwise (use a wrench on the white plastic bar if necessary).
   C. Remove any water from the O-ring mating surfaces inside the housing with a lint-free cloth or tissue.
   D. Put the end cap aside, being careful to protect the O-ring from damage or contamination.

2. Recharge the batteries:
   A. Connect the battery charger leads to the battery cover pin jacks, matching black-to-black and red-to-red (the pin jacks are different sizes to prevent cross-wiring).
   B. Plug the battery charger into a suitable AC mains power source.
   C. The red Charge LED on the charger comes on. Recharging takes approximately 15 hours. When recharging is complete, the yellow Trickle LED comes on, indicating the charger is providing a maintenance level charge.
   D. Disconnect the battery pack from the charger and the charger from the power source.
   E. Check the voltage at BAT + and BAT – on the battery cover. It should be approximately 13.5 volts.

3. Reinstall the battery end cap:
   A. Remove any water from the O-rings and mating surfaces with a lint-free cloth or tissue. Inspect the O-rings and mating surfaces for dirt, nicks, and cuts. Clean or replace as necessary. Apply a light coat of O-ring lubricant (Parker Super O Lube) to O-rings and mating surfaces.
   B. Carefully fit the end cap into the housing and rethread the end cap into place. Use a wrench on the white plastic bar to ensure the end cap is tightly secured.

Verify that the magnetic switch on the conductivity cell guard is in the Off position, so the SBE 19plus will be in quiescent (sleep) state.
Conductivity Cell Maintenance

The SBE 19plus' conductivity cell is shipped dry to prevent freezing in shipping. Sea-Bird recommendations follow for three situations:
- Active use - storing for one day or less between uses
- Storage - storing for longer than one day
- Cleaning

Active Use (storing for one day or less)
1. After each recovery, rinse the cell with clean, de-ionized water and drain.
   - If the cell is not rinsed between uses, salt crystals may form on the platinized electrode surfaces. When the instrument is used next, sensor accuracy may be temporarily affected until these crystals dissolve.
2. Fill the cell with a 0.1% solution of Triton X-100 (included with shipment), using a length of Tygon tubing attached to each end of the cell to close the cell ends.
   - The Triton X-100 solution is a mild, non-ionic detergent that keeps contamination from ocean surface film, aerosols, and spray/wash on the ship deck from harming the cell calibration.

Storage (storing for longer than one day)
1. Rinse the cell with clean, de-ionized water and drain. Remove larger droplets of water by blowing through the cell. **Do not use compressed air**, which typically contains oil vapor.
2. Attach a length of Tygon tubing from one end of the conductivity cell to the other, to prevent dust and aerosols from entering the cell during storage.
3. When ready to deploy again - Fill the cell with a 0.1% solution of Triton X-100 for 1 hour before deployment. Then remove the looped Tygon tubing, and reconnect the tubing connecting the pump to the conductivity cell.

Cleaning
The rinse and soak procedure recommended for Active Use is generally sufficient. However, occasionally the cell becomes contaminated and requires more intensive cleaning. We recommend two procedures, depending on the type of contamination:

**Triton Cleaning for Ocean Surface Films or Oily Contamination**
1. Heat a stronger (1%-2%) solution of Triton X-100 to less than 60 °C.
2. Agitate the warm solution through the cell many times in a washing action. This can be accomplished with Tygon tubing and a syringe kit.
3. Fill the cell with the solution and let it soak for 1 hour.
4. Drain and flush with clean, de-ionized water for 1 minute. Then:
   - Prepare for deployment, **or**
   - Follow recommendations above for storage.
Section 5: Routine Maintenance and Calibration

**Acid Cleaning for Biological or Mineral Contamination**

1. Prepare for cleaning:
   A. Place a 0.6 m (2 ft) length of Tygon tubing over the end of the cell.
   B. Clamp the SBE 19plus so that the cell is vertical, with the Tygon tubing at the bottom end.
   C. Loop the Tygon tubing into a U shape, and tape the open end of the tubing in place at the same height as the top of the glass cell.

2. Clean the cell:
   A. Pour muriatic acid (37% HCl) into the open end of the tubing until the cell is nearly filled. **Let it soak for 1 minute only.**
   B. Drain the acid from the cell.
   C. Rinse the exterior of the SBE 19plus to remove any spilled acid from the surface.
   D. Flush the cell for 5 minutes with warm (not hot), clean, de-ionized water.
   E. Fill the cell with a 1% solution of Triton X-100 and let it stand for 5 minutes.
   F. Drain and flush with warm, clean, de-ionized water for 1 minute.

3. Prepare for deployment, or Follow recommendations above for storage.

Repeat this procedure a few times for reluctant contamination. Return to Sea-Bird for cleaning if three acid rinses do not restore the cell’s calibration. We recommend that you do not clean with acid more than once per week.

**Pressure Sensor Maintenance**

At the factory, the pressure sensor and pressure port were filled with a silicon oil, and a pressure port plug was used to retain the oil. The oil transmits hydrostatic pressure to the pressure sensor inside the instrument. Because of the viscosity of the silicone oil, the oil does not run out of the pressure sensor port plug. However, due to temperature and pressure cycling over long periods, it is normal for some oil to slowly leak out of the plug. **It is not necessary to refill the oil.**

Periodically (approximately once a year) inspect the pressure port to remove any particles, debris, etc:

1. Unscrew the pressure port plug from the pressure port. The fitting may contain silicon oil from the factory, so there may be some spillage.

2. Rinse the pressure port with warm, de-ionized water to remove any particles, debris, etc.

3. Replace the pressure port plug.

**WARNING!**
Observe all precautions for working with strong acid. Avoid breathing the acid fumes. Work in a well-ventilated area.

**CAUTION:**
Do not put a brush or any object in the pressure port. Doing so may damage or break the pressure sensor.
Recovering Anti-Foulant Devices (SBE 16\textit{plus}, SBE 19\textit{plus})

The SBE 16\textit{plus} and 19\textit{plus} (moored option) have an anti-foulant device cup and cap on each end of the conductivity cell. A new SBE 16\textit{plus} (or moored option 19\textit{plus}) is shipped with an Anti-Foulant Device and a protective plug pre-installed in each cup.

\textbf{Wearing rubber or latex gloves}, follow this procedure to replace each Anti-Foulant Device (two):

1. Remove the protective plug;
2. Unscrew the cap with a 5/8-inch socket wrench;
3. Remove the old Anti-Foulant Device. If the old Anti-Foulant Device is difficult to remove:
   - Use needle-nose pliers and carefully break up material;
   - If necessary, remove the conductivity cell guard to provide easier access;
4. Place the new Anti-Foulant Device in the cup;
5. Rethread the cap onto the cup. Do not overtighten;
6. Replace the protective plug if not ready to redeploy.

\textbf{WARNING!}

AF24173 Anti-Foulant Devices contain bis(tributyltin) oxide. Handle the devices only with rubber or latex gloves. Wear eye protection. Wash with soap and water after handling.

Read precautionary information on product label before proceeding.

It is a violation of US Federal Law to use this product in a manner inconsistent with its labeling.

\textbf{CAUTION:}

One of the anti-foulant device cups is attached to the guard and connected to the conductivity cell. \textbf{Removing the guard without disconnecting the cup from the guard will break the cell}. If the guard must be removed:

1. Remove the two screws connecting the anti-foulant device cup to the guard;
2. Remove the four Phillips-head screws connecting the guard to the housing and sensor end cap;
3. Gently lift the guard away.
Sensor Calibration

Sea-Bird sensors are calibrated by subjecting them to known physical conditions and measuring the sensor responses. Coefficients are then computed, which may be used with appropriate algorithms to obtain engineering units. The conductivity, temperature, and pressure sensors on the SBE 19plus are supplied fully calibrated, with coefficients stored in EEPROM in the SBE 19plus and printed on their respective Calibration Certificates (see back of manual).

We recommend that the SBE 19plus be returned to Sea-Bird for calibration.

Conductivity Sensor Calibration

The conductivity sensor incorporates a fixed precision resistor in parallel with the cell. When the cell is dry and in air, the sensor’s electrical circuitry outputs a frequency representative of the fixed resistor. This frequency is recorded on the Calibration Certificate and should remain stable (within 1 Hz) over time.

The primary mechanism for calibration drift in conductivity sensors is the fouling of the cell by chemical or biological deposits. Fouling changes the cell geometry, resulting in a shift in cell constant.

Accordingly, the most important determinant of long-term sensor accuracy is the cleanliness of the cell. We recommend that the conductivity sensors be calibrated before and after deployment, but particularly when the cell has been exposed to contamination by oil slicks or biological material.

Temperature Sensor Calibration

The primary source of temperature sensor calibration drift is the aging of the thermistor element. Sensor drift will usually be a few thousandths of a degree during the first year, and less in subsequent intervals. Sensor drift is not substantially dependent upon the environmental conditions of use, and — unlike platinum or copper elements — the thermistor is insensitive to shock.

Pressure Sensor Calibration

The SBE 19plus includes a strain-gauge pressure sensor. This sensor is capable of meeting the SBE 19plus’ error specification with some allowance for aging and ambient-temperature induced drift.

For demanding applications, or where the sensor’s air ambient pressure response has changed significantly, calibration using a dead-weight generator is recommended. The end cap’s 7/16-20 straight thread permits mechanical connection to the pressure source. Use a fitting that has an O-ring tapered seal, such as Swagelok-200-1-4ST, which conforms to MS16142 boss.

Note:
After recalibration, Sea-Bird enters the new calibration coefficients in the SBE 19plus’ EEPROM, and ships the instrument back to the user with Calibration Certificates showing the new coefficients. The user must enter the coefficients in the instrument configuration (.con) file in the Configure menu in SEASAVE or SBE Data Processing.
Section 6: Troubleshooting

This section reviews common problems in operating the SBE 19plus, and provides the most likely causes and solutions.

Each SBE 19plus is shipped with a configuration (.con) file that matches the configuration of the instrument (number and type of auxiliary sensors, etc.) and includes the instrument calibration coefficients.

Problem 1: Unable to Communicate

The $> prompt indicates that communications between the SBE 19plus and computer have been established. Before proceeding with troubleshooting, attempt to establish communications again by clicking the Connect button on SEATERM’s toolbar or hitting the Enter key several times.

**Cause/Solution 1**: The I/O cable connection may be loose. Check the cabling between the SBE 19plus and computer for a loose connection.

**Cause/Solution 2**: The instrument type and/or its communication settings may not have been entered correctly in SEATERM. Select the SBE 19plus in the Configure menu and verify the settings in the Configuration Options dialog box. The settings should match those on the instrument Configuration Sheet.

**Cause/Solution 3**: The I/O cable may not be the correct one. The I/O cable supplied with the SBE 19plus permits connection to the DB-25P input connectors used on IBM Asynchronous Adapter Cards, i.e., standard RS-232 interfaces. (Sea-Bird also supplies a 25-to-9 pin adapter, for use if your computer has a 9-pin serial port.)

- SBE 19plus Pin 1 (large pin) goes to DB-25 pin 7 (ground)
- SBE 19plus pin 2 (counter-clockwise from large pin) goes to DB-25 pin 2
- SBE 19plus pin 3 (opposite the large pin) goes to DB-25 pin 3

Problem 2: No Data Recorded

**Cause/Solution 1**: The SBE 19plus’ memory may be full; once the memory is full, no further data is recorded. Verify that the memory is not full using the DS command (free = 0 or 1 if memory is full). Sea-Bird recommends that you upload all previous data before beginning another deployment. Once the data is uploaded, use the INITLOGGING command to reset the memory. After the memory is reset, the DS command will show samples = 0.
Problem 3: Nonsense or Unreasonable Data

The symptom of this problem is an uploaded file that contains nonsense values (for example, 9999.999) or unreasonable values (for example, values that are outside the expected range of the data).

**Cause/Solution 1:** An uploaded data file with nonsense values may be caused by incorrect instrument configuration in the .con file. Verify that the settings in the instrument .con file match the instrument Configuration Sheet.

**Cause/Solution 2:** An uploaded data file with unreasonable (i.e., out of the expected range) values for temperature, conductivity, etc. may be caused by incorrect calibration coefficients in the instrument .con file. Verify the calibration coefficients in the instrument .con file match the instrument Calibration Certificates.

Problem 4: Program Corrupted

**Note:** Using the reset switch does not affect the SBE 19plus’ memory - data in memory and user-programmable parameter values are unaffected.

**Cause/Solution 1:** In rare cases, the program that controls the SBE 19plus’ microprocessor can be corrupted by a severe static shock or other problem. This program can be initialized by using the reset switch. Proceed as follows to initialize:

1. Open the battery end cap and remove the batteries (see *Replacing /Recharging Batteries in Section 5: Routine Maintenance and Calibration*).
2. There is a small, pushbutton switch on the battery compartment bulkhead, which is visible after the batteries are removed. The switch is used to disconnect the internal lithium batteries from the electronics. Push the switch in for 1 second.
3. Reinstall or replace the batteries, and close the battery end cap.
4. Establish communications with the SBE 19plus (see *Section 3: Power and Communications Test*). Use the DS command to verify that the date and time and sample number are correct.
Glossary

**Batteries** – Nine alkaline D-cells standard. Available with optional Ni-Cad batteries.

**Fouling** – Biological growth in the conductivity cell during deployment.

**PCB** – Printed Circuit Board.

**SBE Data Processing** – Sea-Bird’s Win 95/98/NT/2000/XP data processing software, which calculates and plots temperature, conductivity, and pressure, data from auxiliary sensors, and derives variables such as salinity and sound velocity.

**Scan** – One data sample containing temperature, conductivity, pressure, date and time (moored mode only), and optional auxiliary inputs.

**SEACATplus** – High-accuracy conductivity, temperature, and pressure recorder. The SEACATplus is available as the SBE 16plus (moored applications) and SBE 19plus (profiling or moored applications). A plus version of the SBE 21 (thermosalinograph) is under development.

**SEASAVE** – Sea-Bird’s Win 95/98/NT/2000/XP software used to acquire, convert, and display real-time or archived raw data.

**SEASOFT-DOS** – Sea-Bird’s complete DOS software package, which includes software for communication, real-time data acquisition, and data analysis and display. SEASOFT-DOS’ modules for real-time data acquisition and data analysis are not compatible with the SBE 19plus’ data output formats (except for an SBE 19plus operating in Compatible State).

**SEASOFT-Win32** – Sea-Bird’s complete Win 95/98/NT/2000/XP software package, which includes software for communication, real-time data acquisition, and data analysis and display. SEASOFT-Win32 includes SEATERM, SeatermAF, SEASAVE, SBE Data Processing, and Plot39.

**SEATERM** – Sea-Bird’s Win 95/98/NT/2000/XP terminal program used to communicate with the SBE 19plus.

**SeatermAF** – Sea-Bird’s Win 95/98/NT/2000/XP terminal program used to communicate with the SBE 19plus when it is used with a 90208 Auto Fire Module (AFM). See the AFM manual.

**TCXO** – Temperature Compensated Crystal Oscillator.

**Triton X-100** – Concentrated liquid non-ionic detergent, used for cleaning the conductivity cell.
Appendix I: Functional Description and Circuitry

Sensors

The SBE19plus embodies the same sensor elements (3-electrode, 2-terminal, borosilicate glass cell, and pressure-protected thermistor) previously employed in Sea-Bird’s modular SBE 3 and SBE 4 sensors and in the original SEACAT design. The SBE19plus differs from the SBE 19 in that it uses three independent channels to digitize temperature, conductivity, and pressure concurrently. Multiplexing is not used for these channels.

The pressure sensor is a Druck strain-gauge sensor.

Sensor Interface

Temperature is acquired by applying an AC excitation to a bridge circuit containing an ultra-stable aged thermistor with a drift rate of less than 0.002 °C per year. The other elements in the bridge are VISHAY precision resistors. A 24-bit A/D converter digitizes the output of the bridge. AC excitation and ratiometric comparison avoids errors caused by parasitic thermocouples, offset voltages, leakage currents, and reference errors.

Conductivity is acquired using an ultra-precision Wein-Bridge oscillator to generate a frequency output in response to changes in conductivity.

Strain-gauge pressure is acquired by applying an AC excitation to the pressure bridge. A 24-bit A/D converter digitizes the output of the bridge. AC excitation and ratiometric comparison avoids errors caused by parasitic thermocouples, offset voltages, leakage currents, and reference errors. A silicon diode embedded in the pressure bridge is used to measure the temperature of the pressure bridge. This temperature is used to perform offset and span corrections on the measured pressure signal.

The four external 0 to 5 volt DC voltage channels are processed by differential amplifiers with an input resistance of 50K ohms and are digitized with a 14-bit A/D converter.

Real-Time Clock

To minimize power and improve clock accuracy, a temperature-compensated crystal oscillator (TCXO) is used as the real-time-clock frequency source. The TCXO is accurate to ± 1 minute per year (0 °C to 40 °C).
Battery Wiring

SBE 19plus’ main battery is a series connection of D-cells that drop into the battery compartment as a cluster of end-to-end stacks, three batteries each (standard 9-cell battery pack has three stacks). The positive battery connections are contact areas on double-thick printed circuit disks that form the internal bulkhead and battery retainer plates. Battery negative contacts are heavy beryllium-copper springs. The three cell stacks are aligned by plastic insulated aluminum spacers which also serve as electrical interconnects. The battery-to-circuit card connection is made by means of a Molex-type 3-pin pc board connector (JP3 on the power PCB).

The Power PCB contains three series-connected lithium cells (1/2 AA non-hazardous) which are diode OR’d with the main battery (and external power source, if used). The lithium supply is capable of supporting all SBE 19plus functions and serves to permit orderly shutdown in the event of failed or exhausted main batteries. The main batteries can be changed without disturbing memory or the real-time clock.
Appendix II: Electronics Disassembly/Reassembly

CAUTION: Use caution during disassembly and reassembly to avoid breaking the conductivity cell.

Disassembly

1. As a precaution, upload any data in memory before beginning.

2. Remove the two Phillips-head screws holding the conductivity cell guard to the housing. Do not remove the two screws holding the conductivity cell guard to the sensor end cap.

3. Remove the Phillips-head screw holding the sensor end cap to the housing on the side opposite the conductivity cell guard.

4. Remove the sensor end cap (with attached conductivity cell and cell guard) and electronics:
   A. Wipe the outside of the sensor end cap and housing dry, being careful to remove any water at the seam between them.
   B. Slide the end cap and attached electronics out of the housing.
   C. The electronics are electrically connected to the battery compartment bulkhead with a Molex connector. Disconnect the Molex connector.
   D. Remove any water from the O-rings and mating surfaces inside the housing with a lint-free cloth or tissue.
   E. Be careful to protect the O-rings from damage or contamination.

Reassembly

1. Reinstall the sensor end cap, conductivity cell and guard, and electronics:
   A. Remove any water from the O-rings and mating surfaces in the housing with a lint-free cloth or tissue. Inspect the O-rings and mating surfaces for dirt, nicks, and cuts. Clean or replace as necessary. Apply a light coat of O-ring lubricant (Parker Super O Lube) to the O-rings and mating surfaces.
   B. Plug the Molex connector onto the pins on the battery compartment bulkhead. Verify the connector holes and pins are properly aligned.
   C. Carefully fit the end cap and electronics into the housing until the O-rings are fully seated.

2. Reinstall the three screws to secure the end cap.

3. Reset the date and time (MMDDYY= and HHMMSS=) and initialize logging (INITLOGGING) before redeploying. No other parameters should have been affected by the electronics disassembly (send the DS command to verify).

Note: Before delivery, a desiccant package is inserted in the electronics chamber, and the chamber is filled with dry Argon gas. These measures help prevent condensation. If the electronics are exposed to the atmosphere, dry gas backfill with Argon and replace the desiccant package. See Application Note 71: Desiccant Use and Regeneration (drying) for desiccant information. Battery replacement does not affect desiccation of the electronics, as no significant gas exchange is possible unless the electronics PCBs are actually removed from the housing.

CAUTION: Use caution during disassembly and reassembly to avoid breaking the conductivity cell.
## Appendix III: Command Summary

<table>
<thead>
<tr>
<th>CATEGORY</th>
<th>COMMAND</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Status</strong></td>
<td>DS</td>
<td>Display status and setup parameters.</td>
</tr>
<tr>
<td><strong>Setup</strong></td>
<td>MMDDYY=mmddyy</td>
<td>Set real-time clock month, day, year. Follow with HHHMMSS= or it will not set date.</td>
</tr>
<tr>
<td></td>
<td>DDDMMYY=ddmmyy</td>
<td>Set real-time clock day, month, year. Follow with HHHMMSS= or it will not set date.</td>
</tr>
<tr>
<td></td>
<td>HHHMMSS=hhmmss</td>
<td>Set real-time clock hour, minute, second.</td>
</tr>
<tr>
<td></td>
<td>BAUD=x</td>
<td>x= baud rate (1200, 2400, 4800, 9600, 19200, or 38400). Default 9600.</td>
</tr>
<tr>
<td></td>
<td>ECHO=x</td>
<td>x=Y: Echo characters as you type. x=N: Do not.</td>
</tr>
<tr>
<td></td>
<td>MM</td>
<td>Set to Moored mode.</td>
</tr>
<tr>
<td></td>
<td>MP</td>
<td>Set to Profiling mode.</td>
</tr>
<tr>
<td></td>
<td>MOOREDTPXREALTIME=x</td>
<td>Moored mode only. x=Y: Output real-time data. x=N: Do not.</td>
</tr>
<tr>
<td></td>
<td>BATTERYTYPE=x</td>
<td>x=0: Alkaline (or optional lithium) batteries. x=1: Ni-Cad batteries.</td>
</tr>
<tr>
<td></td>
<td>PTYPE=x</td>
<td>x=1: Strain-gauge pressure sensor.</td>
</tr>
<tr>
<td></td>
<td>VOLT0=x</td>
<td>x=Y: Sample external voltage 0. x=N: Do not.</td>
</tr>
<tr>
<td></td>
<td>VOLT1=x</td>
<td>x=Y: Sample external voltage 1. x=N: Do not.</td>
</tr>
<tr>
<td></td>
<td>VOLT2=x</td>
<td>x=Y: Sample external voltage 2. x=N: Do not.</td>
</tr>
<tr>
<td></td>
<td>VOLT3=x</td>
<td>x=Y: Sample external voltage 3. x=N: Do not.</td>
</tr>
<tr>
<td></td>
<td>MOOREDTPMPMODE=x</td>
<td>Moored mode only. x=0: No pump. x=1: Run pump for 0.5 seconds before each sample. x=2: Run pump during each sample.</td>
</tr>
<tr>
<td></td>
<td>DELAYBEFORESAMPLING=x</td>
<td>Moored mode only. x= time (seconds) to wait after switching on external voltage before sampling (0-32,000 seconds). Default 0 seconds.</td>
</tr>
<tr>
<td></td>
<td>MINCONDFREQ=x</td>
<td>Profiling mode only. x= minimum conductivity frequency (Hz) to enable pump turn-on.</td>
</tr>
<tr>
<td></td>
<td>PUMPDELAY=x</td>
<td>Profiling mode only. x= time (seconds) to wait after minimum conductivity frequency is reached before turning pump on. Default 60 seconds.</td>
</tr>
<tr>
<td></td>
<td>OUTPUTFORMAT=x</td>
<td>x=0: output raw frequencies and voltages in Hex (required if using SEASAVE). x=1: output converted data in Hex. x=2: output raw frequencies and voltages in decimal. x=3: output converted data in decimal. x=4: output pressure and scan number in Hex.</td>
</tr>
<tr>
<td></td>
<td>OUTPUTSAL=x</td>
<td>x=Y: Calculate and output salinity (psu). Only applies if OUTPUTFORMAT=3. x=N: Do not.</td>
</tr>
<tr>
<td></td>
<td>OUTPUTSV=x</td>
<td>x=Y: Calculate and output sound velocity (m/sec). Only applies if OUTPUTFORMAT=3. x=N: Do not.</td>
</tr>
</tbody>
</table>

**Note:**
See Command Descriptions in Section 4: Deploying and Operating SBE 19plus for detailed information and examples.
<table>
<thead>
<tr>
<th>CATEGORY (continued)</th>
<th>COMMAND</th>
<th>DESCRIPTION</th>
</tr>
</thead>
</table>
| Setup                | IGNORESWITCH=x | Profiling mode only.  
\(x=Y\): Ignore magnetic switch position for starting or stopping logging. Use STARTNOW, STARTLATER, and STOP to control logging.  
\(x=N\): Do not ignore magnetic switch position. |
|                      | AUTORUN=x | Profiling mode only.  
\(x=Y\): Automatically wake up and start logging when external power is applied; stop logging when external power is removed. Magnetic switch position has no effect on logging.  
\(x=N\): Do not automatically start logging when external power is applied. |
|                      | FLASHINIT | Map bad blocks and erase FLASH memory, which destroys all data in SBE 19plus. |
|                      | QS | Enter quiescent (sleep) state. Main power turned off, but data logging and memory retention unaffected. |
| Logging              | SAMPLEINTERVAL=x | Moored mode only.  
x= interval (seconds) between samples (10 - 14,400). |
|                      | NCYCLES=x | Moored mode only.  
x= number of measurements to take and average every SAMPLEINTERVAL seconds. Default = 1. |
|                      | NAVG=x | Profiling mode only.  
x= number of samples to average. SBE 19plus samples at 4 Hz and averages NAVG samples. Default =1. |
|                      | INITLOGGING | After all previous data has been uploaded, send this command before starting to log to make entire memory available for recording. If not sent, data stored after last sample. Equivalent to SAMPLENUMBER=0. |
|                      | SAMPLENUMBER=x | x= sample number for first sample when logging begins. After all previous data has been uploaded, set to 0 before starting to log to make entire memory available for recording. If not reset to 0, data stored after last sample. Equivalent to INITLOGGING. |
|                      | HEADERNUMBER=x | x= header and cast number for first cast when logging begins. |
|                      | STARTNOW | Start logging now. |
|                      | STARTMMDDYY | Delayed logging start: month, day, year.  
Must follow with STARTTHHMMSS=. |
|                      | STARTDDMMYY | Delayed logging start: day, month, year.  
Must follow with STARTTHHMMSS=. |
|                      | STARTTHHMMSS | Delayed logging start: hour, minute, second. |
|                      | STARTLATER | Start logging at delayed logging start date and time. |
|                      | STOP | Stop logging or stop waiting to start logging. Press Enter key to get \(S>\) prompt before entering command. Must stop logging before uploading data.  
If in Profiling mode and IGNORESWITCH=N, can also turn magnetic switch Off to stop logging. |
| Data Upload          | DD\(b,e\) | Upload data from scan \(b\) to scan \(e\). |
|                      | DC\(n\) | Profiling mode only.  
Upload data from cast \(n\). |
|                      | DD\(b,e\) | Upload headers from header \(b\) to header \(e\). |
| Sampling             | SL | Output last sample from buffer and leave power on. |
|                      | SLT | Output last sample from buffer, then take new sample and store data in buffer. Leave power on. |
|                      | TS | Take sample, store data in buffer, output data, and leave power on. |
|                      | TSS | Take sample, store in buffer and FLASH memory, output data, and turn power off. |
|                      | TSSON | Take sample, store in buffer and FLASH memory, output data, and leave power on. |

**Note:** Use the Upload button on the Toolbar or Upload Data in the Data menu to upload data that will be processed by SBE Data Processing. Manually entering the data upload command does not produce data with the required header information for processing by SBE Data Processing.
<table>
<thead>
<tr>
<th>CATEGORY</th>
<th>COMMAND</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>Testing</td>
<td>TT</td>
<td>Measure temperature, output converted data.</td>
</tr>
<tr>
<td></td>
<td>TC</td>
<td>Measure conductivity, output converted data.</td>
</tr>
<tr>
<td></td>
<td>TP</td>
<td>Measure pressure, output converted data.</td>
</tr>
<tr>
<td></td>
<td>TV</td>
<td>Measure four external voltage channels, output converted data.</td>
</tr>
<tr>
<td></td>
<td>TTR</td>
<td>Measure temperature, output raw data.</td>
</tr>
<tr>
<td></td>
<td>TCR</td>
<td>Measure conductivity, output raw data.</td>
</tr>
<tr>
<td></td>
<td>TPR</td>
<td>Measure pressure, output raw data.</td>
</tr>
<tr>
<td></td>
<td>TVR</td>
<td>Measure four external voltage channels, output raw data.</td>
</tr>
<tr>
<td></td>
<td>PUMPON</td>
<td>Turn pump on for testing purposes.</td>
</tr>
<tr>
<td></td>
<td>PUMPOFF</td>
<td>Turn pump off for testing purposes.</td>
</tr>
<tr>
<td>Coefficients</td>
<td>DCal</td>
<td>Display calibration coefficients; all coefficients and dates listed below are included in display (as applicable). Use individual commands below to modify a particular coefficient or date.</td>
</tr>
<tr>
<td></td>
<td>TCALDATE=S</td>
<td>Temperature calibration date.</td>
</tr>
<tr>
<td></td>
<td>TAO=F</td>
<td>Temperature A0.</td>
</tr>
<tr>
<td></td>
<td>TA1=F</td>
<td>Temperature A1.</td>
</tr>
<tr>
<td></td>
<td>TA2=F</td>
<td>Temperature A2.</td>
</tr>
<tr>
<td></td>
<td>TA3=F</td>
<td>Temperature A3.</td>
</tr>
<tr>
<td></td>
<td>TOFFSET=F</td>
<td>Temperature offset correction.</td>
</tr>
<tr>
<td></td>
<td>CCALDATE=S</td>
<td>Conductivity calibration date.</td>
</tr>
<tr>
<td></td>
<td>CG=F</td>
<td>Conductivity G.</td>
</tr>
<tr>
<td></td>
<td>CH=F</td>
<td>Conductivity H.</td>
</tr>
<tr>
<td></td>
<td>CI=F</td>
<td>Conductivity I.</td>
</tr>
<tr>
<td></td>
<td>CJ=F</td>
<td>Conductivity J.</td>
</tr>
<tr>
<td></td>
<td>CPCOR=F</td>
<td>Conductivity pcor.</td>
</tr>
<tr>
<td></td>
<td>CTCOR=F</td>
<td>Conductivity tcor.</td>
</tr>
<tr>
<td></td>
<td>CSLOPE=F</td>
<td>Conductivity slope correction.</td>
</tr>
<tr>
<td></td>
<td>CF0=F</td>
<td>Conductivity 0 value (Compatible State only).</td>
</tr>
<tr>
<td></td>
<td>PCALDATE=S</td>
<td>Pressure calibration date.</td>
</tr>
<tr>
<td></td>
<td>PRange=F</td>
<td>Pressure sensor full scale range (psi).</td>
</tr>
<tr>
<td></td>
<td>POFFSET=F</td>
<td>Pressure offset correction.</td>
</tr>
<tr>
<td></td>
<td>PA0=F</td>
<td>Strain-gauge pressure A0.</td>
</tr>
<tr>
<td></td>
<td>PA1=F</td>
<td>Strain-gauge pressure A1.</td>
</tr>
<tr>
<td></td>
<td>PA2=F</td>
<td>Strain-gauge pressure A2.</td>
</tr>
<tr>
<td></td>
<td>PTEMPA0=F</td>
<td>Strain-gauge pressure temperature A0.</td>
</tr>
<tr>
<td></td>
<td>PTEMPA1=F</td>
<td>Strain-gauge pressure temperature A1.</td>
</tr>
<tr>
<td></td>
<td>PTEMPA2=F</td>
<td>Strain-gauge pressure temperature A2.</td>
</tr>
<tr>
<td></td>
<td>PTC0=F</td>
<td>Strain-gauge pressure temperature compensation ptca0.</td>
</tr>
<tr>
<td></td>
<td>PTC1=F</td>
<td>Strain-gauge pressure temperature compensation ptca1.</td>
</tr>
<tr>
<td></td>
<td>PTC2=F</td>
<td>Strain-gauge pressure temperature compensation ptca2.</td>
</tr>
<tr>
<td></td>
<td>PTCB0=F</td>
<td>Strain-gauge pressure temperature compensation ptcb0.</td>
</tr>
<tr>
<td></td>
<td>PTCB1=F</td>
<td>Strain-gauge pressure temperature compensation ptcb1.</td>
</tr>
<tr>
<td></td>
<td>PTCB2=F</td>
<td>Strain-gauge pressure temperature compensation ptcb2.</td>
</tr>
</tbody>
</table>
Appendix IV: Compatible State

Sea-Bird can provide a custom EEPROM for the SBE 19plus to accommodate customers with older SBE 19s who need to replace the electronics but want to maintain the command set and output format of the original instrument. Instruments with this custom EEPROM operate in Compatible State, and can then be set to operate in Profiling or Moored mode.

Compatible State Commands

- Commands marked with * (* is not part of the command) alter the SBE 19plus’ memory and require verification before executing, to prevent accidental modifications.

After the command entry, the SBE 19plus responds:

‘message’ Y/N

Type Y and press the Enter key.

The SBE 19plus then responds:

Are you sure ^Y/N

Hold down the Ctrl key and type Y (any other response aborts command).

- Braces [ ] indicate optional command parameters. Items enclosed in braces need not be entered.

NRC

x=Y: Set conductivity channel to narrow range (fresh water, 0 - 0.6 S/m). If set to narrow range, DS command indicates Narrow Range Conductivity.

x=N: Set conductivity channel to standard range (salt water, 0 - 6.5 S/m).

IL * Initialize logging - after all previous data has been uploaded from SBE 19plus, initialize logging before starting to log again to make entire memory available for recording. This command resets sample number, header number, and cast number all to 0. If IL is not sent, data will be stored after last recorded sample. Do not send this command until all existing data has been uploaded.

GL * Start logging now, overwriting existing data. First scan is set to 0, so any previously recorded data will be overwritten, regardless of whether memory has been initialized or not.

RL * Resume logging now; do not overwrite existing data.

Note: Profiling mode - The CPU must be active (not in quiescent state) and the magnetic switch must be turned on before using the GL or RL command.

Notes:
The following Compatible State commands have equivalent commands in the SBE 19plus command set:
- IL = INITLOGGING
- GL = INITLOGGING followed by STARTNOW
- RL = STARTNOW
- QL = STOP
Appendix IV: Compatible State

QL  *  Moored mode - Quit logging. Press Enter key to get S> prompt before entering this command.

DD[Bb,e]  Upload raw data from scan b to scan e, at baud rate B. If B is omitted, baud rate that you are currently communicating with is used. If b and e are omitted, all data is uploaded. First sample is number 0.

Example: Upload samples 0 through 199 at 38400 baud to a file: (Click Capture on Toolbar and enter desired filename in dialog box.)
S>DD50,199

Notes:
- To save data to a file, click the Capture button on the Toolbar before entering the DD, DC, or DH command.
- In all upload commands, B is upload baud rate (1 = 600 baud, 2 = 1200 baud, 3 = 9600 baud, 4 = 19200 baud, 5 = 38400 baud).
- See Data Output Formats after these Command Descriptions.
- Use the Upload button on the Toolbar or Upload Data in the Data menu to upload data that will be processed by SEASOFT. Manually entering the data upload command does not produce data in the correct format for processing by SEASOFT.

DC[Bn]  Applicable to Profiling mode only - Upload raw data from cast n, at baud rate B. If B is omitted, baud rate that you are currently communicating with is used. If n is omitted, data from cast 0 is uploaded. First cast number is 0.

Example: Upload all data in second cast (cast 1) at 38400 baud to a file: (Click Capture on Toolbar and enter desired filename in dialog box.)
S>DC51

Notes:
- To quit logging in Profiling mode, slide the magnetic switch off or press Ctrl Z or Home key.
- You must quit logging before uploading data.

DH[b,e]  Upload headers from b to e. Baud rate is baud rate that you are communicating with currently. If b and e are omitted, all headers are uploaded. First header is 0. The header includes:
- cast number
- month, day, hour, minute, and second when cast was started
- first and last sample in cast
- sample rate (Profiling mode) or interval (Moored mode)
- reason logging was halted (batfail = battery voltage too low; switch off = switch turned off; recv cmd = received QL command or Home or Ctrl Z character; timeout = error condition; unknown = error condition; ?????? = error condition)
Compatible State Output Format

In Compatible State, data is always output in Hexadecimal form in the order listed below, with no spaces or commas between parameters. Shown with each parameter are the number of digits, and how to calculate the parameter from the data (use the decimal equivalent of the hex data in the equations).

The parameters are defined as follows:
- **tttt** = 2 bytes of temperature frequency
- **cccc** = 2 bytes of conductivity frequency
- **pppp** = 2 bytes of pressure data for Paine strain-gauge pressure sensor
- **pppppp** = 3 bytes of pressure data for Quartz pressure sensor
- **dddd** = 2 bytes of pressure temperature data for Quartz pressure sensor
- **uuu**, **vvv**, **xxx**, and **yyy** = 12 bits each, representing first, second, third, and fourth stored voltage respectively

Shown below are the data formats:

**Profiling Mode**

- No external voltages sampled:
  - With Paine pressure sensor - ttttccccpppp
  - With Quartz pressure sensor - ttttccccpppppppddd
- Two external voltages sampled:
  - With Paine pressure sensor - ttttccccuuuvvvpppp
  - With Quartz pressure sensor - ttttccccppppppuuuvvvddd
- Four external voltages sampled:
  - With Paine pressure sensor - ttttccccuuuvvvxxxyyypppp
  - With Quartz pressure sensor - ttttccccppppppuuuvvvxxxyyyddd

The following equations define the calculation of the parameters from the data (use the decimal equivalent of the hex data in the equations):

- Raw temperature frequency = \( \frac{tttt}{17} + 1950 \)
- Raw standard conductivity frequency = \( \text{square root } [cccc \times 2900 + 6,250,000] \)
- Raw narrow range conductivity frequency (older models) = \( \text{square root } [cccc \times 303 + 6,250,000] \)
- Voltage = voltage number (such as **uuu**) / 819
- Paine pressure = decimal equivalent of bits 0 - 13 of **pppp**. Bit 14 is sign bit: + if bit 14 = 0; - if bit 14 = 1.
- Quartz pressure = **pppppp** / 256
- Quartz pressure temperature = \( \left\{ \left[ \frac{dddd}{819} + 9.7917 \right] \times 23.6967 \right\} - 273.15 \)

**Example:** SBE 19plus in Profiling mode with Quartz pressure sensor and two external voltages sampled,
equivalent scan = 69CC43228D1B8003005908AA

- **tttt** = 69CC (27084 decimal);
  - temperature frequency = \( \frac{27084}{17} + 1950 = 3543.176\text{Hz} \)
- **cccc** = 4322 (17186 decimal);
  - conductivity frequency = \( \text{square root } [17186 \times 2900 + 6250000] = 7489.286\text{Hz} \)
- **pppppp** = 8D1B80 (9247616 decimal);
  - Quartz pressure = 9247616 / 256 = 36123.5
- **uuu** = 030 (48 decimal);
  - voltage = 48 / 819 = 0.059 volts
- **vvv** = 059 (89 decimal);
  - voltage = 89 / 819 = 0.109 volts
- **dddd** = 08AA (2218 decimal);
  - Quartz pressure temperature = \( \left\{ \left[ \frac{2218}{819} + 9.7917 \right] \times 23.6967 \right\} - 273.15 = 23.0 \)
Appendix IV: Compatible State

Reference Data for Profiling Mode

If profiling in Compatible State, the SBE 19plus contains reference scans that allow for the calculation of corrected frequencies for temperature and conductivity. The reference data is in scans 5 and 6, and then in two scans after every additional 120 scans. For each set of reference scans, one scan contains a high frequency reference and the other scan contains a low frequency reference.

The data format for the reference scans is:

- **With strain-gauge pressure sensor** - xxrrrrruuuuuuuvvvxxxyyypppp
- **With Quartz pressure sensor** - xxrrrrrrrrppppppuuuuuvvvvxxxxyyyyyyddddd

where

- Most significant bit of pressure data (pppp for strain-gauge or pppppp for Quartz) indicates whether the scan is a reference scan.
- If the most significant bit is 1, the scan contains reference resistor frequency information.
- rrrrr = reference data
- xx = indicator of type of reference data and conductivity range:
  - xx = 05 for scans containing high frequency reference data, with Standard conductivity range
  - xx = 08 for scans containing high frequency reference data, with Narrow conductivity range
  - xx = FF for scans containing low frequency reference data
- u, v, x, y, p, and d are as defined above. Note that if there are no external voltages (or only two), the corresponding terms will be omitted.

The following equations define the calculation of the corrected frequencies from the reference data (use the decimal equivalent of the hex data in the equations):

\[
f_{cor} = \sqrt{\frac{\left(\left(f_{raw} \times f_{raw}\right) - b\right)}{a} - PC}
\]

where

- \(f_{cor}\) = corrected frequency
- \(f_{raw}\) = raw frequency
- \(a = \frac{f_{hisq} - f_{flowsq}}{X_3}\)
- \(b = f_{flowsq} - \left(\frac{a}{X_2}\right)\)
- \(f_{hisq} = refhi \times refhi\) (where \(refhi\) = high frequency reference data)
- \(f_{flowsq} = reflow \times reflow\) (where \(reflow\) = low frequency reference data)
- \(KK = 2.4018669 \times 10^{-11}\)
- \(X_1 = 9.6036247 \times 10^{-9}\)
- \(X_2 = 1.1949587 \times 10^{-7}\)
- \(X_3 = (X_2 - X_1) \times (X_2 \times X_1)\)
- \(PC = 1 / (1 \times 10^6 \times KK)\)
Appendix IV: Compatible State

Moored Mode

Moored mode temperature and conductivity data are stored as corrected frequencies. The reference information is not stored with the data. The equations for calculating temperature and standard range conductivity are different than in Profiling Mode; data format and other equations are unchanged from those for Profiling Mode.

The following equations define the calculation of temperature frequency and standard range conductivity frequency from the data (use the decimal equivalent of the hex data in the equations):

Temperature frequency = \( \left( \frac{\text{tttt}}{19} \right) + 2100 \)

Standard conductivity frequency = square root \( [\text{cccc} \times 2100 + 6250000] \)
Appendix V: Replacement Parts

<table>
<thead>
<tr>
<th>Part Number</th>
<th>Part</th>
<th>Application Description</th>
<th>Quantity in 19plus</th>
</tr>
</thead>
<tbody>
<tr>
<td>30816</td>
<td>Parker 2-234E603-70</td>
<td>Battery end cap to housing piston seal (1), sensor end cap to housing seals (2)</td>
<td>3</td>
</tr>
<tr>
<td>30090</td>
<td>Parker 2-153N674-70</td>
<td>Battery end cap to housing face seal</td>
<td>1</td>
</tr>
<tr>
<td>30507</td>
<td>Parker 2-206N674-70</td>
<td>At each end of conductivity cell</td>
<td>2</td>
</tr>
<tr>
<td>31090</td>
<td>Screw, 10-32 x 5/8 flat Phillips-head, titanium</td>
<td>Secures conductivity cell guard to housing</td>
<td>2</td>
</tr>
<tr>
<td>31089</td>
<td>Screw, 10-32 x 1/2 flat Phillips-head, titanium</td>
<td>Secures sensor end cap to housing (side opposite conductivity cell guard)</td>
<td>1</td>
</tr>
<tr>
<td>30145</td>
<td>Screw, 6-32 x 1/2 Phillips-head, stainless steel</td>
<td>Secures battery cover plate to battery posts</td>
<td>3</td>
</tr>
<tr>
<td>30242</td>
<td>Washer, #6 flat, stainless steel</td>
<td>For screw 30145 (secure battery cover plate to battery posts)</td>
<td>3</td>
</tr>
<tr>
<td>80076.1</td>
<td>Battery cover plate</td>
<td>Retains alkaline batteries</td>
<td>1</td>
</tr>
<tr>
<td>22018</td>
<td>Batteries, alkaline D-cell</td>
<td>Power SBE 19plus</td>
<td>9</td>
</tr>
<tr>
<td>80256</td>
<td>Ni-Cad battery pack</td>
<td>Rechargeable 9-battery pack</td>
<td>1</td>
</tr>
<tr>
<td>17133*</td>
<td>2-pin to 2-pin cable, 1.1 m (3.7 ft)</td>
<td>From SBE 19plus to pump</td>
<td>1</td>
</tr>
<tr>
<td>80087*</td>
<td>4-pin to 25-pin I/O cable, 2.4 m (8 ft)</td>
<td>From SBE 19plus to computer</td>
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<td>17130</td>
<td>25-pin to 9-pin adapter</td>
<td>Connects I/O cable to 9-pin COM port on computer</td>
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<td>17043*</td>
<td>Locking sleeve</td>
<td>Locks I/O cable or dummy plug in place</td>
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<td>17044*</td>
<td>2-pin dummy plug</td>
<td>For when pump not used</td>
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<td>17046*</td>
<td>4-pin dummy plug</td>
<td>For when I/O cable not used</td>
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<td>17047*</td>
<td>6-pin dummy plug</td>
<td>For when auxiliary differential input sensors not used</td>
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<td>50091</td>
<td>Triton X-100</td>
<td>Conductivity cell cleaning solution</td>
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<td>60021</td>
<td>Spare battery end cap parts</td>
<td>Assorted o-rings and hardware</td>
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<td>50273</td>
<td>Spare hardware kit</td>
<td>Assorted hardware</td>
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<td>50274</td>
<td>Spare o-ring kit</td>
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<td>50275</td>
<td>Spare magnetic switch assembly</td>
<td>For starting/stopping logging in Profiling mode</td>
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<tr>
<td>50276*</td>
<td>Seaspares kit</td>
<td>Includes 50273, 50274, and 50275 as well as bulkhead connectors, dummy plugs, and other parts</td>
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<td>50288</td>
<td>Moored Mode Conversion Kit</td>
<td>Anti-foulant device fittings for moored applications (order AF24173 Anti-Foulant Devices separately)</td>
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<tr>
<td>24173</td>
<td>AF24173 Anti-Foulant Device</td>
<td>bis(tributyltin) oxide device inserted into anti-foulant device cup, for moored applications</td>
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* For standard bulkhead connectors
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