Cruise Report No. 15

RRS Discovery Cruise 312
11 – 31 OCT 2006

The extended Ellett Line 2006

Principal Scientist
J T Allen

Editor
M C Stinchcombe

2007
UK oceanographers have been making repeated measurements on a short section across the Rockall Trough, since 1975. The section consists of a series of stations from the Scottish continental shelf to Rockall. The time series was established by David Ellett and was thus called the "Ellett Line". The Ellett line is one of a relatively small number of high quality physical time series in the North Atlantic Ocean and is important for monitoring oceanic climate variability.

Since 1996 NOCS and SAMS have been occupying an extended version of the Ellett Line that runs all the way to Iceland. The Extended Ellett line is important oceanographically because it completes the measurements of the warm saline water flowing into the Nordic Seas from the eastern North Atlantic. It also monitors around half of the returning deep and cold current, the overflow water (the rest returns to the Atlantic via the Denmark Strait to the west of Iceland).

There is little added cost, either in time or financially, in making a number of biogeochemical measurements using water samples from the hydrographers’ CTD stations. Thus, recently, the scientific interests in the Extended Ellett line have become more multidisciplinary; the 2006 occupation was no exception. Samples were filtered for POC, HPLC studies and trace aluminium concentration determination, in addition some extra time was found for a number of zooplankton net hauls.

**KEYWORDS**
acronym, ATLNENROC, ATLNN, cruise 312 2006, CTD observations, Discovery, Ellett Line, Iceland Basin, Rockall Trough, sediment traps, Wyville Thomson Ridge
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SCIENTIFIC PERSONNEL

ALLEN, John (Principal Scientist) NOC-OBE
ARULA, Timo Estonian Marine Institute
BARHAM, Mark NOC-OOC (MSc)
EDWARDS, Terry NOC-NMFD
GRIFFITHS, Colin SAMS
INALL, Mark SAMS
EVANS, Katie NOC-OBE (MRes)
KNIGHT, Gareth NOC-NMFD
MARKS, Margaret Artel Artists
PAINTER, Stuart NOC-OBE
PÖLLUPÜÜ, Maria Estonian Marine Institute
PROVOST, Paul SAMS
RAE, Ian ERI
READ, Jane NOC-OBE
SANDERS, Richard NOC-OBE
SHERRING, Alan NOC-NMFD
SHERWIN, Toby SAMS
VENABLES, Emily SAMS (PhD)
WALLHEAD, Phil NOC-OBE (PhD)
ZHOU, Yingzhao SAMS

NOC - National Oceanography Centre
OBE – Ocean Biogeochemistry and Ecosystems
OOC – Ocean Observing and Climate
NMFD – NERC Marine Facilities Division
SAMS – Scottish Association for Marine Science
ERI – Environmental Research Institute, Thurso
SHIP'S PERSONNEL

SARJEANT, Peter Master
GAULD, Phil Chief Officer
CARLO, Georgina 2nd Officer
RUMBOLD, Katie 3rd Officer
BENDELL, David Deck Cadet
KISHORKUMAR, Jet Chief Engineer
BELL, Steve 2nd Engineer
SLATER, Gary 3rd Engineer
HARNETT, John 3rd Engineer
JAKOBAUFDERSTRÖHT, Dennis Electrical Engineer
HARTSHORNE, David PCO
THOMSON, Iain CPO(D)
SMITH, Steve CPO(S)
DAY, Steve PO(D)
MOORE, Carl Motorman I.A. (Leg1)
DALE, John S.1.A.
BUFFERY, Dave S.1.A.
CRABB, Gary S.1.A.
DOWNIE, Eric S.1.A.
LYNCH, Peter Head Chef
CAINES, Darren Chef
PATERSOH, Jacqui STWD
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ABSTRACT

UK oceanographers have been making repeated measurements on a short section across the Rockall Trough, since 1975. The section consists of a series of stations from the Scottish continental shelf to Rockall. The time series was established by David Ellett and was thus called the "Ellett Line". The Ellett line is one of a relatively small number of high quality physical time series in the North Atlantic Ocean and is important for monitoring oceanic climate variability.

Since 1996 NOCS and SAMS have been occupying an extended version of the Ellett Line that runs all the way to Iceland. The Extended Ellett line is important oceanographically because it completes the measurements of the warm saline water flowing into the Nordic Seas from the eastern North Atlantic. It also monitors around half of the returning deep and cold current, the overflow water (the rest returns to the Atlantic via the Denmark Strait to the west of Iceland).

There is little added cost, either in time or financially, in making a number of biogeochemical measurements using water samples from the hydrographers’ CTD stations. Thus, recently, the scientific interests in the Extended Ellett line have become more multidisciplinary; the 2006 occupation was no exception. Samples were filtered for POC, HPLC studies and trace aluminium concentration determination, in addition some extra time was found for a number of zooplankton net hauls.

1. INTRODUCTION

The Ellett Line has revealed interannual to decadal scale variability in properties, including a significant rise in temperature since 1995 (Ellett et al. 1986, Holliday et al. 2000, Holliday, 2003). This warming likely results from a greater inflow of warm salty waters rather than changes in atmospheric fluxes. The extension to Iceland increases the value of the original section by monitoring the N. E. Atlantic current extension, the recirculation of the eastern subpolar gyre and the Iceland Scotland overflow. The Extended Ellett Line has been occupied almost annually since 1988 and has thus revealed upper ocean mode water
variability of order 1-1.5 °C and 0.15 salinity over 5-10 year periods (Holliday, 2003). Data from recent extended Ellett Line occupations show that the upper layers (upper ~ 800 m) of the Rockall Trough are the warmest and saltiest of the time series so far. The Rockall Trough has a strong seasonal cycle in the upper layers (broadly speaking cold and salty in the winter, warm and fresher in the summer) and this cycle has to be eliminated on a cruise-by-cruise basis in order to highlight the changes over longer timescales.

In the deeper waters the Labrador Sea Water (LSW) in 2005 showed an increase in salinity over the previous year (little change in temperature). The source region of LSW, the Labrador Basin, showed dramatic freshening and cooling in the 1990s when unusually deep winter convection took place (0.05 psu and 0.5 °C at 1800m), followed by a similar increase from 1998 onwards. The changes seen in the Rockall Trough may reflect those large changes in the Labrador Sea, but alternatively, may simply reflect local differences in mixing between LSW and other more saline water masses.

An extensive suite of bio-geochemical observations can be made on hydrographic cruises at the cost of minimal extra on-station time. We observed intense silicification, the production of a mineral phase which is likely linked to export, in this region in spring 2001 (Brown et al., 2003) and calcifying plankton also bloom extensively (Holligan et al. 1991, 1993) in the region. Waniek et al. (2005) showed opposing gradients in opal fluxes in the N. E. Atlantic; the implications of this for shallow particle export are unclear. On this occupation of the extended Ellett Line additional water samples were taken for a total of 12 upper ocean (~ 350 m) profiles of particulate organic carbon (POC) content, chlorophyll concentration and HPLC pigment determination. Deep ocean water samples from 19 CTD stations were filtered for trace aluminium concentration particularly focussed where deep-water outflows were expected.

In addition to the extended Ellett Line, extra time was allocated on this cruise to three other tasks required by different complementary science programmes. Firstly, four sediment trap and current meter moorings were deployed some 70 km apart in a triangular array centred near 59 °N, 19 °W. These are intended to provide a particulate export dataset, pertaining to, and to be turned around during the first cruise of Theme 2 of the OCEANS2025 NERC core strategic programme. Secondly, a limited number of vertical zooplankton net hauls were made on selected stations to support a historical record of zooplankton observations.
maintained by scientists at the SAMS. Thirdly, a study of turbulence over a tidal cycle had been planned with the use of a new free-fall turbulence probe acquired by the SAMS.

RRS Discovery cruise 312

Figure 1: Schematic cruise track for Ellett.

2. NARRATIVE

PSO’s Diary

11th Oct (Day 284)

*Discovery* slipped from Reykjavik harbour at 09:20; towed out stern first by tug due to increasingly poor weather and increasing wind speeds. At 10:30 a meeting was held in the plot for all senior scientists, at which the responsibilities for all the main jobs were shared out
and a number of decisions were made regarding the processing routes that would be used. With a forecast of continued force 6/7 winds all day, the safety muster and call to boat stations was held at 13:00 whilst still in the lee of the Reykjanes Peninsular. A general science meeting for all the ships company both available and ‘feeling up to it’ was held at 16:15. Weather forecasts indicated marginal conditions for the next couple of days – but apparently there is an Icelandic saying along the lines of ‘…leave in a storm for a fine weather trip...’ so we held tightly onto this small comfort!

12th Oct (Day 285)

Overnight *Discovery* had held a course towards station IB21S rather than IB23S as this provided a much more comfortable heading. By first light the wind had dropped and the sea state was clearly lighter. We were on station IB21S at 08:30 and the PES (Precision Echo Sounder) fish was deployed at a depth of 8 m. The initial deployment of the CTD was aborted when the primary temperature sensor suffered severe data spiking. A wet connector plug was discovered and the connector lead was replaced. At the same time the primary conductivity and temperature sensors were moved onto the vane. The CTD was redeployed for IB21S (stn. 16126) at 10:45. Sadly, on reaching the bottom of the cast, it was found that we had no bottle firing control and the CTD was recovered without any water bottle samples. The CTD was inboard at 11:44 and the ship set course NW for station IB22S.

Whilst steaming further cable problems were diagnosed and the cable between the CTD and the bottle firing pylon was replaced. We arrived at IB22S at 13:12 but by this time the wind was gusting strongly at 40 knots plus and so science was stopped and the vessel was hove to. With conditions marginally workable later in the day, IB22S (stn. 16127) began at 18:40 and was completed successfully by 19:48. Conditions were not such as to allow sampling on deck whilst steaming and therefore the steam to IB23S, our most northerly station and closest to the Vestmannaeyjar, did not begin until 20:30.

During IB22S the oxygen data became very spiky and once again this was traced to a wet connector. The lead was replaced as we came onto station IB23S and the CTD was in the water (stn. 16128) by 21:47. IB23S was completed at 22:15 and we began the 30 n. mile steam back south to IB20S, slowly at first to allow for safe sampling of the CTD.

13th Oct (Day 286)

A lovely start to the day, still blustery, but clear, sunny, and a sea state of 4/5. Station IB20S (stn. 16129) had begun at 02:39 and was completed by 04:33. Station IB19S (stn. 16130) had begun at 06:43 and was completed after breakfast at 08:18. We were not losing any time overall on station, but a heavy swell and difficult positioning on station were accounting for significant loses between stations.
Station IB18S (stn. 16131), was completed, on board and secure by 13:09. Station IB17 (stn. 16132) began at ~16:15 but nearly 45 minutes were lost trying to position the ship. It was a reminder of how difficult even moderate seas can be. Head to wind the ship rolled terribly because wind and swell were at right angles, however head to swell left the ship drifting at speeds around 1 knot. Nevertheless the station was successfully completed by 18:02.

Station IB16 (stn. 16133) began at 21:16, by now however, the weather had seriously deteriorated and a severe showery squall of high winds nearly stopped the show. Acoustic releases were tested here, one successfully, one not so successfully – c’est la vie, we will have to try for a better day tomorrow. IB16 was completed at 00:08 on the 14th and Discovery headed south for IB15.

14th Oct (Day 287)

Whilst writing my daily plan of action at ~ 00:30 a rapidly intensifying roaring of the wind past the windows of the PSO’s office made me realise that further writing would be fairly futile; plans would change soon. By 01:15 Discovery was hove to in wind speeds of 55-60 knots. This small depression had been forecast, but it was rather more severe in reality.

During the early morning, Discovery continued to edge further south towards IB15 as conditions began to moderate. By 07:45 we had reached IB15 and we waited for conditions to improve sufficiently to work. The CTD was deployed (16134) at 09:25 and mooring releases were tested successfully. Station IB15 was completed by ~12:00.

IB14 (stn. 16135) was completed successfully by 16:57. The final two acoustic releases were also successfully tested here.

Just after lunch a new weather forecast indicated force 9 northeast winds by late afternoon Monday (16th). This forced a change of plan in order to endeavour to start and complete the sediment trap mooring array (four moorings in an triangular pattern of side ~ 120 km, but with a central mooring providing a 70 km separation scale) by noon on Monday. As a result, IB12 and IB11 would be removed from the station list at least for now; however, full depth CTDs at the mooring locations would provide closure of the 60 °N, 20 °W corner of the extended Ellett line even if the line looked a little awkward geographically.

IB13 (stn. 16136) was successfully completed by 23:29 and Discovery set off in a south-south-west direction towards the first sediment trap mooring location STNW (sediment trap NW).
A full depth CTD was completed at mooring station STNW (16137#1) by 06:58. The hash number referring to the platform being deployed, these would be as follows: #1 CTD, #2 vertical net hauls, #3 series of rapid turbulence profiler deployments, #4 mooring deployment, and #5 to be assigned to a SAMS experimental ‘modified’ argo float if deployed. At 08:02 the mooring anchor for the STNW sediment trap mooring (16137#4) was released (60° 00.063′ N, 020° 49.572′ W) and the descent of the acoustic release was monitored until the anchor had clearly reached the bottom. By 08:30, Discovery had set course for the central mooring location ~ 70 km away in a roughly south-southeast direction.

An upward looking 75 kHz SC-ADCP, unique to mooring STC (sediment trap central), was setup and started pinging at 11:59. A new weather forecast indicated that the force 9 gales originally forecast for Monday afternoon may well increase to force 10 but that the strongest winds may develop to the east by Tuesday/Wednesday. Therefore the order of the last two moorings would be changed to attempt to steam with the wind/sea where possible: we would then plan to remain west and attempt to complete the extended Ellett line eastwards following behind the path of the weather. The CTD station on station STC began at 12:30 (stn. 16138#1) and the mooring deployment was completed at ~17:10 (stn. 16138#4) at position 59° 29.913′ N, 019° 59.757′ W.
A long cloudbank indicated that the cold front at the head of the impending weather system was closing on our position possibly more rapidly than expected. As mooring station STNE (sediment trap NE) was very close to the Ellett line we decided that we would cancel the CTD deployment here and try to pick it up on our return to the line when behind the weather system. *Discovery* arrived on station STNE at ~ 20:45 and the sediment trap mooring had been fully deployed and landed by ~21:25 (16139#4) at position 59° 38.972’ N, 18° 46.838’ W. *Discovery* set course south south-west for the fourth, final and southern most sediment trap mooring deployment, STS (sediment trap south): winds were freshening, still south south-westerly but veering slowly and still expected strong and north-easterly by Monday afternoon.
16th Oct (Day 289)

By 05:10 *Discovery* was on station STS and, with a freshening wind that had veered northerly as forecast through the night, we decided to deploy the sediment trap mooring first and carry out the full depth CTD if conditions were still workable later. The mooring was fully deployed (16140#4 – at 58° 51.96’ N, 020° 24.17’ W) by 07:12 and *Discovery* repositioned 1 n. mile down wind to deploy the CTD. The CTD at STS was completed (16140#1) at 10:15 and *Discovery* set a northerly course for IB12 which had previously been skipped in our hurry to undertake the mooring deployments before the weather conditions deteriorated too far.

A continued increasing of sea state under constant wind speeds of 25-30 knots resulted in *Discovery* taking a more northerly course to IB12, overshooting, and then making a south southeasterly course with the swell into the IB12 station position. We were hove to on station IB12 and the CTD was deployed (16141) by 20:30. Station IB12 was completed by 23:00. Conditions were very marginal but a similar careful choice of steaming direction would hopefully allow us to get further along the Ellett line to at least IB11 whilst conditions remained workable.

17th Oct (Day 290)

Despite a heavy swell, the 4-8 watch began station IB11 (16142) at 04:52 and the CTD was back inboard and secured by 07:18. Sadly, the forecast force 9/10 winds hit us at 08:35 and 50 knot winds forced *Discovery* to heave to. From the forecasts this looks set in for a few days. As always these storm conditions are both spectacular and humbling when viewed from the bridge windows.

Just after lunch, new detailed forecasts confirmed a long duration for these conditions but they also indicated much closer isobar spacing and potentially more severe conditions for the end of the week. We would wait until the next forecast on Wednesday before making a final decision to run southwest in a small lull that we are expecting on Wednesday night.

18th Oct (Day 291)

The wind began to drop somewhat over night and during the morning, but 40 knot winds were still sufficient to maintain and even continue to build the swell. During our period hove to, we had slowly steamed NE against the swell; by 10:20 we were around 60° 11’ N, 17° 55’ W. With the latest forecasts still indicating force 9/10 winds from the NE for as far as they could forecast, i.e. 4/5 days, it was time to try and get round the weather rather than just sit it out. *Discovery* turned to run as south of SW as possible at 12:30, with the swell as far on her
port quarter as possible. The forecasts all showed that Rockall might be suffering somewhat lighter weather in 2-3 days time and that conditions might be workable if we could just get there. A course of ~210° T was comfortable for now.

19th Oct (Day 292)

Wind speed had dropped a little over night but during the morning it increased slowly to a steady 40 knots again by lunchtime. However, over night the wind direction had backed more northerly and a slightly more southerly course of 205° T had been held during the morning. At 12:30, *Discovery* was around 56° 29’ N, 22° 20’ W. At this point we decided to try turning round and heading NNE towards the Rockall Plateau. *Discovery* was able to hold a course of 065-070° T at 4-5 knots initially with moderate comfort. Later in the afternoon the sea had eased sufficiently to allow speeds of between 6 and 8 knots, but it would still be a long haul to Rockall. Still heading towards IB4 at midnight, but we continue to try for a more easterly course.

20th Oct (Day 293)

By late morning the sea had dropped significantly, and 25-30 knot winds opposed the swell. *Discovery* was now maintaining ~ 10 knots on a course of ~ 055° T with an ETA at station IB4 of ~ 19:00.

At 16:15 an emergency muster drill was followed by a quiz for all the scientists. We had at last now clearly made it over to the SE side of the front that had been causing us so much trouble, and although we had probably now lost stations IB10 through IB5, we had high hopes of sampling much of the Ellett line from Rockall east. Interestingly we were in a quasi-stationary low pressure region: its stationary appearance driven by the blocking highs over Greenland and northern Europe creating a kind of cul-de-sac in which this low pressure system had become corralled. A long cloudbank marked the front under which we would still have been suffering gale or even severe gale force winds.

Before reaching IB4 the wind speed began to rise sharply as we approached the front, itself spreading in a southerly direction, from the south side. *Discovery* hove to and this became station IB4a, an alternative position in the centre of the Hatton-Rockall Basin, approximately 10 n. miles WSW of the original IB4. The CTD at IB4a (16143) was in the water at 18:47 and the station was completed with the CTD secured by 20:15.

Sadly the transect to IB3 would be tortuous, a heavy swell still requiring that we travel a long way south before turning NNE into the sea to reach the station.
21st Oct (Day 294)

*Discovery* finally reached IB3 at 04:30. Significantly deteriorating weather, 30+ knot winds force seven seas and occasional packets of large swell waves, made this station a close call. But at 05:07 the CTD was deployed (16144). IB3 was completed with the CTD secured on deck by 06:00.

The lunchtime MetWorks forecasts were not good, our weather window had closed and the next significant window would be Tuesday, it is now Saturday! Small comfort was taken from their expression “…. amazed anyone can do any work in those conditions up there just now but I guess you guys are used to that by now.”.

We were on station IB2 at 14:54, once again in extremely marginal conditions with 25-40 knot winds and force 7 seas. The CTD (16145) was deployed at 15:17 and it was back on deck and secured by 16:05.

*Discovery* was hove to on IB1 at 23:30, whilst the marginal conditions were assessed.

22nd Oct (Day 295)

Once again IB1 would be in marginal conditions, force 7 seas and occasional gale force gusting winds. It is useful to note here that everyone is working very hard to get work done. In a generally fine weather cruise we would have made the simpler decision to heave to and wait more often. The CTD was deployed (16146) at 12:46, but not before a trip out on the winch slack wire compensator had required the CTD to be lashed down just above the deck frame. Station IB1 was completed at 01:11. The Rockall station, A, would not be carried out during darkness and therefore, with time pressing, station A would be dropped for now. We will try to make station B by first light and carry out the net hauls intended for station A at station B instead.

The CTD at station B (16147) began at 07:28 and was completed by 08:18. The vertical net hauls were cancelled due to the continued marginal seas. These vertical hoop nets have a relatively light compressor weight and in these conditions the net could easily be drawn under the ship during deployment or recovery.

The CTD at station C (16148) began at 11:48 and was completed and secured by 12:40.

The CTD at station D (16149) began at 14:50 and was completed and secured by 16:03.

The CTD at station D1 (16150) began at 17:43 and was completed and secured by 19:24.

The CTD at station E (16151) began at 21:12 and was completed and secured by 23:07.
Although the weather conditions had not deteriorated as forecast today, there had been little let up from the force 7/8 winds except for a brief period of 25 knot winds during the afternoon. Working along the Ellett line was still difficult and slow.

23rd Oct (Day 296)

*Discovery* was hove to at E1 by 00:45 and the CTD was in the water (16152) at 01:03. The CTD recovery was difficult as a result of increased sea-state and strong 35+ knot winds. After three attempts to land the CTD in the deck frame the CTD was finally secured at 02:46. With significant water now washing on deck from occasional swell waves, conditions had passed from marginal to unworkable, at least in darkness. *Discovery* set a course for station F where we would heave to until first light and then the conditions would be re-assessed.

*Discovery* was hove to on station F at 07:24. It was immediately clear that weather and sea-state had significantly deteriorated over night with strong winds and a mounting swell; we remained hove to. The forecasts at mid-day indicated that conditions should improve later, we wait eagerly.

24th Oct (Day 297)

After a day of unremitting 35+ knot winds until late evening, a somewhat calmer first light was most welcome. *Discovery* had relocated to station F by 08:30 and the CTD (16153#1) was deployed at 08:53. With the CTD recovered and secured by 10:47, the bongo net was deployed at 10:53 and three net hauls were made (16153#2) to complete the station at 11:25. There was considerable excitement at the first zooplankton samples collected, but before anyone could take a look the biologists had them in the formalin – call me a physicist, but a couple of minutes observation first please!!

Then bad news, our third officer had not been very well for a couple of days. What had appeared like signs of a good recovery yesterday had not been maintained today sadly. We steamed east to await a helicopter Med-Evac organised by Stornoway Coastguard. Our casualty was winched up off the aft deck at 13:45 into a hovering Sea-King helicopter. *Discovery* headed back to station G; in fact the Med-Evac had cost us little time as we had ended up just 6 n. miles NNE of G.
Figure 3: Stornoway Coastguard arrives

The CTD at station G (16154) began at 14:47 and was completed and secured by 16:37. *Discovery* still had to make a dog-leg course between stations due to the size of the swell coming from a northeasterly direction. Contrary to the forecast the wind speed had increased again during the afternoon, blowing 25-30 knots steadily by early evening.

The CTD at station H (16155#1) began at 19:15 and was completed and secured by 21:16. Bongo nets followed (16155#2) at 21:30 and the standard three net hauls were completed at 22:03.

25th Oct (Day 298)

The CTD at station I (16156 – western Anton Dohrn station) began at 00:06 and was completed and secured by 01:10.

*Discovery* was hove to on station J at 04:08. The CTD was delayed due to problems with the winch compensator, but was deployed (16157#1 – Anton Dohrn) by 04:35. The CTD was back on board and secured at 05:32 and vertical plankton net hauls (16157#2) began at 05:49. The station was completed after three net hauls at 06:23.
The CTD at station K (16158) began at 07:50 and was completed and secured by 08:45.

*Discovery* was hove to on station L at 10:18. The CTD was deployed (16159#1) at 10:31. The CTD was back on board and secured at 12:23 and vertical plankton net hauls (16159#2) began at 12:35. The station was completed after three net hauls at 13:01. A gale force warning from the routine meteorological service was not supported by the MetWorks forecasts – we await our fate.

The CTD at station M (16160#1) began at 15:40 and was completed and secured by 17:25. Vertical net hauls (16160#2) followed the CTD at 17:41 and the station was completed at 17:53.

Sea state and wind had dropped significantly during the day and a direct steaming course could now be made between stations. The CTD at station N (16161) began at 19:34 and was completed and secured by 21:35.

*Discovery* had now been joined by an entire flight of migrating redwings, presumably nearing the end of their journey south. Sadly I don’t think our presence was doing much for their survival, but they are most curious of us.

The CTD at station O (16162) began at 23:10 and was completed and secured by 00:45 on Thursday morning.

![Migrating redwings took an extraordinary interest in us.](image)

![Migrating redwings took an extraordinary interest in us.](image)
26th Oct (Day 299)

The CTD at station P (16163) was deployed at 02:45, recovered and secured by 04:07.

The CTD at station Q (16164#1) was deployed at 05:10, recovered and secured by 05:51. The plankton net was deployed at 06:03 (16164#2), only one net haul is now being carried out routinely and the station was finished at 06:18.

The CTD at station R (16165#1) was deployed at 07:30, recovered and secured by 07:51. The plankton net was deployed at 08:00 (16165#2) and the station was finished at 08:06.

The CTD at station S (16166) was deployed at 09:25, recovered and secured by 09:47.

The CTD at station 15G (16167) was deployed at 11:02, recovered and secured by 11:20.

The CTD at station T (16168) was deployed at 12:42, recovered and secured by 13:00.

The CTD at station 14G (16169) was deployed at 14:40, recovered and secured by 14:58.

*Discovery* then proceeded to the Barra Head turbulence profiler transect. This was designed to be a 13 hour repeated series of transits along 56° 40’ N backwards and forwards from 007° 34.2’ W to 007° 37.2’ W. The transits began (16170) at 19:18. Once the buoyancy of the turbulence profiler had been assessed as correct the profiling began in earnest. In each descent, the profiler was sent to the bottom with sufficient slack wire in the water to ensure the profiler was free falling. The profiler was then hauled back in on its own winch. Each profile cycle took around 10 minutes. Sadly, at 20:25, after only a few profiles the turbulence profiler became held fast on the bottom in 170 m of water. Despite stopping the ship and then trying to pay out slack wire and backtrack, the cable parted near the seabed at ~20:30.

A CTD (16171) was deployed at 56° 40.2’ N, 007° 34.6’ W to set the limited turbulence data that was gathered in a hydrographic context. The CTD was deployed at 21:26 and recovered by 22:00. Now *Discovery* set a course for 9G to complete more of the Ellett line westwards to where we left off earlier in the day. We still plan to head towards the Wyville Thomson ridge tomorrow morning to turn around a SAMS mooring there.

The CTD at station 9G (16172#1) was deployed at 23:07, recovered and secured by 23:30. The plankton net was deployed at 23:45 (16172#2) and the station was finished at 00:00 Friday.

27th Oct (Day 300)

The CTD at station 10G (16173) was deployed at 01:05, recovered and secured by 01:34.
The CTD at station 11G (16174#1) was deployed at 02:30, recovered and secured by 02:42. The plankton net was deployed at 02:53 (16174#2) and the station was finished at 03:00.

The CTD at station 12G (16175) was deployed at 03:53, recovered and secured by 04:04.

The CTD at station 13G (16176#1) was deployed at 05:03, recovered and secured by 05:27. The plankton net was deployed at 05:39 (16176#2) and the station was finished at 06:04.

*Discovery* then set course northwards for the Wyville Thomson ridge. We made a series of small course changes just before lunch to make a close pass on the St. Kilda islands at around 11:45. Unfortunately, visibility was poor, winds were fresh (~ 30 knots) and it was drizzling heavily, not exactly fine sightseeing conditions but we could at least make out the outlines of some of the big cliffs through the gloom.

**28th Oct (Day 301)**

A new ‘W’ CTD section across the ‘Ellett’ gully had been planned during the steam north. This ~ 9 mile long section of 11 CTDs, from north to south, would look at the volume of Færøe Shetland overflow water crossing the Wyville Thomson Ridge to the south via a small east-west gully on the southern slope of the ridge. The section passed through the SAMS upward looking ADCP mooring and was similar to a section carried out last year on RRS *Charles Darwin* cruise 176.

The CTD at station W1 (16177) was deployed at 04:22, recovered and secured by 04:55.

The CTD at station W2 (16178) was deployed at 05:54, recovered and secured by 06:28.

The CTD at station W3 (16179) was deployed at 07:39, recovered and secured by 08:27.

The CTD at station W5 (16180) was deployed at 09:31, recovered and secured by 10:17.

*Discovery* was hove to at 10:47, 60° 15.7’ N, 008° 54.5’ W, to release the SAMS bottom mounted SC-ADCP mooring (16181). This was released, hooked and safely recovered by 11:25. Over the next four hours the data were downloaded and the instrument was prepared for re-deployment.

The CTD at station W4 (16182) was deployed at 12:33, recovered and secured by 13:18.

The CTD at station W6 (16183) was deployed at 14:02. The mooring release had been serviced and attached to the CTD frame, the release mechanism was tested and confirmed as released at 14:41 when the CTD was at ~1150 m. The CTD was recovered and secured by 15:27.
A position of 60° 15’ N, 008° 55’ W, was then aimed for to re-deploy the SAMS ADCP mooring, i.e. more or less a direct replacement. The mooring was deployed (16184) at 60° 15.003’ N, 008° 54.990’ W by 16:05 and acoustic confirmation that it had reached the bottom and was staying there was made by 16:20.

The CTD at station W8 (16185) was deployed at 16:51, recovered and secured by 18:15.

The CTD at station W9 (16186) was deployed at 19:27, recovered and secured by 20:42.

Stations W7 (60° 14.76’ N, 008° 55.02’ W), W10 (60° 13.02’ N, 008° 55.02’ W) and W11 (60° 11.40’ N, 008° 54.84’ W) were dropped in order to allow time to head south and complete the shelf section of the Ellett line. The signal of the overflow water was not considered strong enough at this point in time to justify continuing further science here as an alternative to completing the Ellett line, and 30-35 knot northwesterly winds had kicked in as forecast this evening. The latest in a long line of depressions to hit us, at least we had just had the nicest and calmest day of the cruise although a strong swell had made things difficult on station at times. *Discovery* set a southerly course for station 8G some ~240 n. miles away.

29th Oct (Day 302)

At 10:00 we held a de-brief meeting. In total, including time lost making sea-state determined courses between stations; over 6 of the 20 days had been lost to weather. Nevertheless 80-85 % of the scientific objectives had been achieved and this level of success in the face of adversity is a testament to the hard work and determination of all on board, particularly some exemplary winch driving and close co-operation between the deck officers and the winch drivers.

By 11:00 we were approaching the St. Kilda island group again. Under clearer skies we had a much nicer view of the islands this time. Village bay looked distinctly deserted as we bore away and left the islands behind us.

The CTD at station 8G (16187) was deployed at 20:54, recovered, secured and sampled by 21:45.

The CTD at station 7G (16188) was deployed at 22:29, recovered, secured and sampled by 23:00.

The weather had been deteriorating significantly all evening, 30-40 knot south southwesterly winds heralded the leading edge of yet another depression.
30th Oct (Day 303)

The CTD at station 6G (16189) was deployed at 00:22, recovered, secured and sampled by 00:33.

The CTD at station 5G (16190) was deployed at 01:37, recovered, secured and sampled by 01:48.

The CTD at station 4G (16191) was deployed at 02:45, recovered, secured and sampled by 03:03.

The CTD at station 3G (16192) was deployed at 03:54, recovered and secured by 04:12.

The CTD at station 2G (16193) was deployed at 05:02, recovered and secured by 05:17.

The CTD at station 1G (16194) was deployed at 06:35, recovered, secured and sampled by 07:00.

*Discovery* set course for the Sound of Mull. With continued gales, *Discovery* entered the Sound of Islay early in the afternoon.

31st Oct (Day 304)

Arrival in Govan, demobilisation all day.

*J. Allen*

**Master’s Diary (Summary)**

Times in text are UTC

2006-10-10

0900   Scientific party commence joining v/l

Mobilisation continues

1500   Sign-on & Safety Briefing for Sci/Tech contingent

2006-10-11

0830   Critical instrument tests – all satisfactory

0850   PoB Ragnsson
0906  ERSB
0908  Singling up
0910  Tug ‘Magni’ fast, port aft
0917  All gone & clear fore & aft
0928  Clearing harbour stern first under tow
0936  Let go Tug
0940  Pilot away; v/l turning to port off harbour entrance
1000  FAOP; Akurey 182 degrs x 0.79nm
1200  64 07.4N  22 48.9W  Wind E’ly 30 knots
1305  63 58.2N  22 55.6W  Complement mustered @ emergency & boat stations
1425  Reykjaness 043 degrs x 2.2nm; v/l hove-to for foc’l pe vent closing
1430  Reduction in rpm continued due rough head seas & heavy swell
1600  Staarborg 018 degrs x 5.4nm Wind SE 32 knots
2000  63 34.7N  22 12.4W  Wind SExE 28 knots
2400  63 23.5N  21 31.7W  Wind SExE 25 knots

2006-10-12
0400  63 12.5N  20 51.0W  Surtsey Is 028 degrs x 7.9nm; A/c 097 degrs; Wind SExE 32
knots
0830  63 08.2N  19 55.2W  Hove-to on stn ‘IB21S’; comm of science; Wind ESE 28 knots
0851  PES deployed
0915  CTD deployed; Stn 16126#1
0930  CTD recovered due temp probe failure
1042  63 08.2N  19 54.8W  CTD re-deployed; Stn 16126#1
1109  63 08.3N  19 54.9W  @ bottom, 1026m
1144  CTD recovered; (bottles inop)
1155  In transit to next stn; Wind E’ly 35 knots
1312  63 13.0N  20 04.7W  Hove-to @ stn ‘IB22S’; WoW; Wind gusting > 40 knots
1600  Wind E’ly 31 knots
1830  Resumption of science
1841  63 13.1N  20 03.7W  CTD deployed; Stn 16127#1
1948  CTD recovered; Wind E’ly 20 knots
2030  63 14.3N  20 02.1W  Sampling complete; In transit to next stn.
2128

Hove-to @ stn ‘IB23S’

2146 63 19.1N 20 13.0W CTD deployed; Stn 16128#1

2215

CTD recovered; in transit to next stn

2400

Wind SxE 23 knots

2006-10-13

0239 62 54.9N 19 32.5W Hove-to @ stn ‘IB20S’

0258

CTD deployed; Stn 16129#1

0340 62 54.9N 19 32.5W @ bottom, 1400m; Wind S’ly 25 knots

0433 62 54.9N 19 31.7W CTD recovered; in transit to next stn ‘IB19S’

0643 62 40.1N 19 40.9W Hove-to & CTD deployed; Stn 16130#1

0719 62 40.3N 19 41.1W @ bottom, 1660m

0800

Wind S’ly 20 knots

0818 62 40.4N 19 41.4W CTD recovered; v/l slow-steaming towards next stn ‘IB18S’

1128 62 20.0N 19 49.8W Hove-to & CTD deployed; Stn 16131#1

1208 @ bottom, 1790m; Wind SxE 18 knots

1309

CTD recovered; v/l slow-steaming towards next stn

1540 62 00.1N 20 00.5W V/l hove-to ‘IB17’; assessing best heading in prevailing conditions

1600

Wind SExS 20 knots

1615 62 00.1N 20 00.9W CTD deployed; Stn 16132#1

1701 62 00.1N 20 01.4W @ bottom, 1800m

1802 62 00.3N 20 01.7W CTD recovered; v/l in transit to next stn

2000

Wind ExS 20 knots

2126 61 30.1N 20 00.0W Hove-to ‘IB16’ & CTD deployed; Stn 16133#1

2250 61 30.6N 19 59.0W @ bottom, 2180m

2400

Wind SxE 28 knots

2006-10-14

0006

CTD recovered; v/l in transit to next station

0110 61 26.3N 19 57.1W Wind gusting to 55 knots; v/l hove-to for sample completion

0234 61 26.3N 20 01.9W Sampling complete; deck secure; co & spd as per conditions
0400 Wind WSW 45 knots
0745 61 14.9N 20 00.0W On stn – assessing conditions
0800 Wind SW 25 knots
0900 Preparing to resume CTD ops ‘IB15’
0925 61 15.0N 20 00.0W CTD deployed; Stn 16134#1
1021 61 15.1N 19 59.6W @ bottom, 2359m
1155 61 15.2N 19 59.7W CTD recovered; v/l in transit to next stn; Wind S’ly 25 knots
1436 61 00.0N 20.00.0W CTD deployed ‘IB14’; Stn 16135#1
1534 @ bottom, 2375m
1600 Wind SSW 23 knots
1657 61 00.5N 19 58.9W CTD recovered; v/l in transit to next stn
2000 Wind S’ly 23 knots
2058 60 30.0N 20 00.0W Hove-to ‘IB13’ & CTD deployed; Stn 16136#1
2329 60 29.9N 19 59.1W CTD recovered; v/l in transit to next stn
2400 Wind SxW 25 knots

2006-10-15

0400 Wind WSW 20 knots
0437 60 00.1N 20 50.0W Hove-to ‘STNW’ & CTD deployed; Stn 16137#1
0537 60 00.3N 20 50.1W @ bottom, 2755m
0656 60 00.7N 20 50.6W CTD recovered; v/l repositioning for ST mooring deployment
0730 60 00.2N 20 49.0W Comm streaming mooring (STNW)
0802 60 00.063N 20 49.572W Mooring anchor wt released; Stn 16137#4; Wind WSW 15 knots
0830 Mooring confirmed @ bottom; v/l in transit to next stn
1200 Wind SW 20 knots
1230 59 29.9N 20.00.0W Hove-to ‘STC’ & CTD deployed; Stn 16138#1
1327 @ bottom, 2775m
1450 CTD recovered; v/l repositioning
1522 59 30.5N 19 58.6W Comm streaming mooring (STC)
1547 First buoyancy o’side @ 800m line out
1600 Wind SW 20 knots
1616 Second buoyancy o’side @ 1800m line out
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<tr>
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<tr>
<td>1650</td>
<td>59 29.913N</td>
<td>19 59.757W</td>
<td>Mooring anchor wt released; Stn 16138#4 (2775m water depth)</td>
</tr>
<tr>
<td>1710</td>
<td></td>
<td></td>
<td>Mooring confirmed @ bottom; v/l in transit to next stn</td>
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<tr>
<td>2000</td>
<td></td>
<td></td>
<td>Wind SW 23 knots</td>
</tr>
<tr>
<td>2045</td>
<td>59 39.2N</td>
<td>19 46.2W</td>
<td>Hove-to &amp; comm streaming mooring (STNE)</td>
</tr>
<tr>
<td>2102</td>
<td>59 38.972N</td>
<td>18 46 838W</td>
<td>Mooring anchor wt released; Stn 16139#4</td>
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<td>2128</td>
<td></td>
<td></td>
<td>Mooring confirmed @ bottom; v/l in transit to next stn</td>
</tr>
<tr>
<td>2400</td>
<td>59 22.6N</td>
<td>19 19.0W</td>
<td>Wind SW 25 knots</td>
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2006-10-16

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<tr>
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<td></td>
<td>Wind W’ly 30 knots</td>
</tr>
<tr>
<td>0510</td>
<td>58 52.0N</td>
<td>20 24.0W</td>
<td>Hove-to on stn ‘STS’; preparation of mooring</td>
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<tr>
<td>0618</td>
<td>58 51.6N</td>
<td>20 23.2W</td>
<td>Commence streaming mooring</td>
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<tr>
<td>0644</td>
<td>58 51.968N</td>
<td>20 24.169W</td>
<td>Mooring anchor wt released; Stn 16140#4</td>
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<tr>
<td>0712</td>
<td></td>
<td></td>
<td>Mooring confirmed @ bottom; v/l repositioning for CTD stn</td>
</tr>
<tr>
<td>0734</td>
<td>58 52.3N</td>
<td>20 26.3W</td>
<td>CTD deployed; Stn 16140#1</td>
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<td>0800</td>
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<td></td>
<td>Wind WNW 28 knots</td>
</tr>
<tr>
<td>0836</td>
<td>58 52.3N</td>
<td>20 27.6W</td>
<td>@ bottom, 2822m</td>
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<tr>
<td>1015</td>
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<td></td>
<td>CTD recovered &amp; secure; v/l in transit towards ‘IB12’ CTD stn</td>
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<tr>
<td>1200</td>
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<td></td>
<td>Wind NWxN 25 knots</td>
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<tr>
<td>1600</td>
<td>59 37.4N</td>
<td>20 24.8W</td>
<td>Wind NxE 32 knots</td>
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<tr>
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<td>Wind NNE 33 knots</td>
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<tr>
<td>2030</td>
<td>59 59.9N</td>
<td>19 59.7W</td>
<td>Hove-to ‘IB12’ &amp; CTD deployed; Stn 16141#1</td>
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<tr>
<td>2124</td>
<td>59 59.7N</td>
<td>19 59.0W</td>
<td>@ bottom, 2705m</td>
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<tr>
<td>2300</td>
<td>59 59.6N</td>
<td>19 58.6W</td>
<td>CTD recovered; v/l in transit towards ‘IB11’</td>
</tr>
<tr>
<td>2400</td>
<td></td>
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<td>Wind NNE 30 knots</td>
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2006-10-17

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<tr>
<td>0200</td>
<td>59 43.5N</td>
<td>19 36.9W</td>
<td>V/l in zig-zag transit towards next stn</td>
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<tr>
<td>0305</td>
<td>59 36.8N</td>
<td>19 25.7W</td>
<td>A/c to 070 (G) towards next stn</td>
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<tr>
<td>0400</td>
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<td>Wind NE 31 knots</td>
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<tr>
<td>0452</td>
<td>59 39.6N</td>
<td>19 06.5W</td>
<td>Hove-to ‘IB11’ &amp; CTD deployed; Stn 16142#1</td>
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33
2006-10-18

0400  59 59.9N  18 17.4W  Wind ENE 40 knots
0800  60 07.0N  18 04.3W  Wind NExE 38 knots
1200  60 13.7N  17 47.5W  Wind ENE 38 knots
1230  60 14.5N  17 45.3W  A/c to run downwind; hdng 215 degs G
1600  59 43.2N  18 27.6W  Wind ENE 30 knots
2000  59 03.7N  19 08.4W  Wind NExE 35 knots
2400  58 25.3N  20 06.3W  Wind NExE 35 knots; hdng 215 (G) @ 11 knots

2006-10-19

0400  57 48.7N  20 56.1W  Wind NExE 35 knots
0800  57 09.7N  21 41.5W  Wind NE 45 knots
1200  56 31.5N  22 16.1W  Wind NE 40 knots; hdng 215 (G) @ 11 knots
1230  56 28.6N  22 19.6W  V/l a/c, head to weather; making good ENE track @ 5 knots
1600  56 30.9N  21 46.1W  Wind NE 48 knots
2000  56 40.5N  21 32.2W  Wind NExN 25 knots
2400  56 55.4N  20 16.5W  Wind NNE 38 knots; making good ENE track @ 8 knots

2006-10-20

0400  57 11.6N  19 20.8W  Wind Var 8 knots
0800  57 36.2N  18 33.9W  Wind S’ly 25 knots
1200  58 00.4N  17 39.8W  Wind SE 23 knots; making good NExE track @ 10 knots
1600 58 19.1N 16 50.9W Wind ENE 22 knots
1615 Emergency exercises: l’boat video/’table-top’/safety quiz
1830 58 30.2N 16 18.2W Heaving-to 10nm west of ‘IB4’ for CTD
1847 58 30.3N 16 17.9W CTD deployed; Stn 16143#1
1921 58 30.6N 16 17.8W @ bottom, 1200m
2000 Wind E’ly 15 knots
2015 58 30.9N 16 17.9W CTD recovered; v/l turning to 180 (G) for z-z co to next stn
2348 57 58.4N 16 16.1W A/c to 060 (G) towards ‘IB3’; Wind ExN 30 knots

2006-10-21

0400 Wind ExN 38 knots
0430 58 15.1N 15 20.1W Hove-to on stn; assessing conditions
0507 58 15.5N 15 20.2W CTD deployed; Stn 16144#1
0559 58 16.2N 15 20.4W CTD recovered; v/l turning to S’ly track for z-z co to next stn
0915 57 45.3N 15 26.6W A/c to 068 (G) towards ‘IB2’
1200 57 51.7N 15 00.9W Wind ExN 38 knots
1517 57 57.0N 14 34.9W Hove-to & CTD deployed; Stn 16145#1
1534 @ bottom, 430m; Wind NExE 38 knots
1604 57 56.8N 14 34.9W CTD recovered; v/l turning to S’ly track for z-z co to next stn
1844 57 32.1N 14 50.8W A/c to 075 (G) towards ‘IB1’
2000 Wind NExE 33 knots
2330 57 40.0N 13 54.0W Hove-to @ IB1 assessing conditions
2400 Wind NE 35 knots

2006-10-22

0048 57 39.9N 13 54.4W CTD deployed; Stn 16146#1
0055 @ bottom, 135m
0109 57 39.8N 13 54.6W CTD recovered
0125 V/l turned to 206 (G), comm z-z track to next stn
0250 57 26.1N 14 06.4W A/c to 070 (G) towards Stn ‘B’
0400 Wind ENE 30 knots
0728 57 34.0N 13 19.9W Hove-to on stn

35
0745  CTD deployed;  Stn 16147#1;  Wind NE 33 knots
0818  57 34.3N  13 19.6W  CTD recovered;  v/l comm z-z track, 067 (G), towards next stn
1043  57 38.6N  12 54.8W  A/c to 215 (G) towards Stn ‘C’
1148  Hove-to on stn
1206  57 33.0N  12 59.7W  CTD deployed;  Stn 16148#1;  Wind NE 30 knots
1218  @ bottom, 280m
1240  57 32.8N  12 59.6W  CTD recovered;  v/l comm z-z track, 065 (G), towards next stn
1430  Hove-to on stn ‘D’
1450  57 32.4N  12 52.1W  CTD deployed;  Stn 16149#1
1521  @ bottom, 1060m
1603  57 32.5N  12 52.4W  CTD recovered;  v/l on z-z track to next stn;  Wind NExE 25 knots
1743  57 32.3N  12 45.7W  Hove-to ‘D1’ & CTD deployed;  Stn 16150#1
1822  @ bottom, 1440m
1924  57 32.2N  12 45.6W  CTD recovered;  v/l on z-z track towards next stn
2000  Wind NE 33 knots
2056  Hove-to on stn ‘E’
2112  57 31.8N  12 37.4W  CTD deployed;  Stn 16151#1
2153  @ bottom, 1640m wire out
2305  57 31.9N  12 37.4W  CTD recovered;  v/l comm z-z track towards next stn
2400  Wind NE 40 knots

2006-10-23

0045  57 31.5N  12 32.0W  Hove-to on stn ‘E1’
0103  57 31.6N  12 31.8W  CTD deployed;  Stn 16152#1
0143  57 31.7N  12 31.8W  @ bottom, 1730m
0246  CTD recovered;  v/l comm z-z track towards next stn
0400  Wind NE 35 knots
0615  57 37.6N  12 04.1W  A/c towards station
0724  57 30.5N  12 15.2W  Hove-to on stn ‘F’;  Wind gusting 45 knots;  V/l WoW
0800  Wind NE 35 knots
1200  57 37.0N  12 07.3W  Wind NE 35 knots
1600  57 43.7N  11 52.0W  Wind NE 33 knots
2000 57 48.3N 11 42.0W Wind NE 33 knots
2400 Wind NE 35 knots

**2006-10-24**

0040 57 56.7N 11 22.9W Wind NE 30 knots
0040 57 57.6N 11 20.7W A/c to 225 (G) towards work site
0800 Wind NE 30 knots
0830 57 30.5N 12 15.1W Hove-to on stn ‘F’; resume science
0836 57 30.5N 12 15.0W CTD deployed; Stn 16153#1
0935 57 30.8N 12 15.2W @ bottom, 1790m
1047 57 31.6N 12 15.7W CTD recovered
1053 Commence bongo net deployments; Stn 16153#2
1125 57 31.9N 12 16.3W Comp. bongo net deployments; v/l in z-z transit for site ‘G’
1200 Steering 080 (G) for 1330hrs Helo r’vous; Wind ENE 30 knots
1312 57 33.0N 11 52.0W VHF exchange with Rescue Helicopter ‘MU’
1334 ‘MU’ on station of port qtr; v/l head to wind (060 G) @ 4.5 knots
1339 Winchman on deck via Hi-Line
1341 Bags winched up to ‘MU’
1345 Casualty & Winchman winched off deck
1346 ‘MU’ clear of v/l, bound for Stornoway
1350 57 34.5N 11 45.4W Aft deck secure; v/l round & hdg for stn ‘G’
1447 57 29.4N 11 50.8W Hove-to & CTD deployed; Stn 16154#1
1527 @ bottom, 1775m
1600 Wind ENE 23 knots
1637 57 29.4N 11 51.1W CTD recovered; v/l comm z-z transit towards next stn
1915 57 29.0N 11 31.9W Hove-to ‘H’ & CTD deployed; Stn 16155#1
2000 @ bottom, 2000m; Wind NE 30 knots
2116 57 30.1N 11 31.5W CTD recovered
2130 Bongo net deployed; Stn 16155#2
2203 Bongo net sampling complete
2225 57 30.9N 11 28.5W V/l on z-z transit towards Stn ‘I’
2353 57 28.0N 11 19.2W Hove-to on stn; Wind NE 35 knots

37
2006-10-25

0006  CTD deployed;  Stn 16156#1
0033     @ bottom, 745m
0110  CTD recovered;  v/l comm z-z transit towards next stn
0400  Wind NExE 28 knots
0408  57 26.9N  11 05.2W  Hove-to on stn ‘J’;  CTD winch compensator problems
0435  57 27.0N  11 05.2W  CTD deployed;  Stn 16157#1
0457     @ bottom, 565m
0532  57 27.3N  11 05.4W  CTD recovered
0549  57 27.4N  11 05.6W  Bongo net deployed;  Stn 16157#2
0623  57 27.9N  11 06.0W  Bongo net sampling complete;  comm z-z transit to next stn
0750  57 24.0N  10 52.0W  Hove-to ‘K’ & CTD deployed;  Stn 16158#1
0811     @ bottom, 770m;  Wind NE 30 knots
0845  57 24.4N  10 52.1W  CTD recovered;  comm z-z transit towards next stn
1018  Hove-to on stn ‘L’
1027  57 22.0N  10 40.0W  CTD deployed;  Stn 16159#1
1114  57 22.1N  10 40.0W  @ bottom, 2095m wire out
1200  Wind ExN 30 knots
1223  57 22.1N  10 39.8W  CTD recovered
1235  Bongo net deployed;  Stn 16159#2
1301  Bongo net sampling complete
1320  Crane secure;  comm z-z transit towards next stn
1540  57 17.8N  10 23.1W est  Hove-to ‘M’ & CTD deployed;  Stn 16160#1
1626  57 18.2N  10 22.7W  @ bottom, 2200m;  Wind ExN 20 knots
1725  57 18.6N  10 22.3W  CTD recovered
1741  Bongo net deployed;  16160#2
1753  Bongo net recovered;  v/l in transit to next stn
1934  57 14.0N  10 03.0W  Hove-to ‘N’ & CTD deployed;  Stn 16161#1
2000  Wind E’ly 15 knots
2023  57 14.0N  10 02.9W  @ bottom, 2090m wire out
2135  57 14.2N  10 02.5W  CTD recovered;  v/l in transit to next stn ‘O’
2310  57 09.0N  09 41.9W  Hove-to & CTD deployed;  Stn 16162#1
2352  57 08.9N  09 42.1W  @ bottom, 1914m wire out
2400  Wind ESE 8 knots

2006-10-26

0045  CTD recovered; v/l in transit to next stn
0245  57 05.9N  09 25.3W  Hove-to ‘P’ & CTD deployed;  Stn 16163#1
0320  @ bottom, 1420m
0407  57 05.9N  09 25.7W  CTD recovered; v/l in transit to stn ‘Q’;  Wind NxW 20 knots
0510  57 03.0N  09 13.0W  Hove-to & CTD deployed;  Stn 16164#1
0551  57 03.2N  09 13.5W  CTD recovered
0603  Bongo net deployed; 16164#2
0618  Bongo net recovered; v/l in transit to stn ‘R’
0730  57 00.0N  09 00.0W  Hove-to & CTD deployed;  Stn 16165#1
0751  56 59.9N  09 00.0W  CTD recovered
0800  Bongo net deployed; 16165#2;  Wind NNW 15 knots
0816  Bongo net recovered; v/l in transit to stn ‘S’
0925  56 57.0N  08 47.0W  Hove-to & CTD deployed;  Stn 16166#1
0935  @ bottom, 118m
0947  56 57.1N  08 47.0W  CTD recovered; v/l in transit to stn ‘15G’
1102  56 53.0N  08 30.2W  Hove-to & CTD deployed;  Stn 16167#1
1120  56 52.9N  08 30.3W  CTD recovered; v/l in transit to stn ‘T’
1200  56 48.8N  08 22.1W  Wind NxW 25 knots
1245  56 50.4N  08 20.4W  Hove-to & CTD deployed;  Stn 16168#1
1300  CTD recovered; v/l in transit to stn ‘14G’
1440  56 48.7N  08.09.9W  Hove-to & CTD deployed;  Stn 16169#1
1458  CTD recovered; v/l in z-z transit towards Turb Profiler site
1600  56 43.9N  08 05.1W  Strng 160 (G);  Wind N’ly 33 knots
1710  56 33.1N  07 56.6W  A/c 055 (G)
1845  56 39.9N  07 37.7W  Assessing conditions @ Profiler site
1918  56 39.9N  07 37.2W  SoL (E-going); adjusting buoyancy;  Stn 16170
1929  56 39.9N  07 36.8W  Profiler streamed; comm cont. vert. profiling; v/l 1.2 kn thro’
       water
2000  Wind N’ly 25 knots;
<table>
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<tr>
<th>Time</th>
<th>Location</th>
<th>Event Description</th>
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<tbody>
<tr>
<td>2025</td>
<td>56 40.05N 07 34.80W</td>
<td>Request to heave-to; instrument snagged on seabed</td>
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<tr>
<td>2030</td>
<td>56 40.07N 07 34.80W</td>
<td>Instrument lost; reeling in slack cable</td>
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<tr>
<td>2040</td>
<td></td>
<td>All cable recovered</td>
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<td>2050</td>
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<td>V/l repositioning for CTD @ position of loss</td>
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<tr>
<td>2126</td>
<td>56 40.2N 07 34.6W</td>
<td>Hove-to &amp; CTD deployed; Stn 16171#1</td>
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<td>2138</td>
<td>56 40.2N 07 34.5W</td>
<td>@ bottom, 215m</td>
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<td>2157</td>
<td>56 40.3N 07 34.6W</td>
<td>CTD recovered; v/l in transit to stn ‘9G’</td>
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<tr>
<td>2307</td>
<td>56 44.1N 07 19.9W</td>
<td>Hove-to &amp; CTD deployed; Stn 16172#1</td>
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<td>2330</td>
<td>56 44.1N 07 19.9W</td>
<td>CTD recovered</td>
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<td>2345</td>
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<td>Bongo net deployed</td>
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<tr>
<td>2400</td>
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<td>Bongo net recovd; v/l in transit to stn ‘10G’; Wind NNE 10 knots</td>
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**2006-10-27**

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<td>0105</td>
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<td>Hove-to &amp; CTD deployed; Stn 16173#1</td>
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<td>0134</td>
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<td>CTD recovered; v/l in transit to stn ‘11G’</td>
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<td>0230</td>
<td>56 44.2N 07 40.2W</td>
<td>Hove-to &amp; CTD deployed; Stn 16174#1</td>
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<td>0242</td>
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<td>CTD recovered</td>
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<td>0253</td>
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<td>Bongo net deployed; 16174#2</td>
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<td>Bongo net recovered; v/l in transit to stn ‘12G’</td>
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<td>0353</td>
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<td>Hove-to &amp; CTD deployed; Stn 16175#1</td>
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<td>Wind Var &amp; Lt</td>
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<td>0404</td>
<td>56 45.7N 07 50.0W</td>
<td>CTD recovered; v/l in transit to stn ‘13G’</td>
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<td>0503</td>
<td>56 47.0N 07 59.9W</td>
<td>Hove-to &amp; CTD deployed; Stn 16176#1</td>
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<td>0527</td>
<td>56 47.3N 07 59.7W</td>
<td>CTD recovered</td>
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<td>0539</td>
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<td>Bongo net deployed; Stn 16176#2</td>
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<td>0549</td>
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<td>Bongo net recovered</td>
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<tr>
<td>0604</td>
<td>56 47.4N 07 58.9W</td>
<td>Deck secure; v/l sets co for Wyville Thomson Ridge</td>
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<tr>
<td>0800</td>
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<td>Wind SxW 15 knots</td>
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<tr>
<td>0806</td>
<td>57 09.8N 08 06.4W</td>
<td>Adj co to 344 (G)</td>
</tr>
<tr>
<td>1136</td>
<td>57 48.3N 08 27.5W</td>
<td>A/c to 270 (T) for passage past St. Kilda</td>
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<tr>
<td>1153</td>
<td>Levanish Is 170 (G) x 0.94</td>
<td>A/c to 322 (T)</td>
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<tr>
<td>1208</td>
<td>Mina Stac Is 181 (G) x 1.0</td>
<td>A/c to 357 (T); Wind SWxS 30 knots</td>
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<td>1600</td>
<td>58 25.8N</td>
<td>08 31.6W</td>
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<td>1615</td>
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<td>08 39.0W</td>
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<td>2000</td>
<td>59 46.5N</td>
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<td>58 25.8N</td>
<td>08 31.6W</td>
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**2006-10-28**

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<tr>
<td>0345</td>
<td>60 20.6N</td>
<td>08 59.1W</td>
<td>Hove-to @ Stn ‘W1’; assessing conditions</td>
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<td>0400</td>
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<td>Wind SWxW 38 knots</td>
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<tr>
<td>0422</td>
<td>60 20.5N</td>
<td>08 59.5W</td>
<td>CTD deployed; Stn 16177#1</td>
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<tr>
<td>0455</td>
<td>60 20.5N</td>
<td>08 59.5W</td>
<td>CTD recovered; v/l repositioning</td>
</tr>
<tr>
<td>0544</td>
<td>60 18.7N</td>
<td>08 56.9W</td>
<td>CTD deployed ‘W2’; Stn 16178#1</td>
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<tr>
<td>0628</td>
<td>60 18.7N</td>
<td>08 57.0W</td>
<td>CTD recovered; v/l repositioning</td>
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<tr>
<td>0739</td>
<td>60 17.8N</td>
<td>08 55.9W</td>
<td>CTD deployed ‘W3’; Stn 16179#1</td>
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<tr>
<td>0800</td>
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<td>Wind SWxW 28 knots</td>
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<td>0827</td>
<td>60 17.9N</td>
<td>08 55.9W</td>
<td>CTD recovered; v/l repositioning to ‘W5’</td>
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<tr>
<td>0931</td>
<td>60 16.0N</td>
<td>08 55.1W</td>
<td>CTD deployed; Stn 16180#1</td>
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<tr>
<td>1017</td>
<td>60 15.9N</td>
<td>08 55.0W</td>
<td>CTD recovered; v/l repositioning to interrogate &amp; release mooring</td>
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<tr>
<td>1040</td>
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<td>Mooring location verified; Stn 16181</td>
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<tr>
<td>1047</td>
<td>60 15.7N</td>
<td>08 54.5W</td>
<td>V/l hove-to &amp; mooring released</td>
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<tr>
<td>1057</td>
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<td>Mooring @ surface</td>
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<tr>
<td>1112</td>
<td>60 15.1N</td>
<td>08 54.6W</td>
<td>ADCP hooked alongside</td>
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<td>1125</td>
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<td></td>
<td>Recovery via hangar top crane completed</td>
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<tr>
<td>1200</td>
<td>60 16.5N</td>
<td>08 01.9W</td>
<td>V/l repositioning for ‘W4’ stn; Wind SWxW 15 knots</td>
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<tr>
<td>1236</td>
<td>60 16.9N</td>
<td>08 55.4W</td>
<td>Hove-to &amp; CTD deployed; Stn 16182#1</td>
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<tr>
<td>1318</td>
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<td>CTD recovered; v/l repositioning to stn ‘W6’</td>
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<tr>
<td>1405</td>
<td>60 15.3N</td>
<td>08 55.1W</td>
<td>Hove-to &amp; CTD deployed; Stn 16183#1</td>
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<td>1434</td>
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<td>@ bottom, 1160m</td>
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<tr>
<td>1527</td>
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<td></td>
<td>CTD recovered; v/l repositioning for mooring re-deployment</td>
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<tr>
<td>1558</td>
<td>60 15.0N</td>
<td>08 54.9W</td>
<td>ADCP flotation buoy streamed; Wind SWxW 15 knots</td>
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<tr>
<td>1603</td>
<td>60 15.003N</td>
<td>08 54.990W</td>
<td>Mooring clump weight released; Stn 16184</td>
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<tr>
<td>1651</td>
<td>60 14.2N</td>
<td>08 54.9W</td>
<td>Hove-to ‘W8’ &amp; CTD deployed; Stn 16185#1</td>
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<tr>
<td>1726</td>
<td>60 14.2N</td>
<td>08 55.0W</td>
<td>@ bottom, 1200m</td>
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</tbody>
</table>
1815  60 14.1N  08 55.0W  CTD recovered; v/l repositioning for final WTR stn
1927  60 13.6N  08 55.0W  Hove-to & CTD deployed; Stn 16186#1
1957  @ bottom, 859m; Wind NWxW 25 knots
2017  60 13.6N  08 55.0W  CTD recovered
2042  60 14.0N  08 55.7W  Sampling comp & deck secure; v/l in transit towards Barra Hd
2400  59 28.1N  08 57.7W  Wind NWxN 35 knots

2006-10-29
0400  58 59.0N  08 46.1W  Wind NWxN 15 knots
0800  Wind W’ly 15 knots
1000  58 00.4N  08 28.0W  Boreray Is 188 (G) x 7.8nm
1046-1153  Co var to MO passing St Kilda group of islands
1200  Wind WSW 12 knots
1600  57 05.4N  08 04.7W  Wind SxE 15 knots
1730  56 52.2N  07 59.9W  A/c 128 (G)
1845  56 44.8N  07 44.2W  A/c 092 (G); v/l rounding Barra Head
2000  Wind SSE 35 knots
2054  56 44.1N  07 09.9W  Hove-to ‘8G’ & CTD deployed; Stn 16187#1
2120  56 44.2N  07 09.6W  CTD recovered; hove-to sampling then v/l in transit to stn ‘7G’
2229  56 44.1N  07 00.0W  Hove-to ‘7G’ & CTD deployed; Stn 16188#1
2247  56 44.2N  07 59.5W  CTD recovered; hove-to sampling then v/l in transit to stn ‘6G’
2355  56 44.0N  06 44.9W  V/l hove-to on stn; Wind SxE 40 knots

2006-10-30
0022  CTD deployed; Stn 16189#1
0033  CTD recovered; hove-to sampling then v/l in transit to stn ‘5G’
0137  56 43.9N  06 36.1W  Hove-to & CTD deployed; Stn 16190#1
0148  CTD recovered; hove-to sampling then v/l in transit to stn ‘4G’
0250  56 43.9N  06 27.0W  Hove-to & CTD deployed; Stn 16191#1
0303  CTD recovered; hove-to sampling then v/l in transit to stn ‘3G’
0354  56 42.6N  06 22.0W  Hove-to & CTD deployed; Stn 16192#1
0400  Wind SW 30 knots
0412  CTD recovered; hove-to sampling then v/l in transit to stn ‘2G’
0502  56 41.0N  06 16.9W Hove-to & CTD deployed; Stn 16193#1
0517  CTD recovered; hove-to sampling then v/l in transit to stn ‘1G’
0545 est  Stbd anchor cleared
0635  56 40.0N  06 08.0W Hove-to & CTD deployed; Stn 16194#1
0658  CTD recovered
0700  56 40.0N  06 08.1W D312 science comp; v/l transitting Snd. of Mull on passage
        Govan
0800  Wind SWxS 30 knots
0932  Clearing Sound of Mull
1200  Wind WSW 25 knots
1248  Entering Sound of Islay
1352  Clearing Sound of Islay
1516  Rubha nan bcn 283 (G) x 6.0nm; A/c to 234 degs
1600  55 29.2N  06 15.3W Wind SWxW 30 knots
1615  PES recovered
1745  Altacarry Hd 206 (G) x 3.5nm; A/c to 144 degs
2000  Wind WSW 25 knots
2012  Sanda Is 334 (G) x 3.84nm; A/c 051 degs; reduce to 85 rpm
2205  Ailsa Craig 132 (G) x 4.0nm
2400  Wind SW 30 knots

2006-10-31

0200  Holy Is 280 (G) x 7.0nm
0233  ETA reported to Clydeport Estuary Control
0400  Wind NW 50 knots
0430  Anchors cleared approaching Cumbrae channel
0532  Mounstuart buoy abeam to port
0630  All critical instruments tested & satis.
0642  ERSB approaching Kempock Pilot stn
0711  Pilot o/b I. Jamieson
0801  Garrison bcn abeam to stbd; Wind WNW 25 knots
0841  Tug ‘Battler’ in attendance
0900 V/I swinging into dock basin
0917 Spring ashore for’d
0919 ‘Battler’ pushing port qtr
0922 Alongside & making fast
0923 Tug away
0930 All fast 4&2 F&A; RFWE; Pilot away

P. Sarjeant

3. TECHNICAL SUPPORT

Deck Operations – Alan Sherring

Sediment Trap / Current Meter Mooring Deployments

Moorings were deployed using a double barrel capstan winch with 90 degree diverter sheave and reeling winch in conjunction with the ship fitted, aft Effer cranes. Mooring lines were passed under a deck mounted counting sheave located in front of the double barrel winch and up through a wide throated sheave block hung from the port crane.

Buoyancy spheres, current meters and acoustic releases were manually handled and connected in, after stopping off the mooring line to a deck-mounted eyebolt. Sediment traps and clump weights were deployed from the starboard crane using a release hook.

ADCP Mooring Turn Around (Wyville Thomson Ridge)

The mooring was recovered by attaching a snap hook onto the buoy frame with a pole from the starboard side. The mooring was then hoisted onto the starboard deck using the ships forward crane. Re-deployment was carried out from the aft deck using both of the aft cranes and quick release hooks, the starboard one for the buoy and port for clump weight.

Zooplankton Net Deployments

Nets were deployed to 100 metres depth using a hydraulic deck winch mounted on the starboard deck in conjunction with the amidships crane fitted with a 2Te snatch block. A Kevlar rope marked off with tape at 25 metre intervals was used. The winch was connected to an 11 gpm deck hydraulic supply giving a rope speed of approx 25 m/min.
The deployment of nets could only be carried out in relatively calm conditions due to concerns with the rope leading aft and becoming entangled with the propeller / rudder.

**CTD Deployments**

CTDs were deployed using the ship fitted winch (standard CTD cable) and the starboard gantry. The CTD “railway track” was used to allow the CTD to be moved forward after deployment to give some degree of shelter during sampling activities.

**UKORS Instrumentation – Terry Edwards**

**CTD Instrumentation**

A total of 70 CTD profiles were carried out. The stainless steel frame configuration was as follows:

- Sea-Bird 9/11 *plus* CTD System
- 24 by 10L Ocean Test Equipment External Spring Water Samplers
- Sea-Bird 43 Oxygen Sensor
- Chelsea MKIII Aquatracka Fluorometer
- Chelsea MKII Alphatracka 25cm path Transmissometer
- OED LADCP Pressure Case Battery Pack
- RD Instruments Workhorse 300 KHz Lowered ADCP (downward-looking master configuration)
- RD Instruments Workhorse 300 KHz Lowered ADCP (upward-looking slave configuration)
- Benthos Altimeter

The pressure sensor was located 30cm from the bottom of the water samplers, and 119cm from the top of the water samplers.
CTD Instrument Configuration

The Sea-Bird CTD configuration can be found in the relevant con files on the D312 SeaBird data disk, but for example, calibration details as follows:

Date: 10/12/2006
ASCII file: C:\D312\ctd\data\16126.con
Configuration report for SBE 911/917 plus CTD
---------------------------------------------
Frequency channels suppressed: 0
Voltage words suppressed: 0
Computer interface: RS-232C
Scans to average: 1
Surface PAR voltage added: No
NMEA position data added: Yes
Scan time added: No

1) Frequency 0, Temperature

Serial number: 03P-2728
Calibrated on: 15 Mar 06
G: 4.36015616e-003
H: 6.44627842e-004
I: 2.34904246e-005
J: 2.24154778e-006
F0: 1000.000
Slope: 1.00000000
Offset: 0.0000

2) Frequency 1, Conductivity

Serial number: 04C-2851
Calibrated on: 9 JUN 06
G: -9.96127762e+000
H: 1.35418827e+000
I: 7.83385464e-004
J: 1.65005990e-005
CTcor: 3.2500e-006
CPcor: -9.57000000e-008
Slope: 1.00000000
Offset: 0.00000

3) Frequency 2, Pressure, Digiquartz with TC

Serial number: 94756
Calibrated on: 15 Apr 2004
C1: -4.722750e+004
C2: -1.465524e-001
C3: 1.449080e-002
D1: 3.863800e-002
D2: 0.000000e+000
T1: 3.011286e+001
T2: -2.710648e-004
T3: 4.095660e-006
T4: 2.377730e-009
T5: 0.000000e+000
Slope: 1.00000000
Offset: 0.00000
AD590M: 1.285020e-002
AD590B: -8.056957e+000

4) Frequency 3, Temperature, 2

Serial number: 03P-4490
Calibrated on: 11 Jun 06
G: 4.40570480e-003
5) Frequency 4, Conductivity, 2

Serial number: 04C-2450
Calibrated on: 15 Jun 06
G: -1.05486233e+001
H: 1.67929419e+000
I: -1.02258454e-003
J: 1.86389112e-004
CTcor: 3.2500e-006
CPcor: -9.57000000e-008
Slope: 1.00000000
Offset: 0.00000

6) A/D voltage 0, Oxygen, SBE 43

Serial number: 0612
Calibrated on: 24 Nov 05
Soc: 3.5720e-001
Boc: 0.0000
Offset: -0.5035
Tcor: 0.0011
Pcor: 1.35e-004
Tau: 0.0

7) A/D voltage 1, Free
8) A/D voltage 2, Altimeter

    Serial number: 1037
    Calibrated on:
    Scale factor: 15.000
    Offset: 0.000

9) A/D voltage 3, Fluorometer, Chelsea Aqua 3

    Serial number: 088108
    Calibrated on: 17 Nov 2004
    VB: 0.287100
    V1: 1.978300
    Vacetone: 0.331500
    Scale factor: 1.000000
    Slope: 1.000000
    Offset: 0.000000

10) A/D voltage 4, Free

11) A/D voltage 5, Free

12) A/D voltage 6, User Polynomial

    Serial number: 169
    Calibrated on: 7 Jul 05
    Sensor name: BBRTD
    A0: -0.00025440
    A1: 0.00318000
    A2: 0.00000000
    A3: 0.00000000
13) A/D voltage 7, Transmissometer, Chelsea/Seatech/Wetlab CStar

    Serial number: 04-4223-001
    Calibrated on: 8 Dec 04
    M: 20.2870
    B: -1.0144
    Path length: 0.250

**CTD Frame Deployment Notes**

One frame was used throughout the cruise. The following notes are taken from the technician diary and are organised by time. Individual casts that had no outstanding events or sensor changes are not logged here.

**12 Oct 2006**

CTD cast 001 (16126) aborted at 80m, primary temp spiking to full scale. Leaking BH connector on CTD. Cleaned it up, and at same time put primary sensors on vane.

Re did the cast same numbers, data good, but bottles would not fire, no feedback. Leaky BH connector on CTD(JT7), cleaned and cable replaced.

**13 Oct 2006**

Removed BBRTD sn169. Had been very noisy. CG had noted that the black end portion had rotated when removing the cap. Noted on removal that the rubber on the pins was damaged also, with slight corrosion on 1 pin.

Still noise on V6. Checked cabling etc.

Cast 16132, comms problem on master ladcp. Removed cable from unit to reset comms, worked ok, but also reset clock.

Exchanged altimeter. Removed #1040, fitted #1037. Worked ok, locked fully at 50m. Still using echosounder for approach. #1040 appears to have something loose inside.
Cast 16133 fitted releases 325 and 440 for wire test. Also fitted full 24 bottles. 325 diagnostics ok, then fired ok. 440, ranged ok, but could not get diagnostics or release to work. Suspect TE finger trouble with TT801.

Post cast, still getting rogue voltage on V6, slight leak at BOB end of aux3 cable. Removed and blanked both ends, put trans onto v4. Removed uwirr cable, as found corrosion on that. Also corrosion on bob trans BH connector, cleaned all BOB connectors, and changed trans cable.

18th Oct 2006

Stripped alt. 1040, slight leak some corrosion on board. Outer O-ring damaged, but also found BH connector not tight. Cleaned and reassembled, but still didn’t work.

21st Oct 2006

Oxy sensor BH leaked. Changed BH connector, now ok, continuous checking for leaky connectors.

26th Oct 2006

Altimeter inconsistent. Found damaged cable, broken in moulding so swapped that out.

Slave LADCP has failed to start on 3 casts, resulting in no data, winadcp showing all zeros for start and end times. Have added a 10 minute delay (ST600) in case it is lack of a synch pulse from the master.

Casts with no data, 16138, 16165 and 16169

27th Oct 2006

Removed and cleaned / checked Latch Mechanism from Rosette. Bottle 15 has been sporadically not firing. No obvious reason, and unable to recreate the problem on deck.
**Sediment trap mooring operations** – *Terry Edwards, Richard Sanders, Paul Provost, Colin Griffiths*

**Mooring deployment 1.**

STNW  Discovery # 16137  15th Oct 06  08:02  2781m

60° 00.063’ N  20° 49.512’ W

RCM8 #11216

Sed trap 21 bottle # ML11804-05

Acoustic release RT661, #440

Timing 0730  Buoyancy in water

0735  Sed trap in water

0736  RCM in water

0739  100m cable join

0752  Release in water

0802  Anchor in water

Tracked using SAMS TT301, single element PES fish.

Ship position 60° 00.0141’N,  20° 49.7065’W

1401m@0814

1837m@0817

2200m@0820

Bottom 0828. Confirmed static.
Mooring Deployment 2

STC Discovery # 16138 15\textsuperscript{th} Oct 06 1650 2775m (2765 corrected)

59° 29.913’ N 19° 59.757’ W

RCM8 #9682
Sed trap 21 bottle # ML11804-02
Acoustic release AR861B2s # 325
RDI 75Khz long ranger #

From Bottom, 1000kg chain clump, 2 x 100m, Release, 200m 10mm polyester, RCM8, 15m 12mm polyester, sed trap, 25m 12mm polyester, 7m chain with 6 spheres, 506+528 10mm polyester, 7m chain with 6 spheres, 887 m 10mm polyester, made up of 520 + 153 + 152 + 45 + 20, 5m chain, 2m 5/8 chain, ADCP in 45” flotech buoy. Total length 2402m. During deployment, the line lengths were calculated incorrectly, a 200m section was not taken into account. Therefore the ADCP is actually at 363m below surface.

Timing
1520 Pellet in water
1523 ADCP in water
1549 Upper buoyancy
1618 lower buoyancy
1628 Sed trap
1631 RCM8
1650 Anchor
Release tracked using SAMS TT301 through fish single element. Descent 140m/min, slowing to 120. Confirmed on seabed static at 1710, range 2585m

Mooring Deployment 3

STNE  Discovery # 16139  15th Oct 2006  2102GMT  2732m
59º 38.972N  18º 46.838W

RCM8 # 12302
Release RT661 # 321
Sediment trap # ML11804-01

Timing
2044 Pellet in water
2045 Buoyancy
2046 Sed trap
2047 RCM8
2053 Release
2101 Anchor gone

500kg 2 x railway wheel anchor.

Tracked using SAMS TT301 through PES fish single element. Descent 130m/min, ranged on bottom at 2127GMT, 2532m.

Mooring Deployment 4

STS Discovery # 16140  16th Oct 2006  0644  2856m
58º 51.968”N  20º 24.169”W
RCM8 # 3344
Release RT661 # 183
Sd trap ML11262-08

Timing
0618       Pellet and buoyancy
0620       Sed trap
0621       RCM8
0629       Release
0643       Anchor

Tracked using SAMS TT301 through PES fish single element. Descent 130m/min. Confirmed on bottom and static at 0711, range 2664m

Maclane Sediment Traps

Sediment traps were set up as indicated below. They were pressure washed prior to sailing and the tops covered with Clingfilm until deployment. Richard sanders carried out the bottle filling and programming. All units had new batteries fitted, both motor batteries and 9v backup. Rotations for bottle filling and alignment were carried out using the spare controller pack. Log files are listed in order of deployment.

ML11804-05
McLane Research Laboratories, USA
ParFlux 21-Cup Sediment Trap
Version: pst-21_1.c   S/N: ML11804-05

<1> Set Time        <5> Create Schedule
Is the rotator aligned to the open hole (Yes/No) [N] ? y

Clock reads 10/14/2006 21:21:07
Change time & date (Yes/No) [N] ? n

Existing deployment data file will be erased. Continue (Yes/No) [N] ? y

Enter new deployment schedule (Yes/No) [N] ? n

Schedule Verification

Event 1 of 22 = 11/22/2006 12:00:00
Event 2 of 22 = 12/06/2006 12:00:00
Event 3 of 22 = 12/20/2006 12:00:00
Event 4 of 22 = 01/03/2007 12:00:00
Event 5 of 22 = 01/17/2007 12:00:00
Event 6 of 22 = 01/31/2007 12:00:00
Event 7 of 22 = 02/14/2007 12:00:00
Event 8 of 22 = 02/28/2007 12:00:00
Event 9 of 22 = 03/14/2007 12:00:00
Event 10 of 22 = 03/28/2007 12:00:00
Event 11 of 22 = 04/11/2007 12:00:00
Event 12 of 22 = 04/25/2007 12:00:00
Event 13 of 22 = 05/09/2007 12:00:00
Event 14 of 22 = 05/23/2007 12:00:00
Event 15 of 22 = 06/06/2007 12:00:00
Event 16 of 22 = 06/20/2007 12:00:00
Press any key to continue.
Event 17 of 22 = 07/04/2007 12:00:00
Event 18 of 22 = 07/18/2007 12:00:00
Event 19 of 22 = 08/01/2007 12:00:00
Event 20 of 22 = 08/15/2007 12:00:00
Event 21 of 22 = 08/29/2007 12:00:00
Event 22 of 22 = 09/12/2007 12:00:00

Modify an event (Yes/No) [N] ? n
Current Header reads:

Deployment 42 Iceland Basin NE D312
ML11804_05
Do you want a different header (Yes/No) [N] ? n

System status:

10/14/2006 21:21:32  21.6 Vb  15 øC  aligned

Caution: Deployment will overwrite the EEPROM data backup cache.

Proceed with the deployment (Yes/No) [N] ? y

>>> Remove communication cable and <<<
>>> attach dummy plug. <<<
>>> Sediment trap is ready to deploy. <<<

<10/14/2006 21:21:35> Waiting for Event 01 of 22 @ 11/22/2006 12:00:00


ML11804-02
McLane Research Laboratories, USA
ParFlux 21-Cup Sediment Trap
Version: pst-21_1.c  S/N: ML11804-02

Éffffffffffffaaaaaaaaaaaaaaaaaaaaaaaaaaà
d Main Menu à
Éffffffffffffffffffffffffffffffffffffffff
 Sat Oct 14 21:30:15 2006

<1> Set Time  <5> Create Schedule
<2> Diagnostics  <6> Deploy System
<3> Fill Containers  <7> Offload Data
<4> Sleep  <8> Contacting McLane

Selection ? 6

Is the rotator aligned to the open hole (Yes/No) [N] ? y

Clock reads 10/14/2006 21:30:29
Change time & date (Yes/No) [N] ? n

Existing deployment dat erased. Continue (Yes/No) [N] ? y
Enter new deployment schedule (Yes/No) [N] ? n

Schedule Verification

Event 1 of 22 = 11/22/2006 12:00:00
Event 2 of 22 = 12/06/2006 12:00:00
Event 3 of 22 = 12/20/2006 12:00:00
Event 4 of 22 = 01/03/2007 12:00:00
Event 5 of 22 = 01/17/2007 12:00:00
Event 6 of 22 = 01/31/2007 12:00:00
Event 7 of 22 = 02/14/2007 12:00:00
Event 8 of 22 = 02/28/2007 12:00:00
Event 9 of 22 = 03/14/2007 12:00:00
Event 10 of 22 = 03/28/2007 12:00:00
Event 11 of 22 = 04/11/2007 12:00:00
Event 12 of 22 = 04/25/2007 12:00:00
Event 13 of 22 = 05/09/2007 12:00:00
Event 14 of 22 = 05/23/2007 12:00:00
Event 15 of 22 = 06/06/2007 12:00:00
Event 16 of 22 = 06/20/2007 12:00:00

Press any key to continue.

Event 17 of 22 = 07/04/2007 12:00:00
Event 18 of 22 = 07/18/2007 12:00:00
Event 19 of 22 = 08/01/2007 12:00:00
Event 20 of 22 = 08/15/2007 12:00:00
Event 21 of 22 = 08/29/2007 12:00:00
Event 22 of 22 = 09/12/2007 12:00:00

Modify an event (Yes/No) [N] ? n

Current Header reads:

Deployment 43 IB2 ML11804_02_D312_Final

Do you want a different header (Yes/No) [N] ? n

System status:

10/14/2006 21:30:45  21.5 Vb  15 øC  aligned

Caution: Deployment will overwrite the EEPROM data backup cache.

Proceed with the deployment (Yes/No) [N] ? y

>>> Remove communication cable and <<<
   >>> attach dummy plug. <<<
   >>> Sediment trap is ready to deploy. <<<

<10/14/2006 21:30:48> Waiting for Event 01 of 22 @ 11/22/2006 12:00:00
<10/14/2006 21:30:50> Sleeping . . .

ML11804-01
McLane Research Laboratories, USA
ParFlux 21-Cup
Version: pst-21_1.c  S/N: ML11804-01

Selection  ? 1
Clock reads 10/15/2006 14:34:19
Change time & date (Yes/No)
Enter date as MM DD YY HH MM SS
Enter year 2001 as 1, 01, 101, or 2001
Clock reads 10/15/2006 15:04:00
Change time & date (Yes/No) [N] ? n

Selection  ? 2
Press any key to pause/continue display, <X> to exit
10/15/2006 15:04:17 22.3 Vb 17 °C aligned
10/15/2006 15:04:18 22.3 Vb 17 °C aligned
10/15/2006 15:04:19 22.3 Vb 17 °C aligned
10/15/2006 15:04:20 22.3 Vb 17
10/15/2006 15:04:21 22.3 Vb 17 °C aligned
10/15/2006 15:04:22 22.3 Vb 17 °C aligned
10/15/2006 15:04:23 22.3 Vb 17 °C aligned
10/15/2006 15:04:24 22.3 Vb 17 °C aligned
10/15/2006 15:04:25 22.3 Vb 17 °C aligned
10/15/2006 15:04:26 22.3 Vb 17 °C aligned
10/15/2006 15:04:27 22.3 Vb 17 °C aligned
10/15/2006 15:04:28 22.3 Vb 17 °C aligned
10/15/2006 15:04:29 22.3 Vb 17 °C aligned
10/15/2006 15:04:30 22.3 Vb 17 °C aligned
10/15/2006 15:04:31 22.3 Vb 17 °C aligned
10/15/2006 15:04:32 22.3 Vb 17 °C aligned
10/15/2006 15:04:33 22.3 Vb 17 °C aligned
10/15/2006 15:04:34 22.3 Vb 17 °C aligned

McLane Research Laboratories, USA
ParFlux 21-Cup Sediment Trap
Version: pst-21_1.c  S/N: ML11804-01

Éfffffffffffffffffffffffffffffffffffffffffff»
* Main Menu  *
Éfffffffffffffffffffffffffffffffffff
Sun Oct 15 15:04:34 2006

<1> Set Time  <5> Create Schedule
<2> Diagnostics  <6> Deploy System
<3> Fill Containers  <7> Offload Data
<4> Sleep  <8> Contacting McLane

Selection  ? 5

Existing deployment data file will be erased. Continue (Yes/No) [N] ? y

Enter new deployment schedule (Yes/No) [N] ? y

Enter the number of events to program (0 to 22) ? 22

Éfffffffffffffffffffffffffffffffffff»
* Schedule Menu  *
Éfffffffffffffffffffffffffffffffffff

<1> Enter each event time
<2> Enter start date & interval
<3> Enter start date & end date
<M> Main Menu
Selection ? 2

Enter START date and time [10/15/2006 15:05:06] ? 11/22/2006 12:00:00

Enter interval

Days (0 to 365) ? 14
Hours (0 to 23) ? 0
Minutes (0 to 59) ? 0

Schedule Verification

Event 1 of 22 = 11/22/2006 12:00:00
Event 2 of 22 = 12/06/2006 12:00:00
Event 3 of 22 = 12/20/2006 12:00:00
Event 4 of 22 = 01/03/2007 12:00:00
Event 5 of 22 = 01/17/2007 12:00:00
Event 6 of 22 = 01/31/2007 12:00:00
Event 7 of 22 = 02/14/2007 12:00:00
Event 8 of 22 = 02/28/2007 12:00:00
Event 9 of 22 = 03/14/2007 12:00:00
Event 10 of 22 = 03/28/2007 12:00:00
Event 11 of 22 = 04/11/2007 12:00:00
Event 12 of 22 = 04/25/2007 12:00:00
Event 13 of 22 = 05/09/2007 12:00:00
Event 14 of 22 = 05/23/2007 12:00:00
Event 15 of 22 = 06/06/2007 12:00:00
Event 16 of 22 = 06/20/2007 12:00:00

---

Press any key to continue.12:00
Event 17 of 22 = 07/04/2007 12:00:00

McLane Research Labor
Event 18 of 22 = 07/18/2007 12:00:00
Event 19 of 22 = 08/01/2007 12:00:00
Event 20 of 22 = 08/15/2007 12:00:00
Version:
Event 21 of 22 = 08/29/2007 12:00:00

Is
Event 22 of 22 = 09/12/2007 12:00:00

Éeffffffffffffffffffffffffff

Modify an event (Yes/No) [N] ? n

Event 16 of
Éff
McLane Research Laboratories, USA

Enter
ParFlux 21-Cup Sedime
Existing deployment data file will be
10/14/2006 20:21:39 22.0 Vb 15
erased. Continue (Yes/No) [N] ? y

Enter new deployment schedule (Yes/No) [N] ? Schedule Verification
Event 1 of 22 = 11/22/2006 12:00:00

Event 2 of 22 = 12/06/2006 12:00:00

Event 3 of 22 = 12/20/2006 12:00:00
ParFlux 21-Cup Sed
Event 4 of 22 = 01/03/2007 12:00:00

Sys
Version: p
Event 5 of 22 = 01/17/2007 12:00:00

Éffí
Event 6 of 22 = 01/31/2007 12:00:00
vement will overwrite the
Event 7 of 22 = 02/14/2007 12:00:00

Event 8 of 22 = 0
Event 21 of 22 = 08/29/2007 12:00:00 Selection ? 1
Event 22 of 22 = 09/12/2007 12:00:00
Event 10 of 22 = 03/28/2007

Modify an event (Yes/No) [N] ? n
Ch
Event 11 of 2
Current Header reads:

Mooring IRM-3, deploy sept 19th 2005 on CAMP/LOCO/CIS04/25/2007 12:00:00_______
RV Pelagia cruise 64PE240, position 59 20.08 N 38 50.98 We Research
met de groeten aan Gert-Jan en Lukas.:00

Do you want a different header (Yes/No) [N] ? y
Event 19 of 22 = 08
Enter new header (three lines, 80 characters/line)

<1> Set Time <5>

> ML11804_01_D312 Iceland Basin Sed Trap 3 Mooring 44 <2

Do you want a different header (Yes/No) [N] ? n

System status:
Caution: Deployment will overwrite the EEPROM data backup cache.

Proceed with the deployment (Yes/No) [N] ? y

>>> Remove communication cable and <<<<
>>> attach dummy plug. <<<
>>> Sediment trap is ready to deploy. <<<

<10/15/2006 15:07:06> Waiting for Event 01 of 22 @ 11/22/2006 12:00:00

<10/15/2006 15:07:07> Sleeping . . .

ML11262-08

McLane Research Laboratories, USA
ParFlux 21-Cup Sediment Trap
with Compass and Tilt
Version: pst-21c4.c  S/N: ML11262-08

Press any key to pause/continue display, <X> to exit

10/15/2006 15:10:26  21.5 Vb  15øC  0øT  0øH  aligned
10/15/2006 15:10:30  21.5 Vb  15øC  0øT  0øH  aligned
10/15/2006 15:10:33  21.4 Vb  15øC  0øT  0øH  aligned
10/15/2006 15:10:36  21.4 Vb  15øC  0øT  0øH  aligned
10/15/2006 15:10:39  21.4 Vb  15øC  0øT  0øH  aligned
10/15/2006 15:10:42  21.4 Vb  15øC  0øT  0øH  aligned
10/15/2006 15:10:45  21.4 Vb  15øC  0øT  0øH  aligned
10/15/2006 15:10:48  21.4 Vb  15øC  0øT  0øH  aligned

McLane Research Laboratories, USA
ParFlux 21-Cup Sediment Trap
with Compass and Tilt
Version: pst-21c4.c  S/N: ML11262-08

ÉİÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍÍ»
Is the rotator aligned to the open hole (Yes/No) [N] ? y

Clock reads 10/15/2006 15:11:07
Change time & date (Yes/No) [N] ? n

Existing deployment data file will be erased. Continue (Yes/No) [N] ? y

Enter new deployment schedule (Yes/No) [N] ? n

Schedule Verification

Event  1 of  22 = 11/22/2006 12:00:00
Event  2 of  22 = 12/06/2006 12:00:00
Event  3 of  22 = 12/20/2006
Event  4 of  22 = 01/03/2007 12:00:00
Event  5 of  22 = 01/17/2007 12:00:00
Event  6 of  22 = 01/31/2007 12:00:00
Event  7 of  22 = 02/14/2007 12:00:00
Event  8 of  22 = 02/28/2007 12:00:00
Event  9 of  22 = 03/14/2007 12:00:00
Event 10 of  22 = 03/28/2007 12:00:00
Event 11 of  22 = 04/11/2007 12:00:00
Event 12 of  22 = 04/25/2007 12:00:00
Event 13 of  22 = 05/09/2007 12:00:00
Event 14 of  22 = 05/23/2007 12:00:00
Event 15 of  22 = 06/06/2007 12:00:00
Event 16 of  22 = 06/20/2007 12:00:0
Press any key to continue.cable and <<<
Event 17 of  22 = 07/04/2007 12:00:00ttach dummy plug. <<<
Event 18 of  22 = 07/18/2007 12:00:00eady to deploy. <<<
Event 19 of  22 = 08/01/2007 12:00:01:08:22> Waiting for Event 01 of 22 @ 1
Event 20 of  22 = 08/15/2007 12:00:00
Event 21 of  22 = 08/29/2007 12:00:00ing . . .
Event 22 of  22 = 09/12/2007 12:00:00

<10/1
Modify an event (Yes/No) [N]? Needed by operator.

Current Header reads:

Enter tilt sample interval [minutes] (43 to 1440)? 1440

System status:

10/15/2006 15:11:40  21.5 Vb  15øC  0øT  0øH aligned

Caution: Deployment will overwrite the EEPROM data backup cache.

Proceed with the deployment (Yes/No) [N]? y

>>> Remove communication cable and <<<
>>> attach dummy plug. <<<
>>> Sediment trap is ready to deploy. <<<

<10/15/2006 15:11:50> Waiting for Event 01 of 22 @ 11/22/2006 12:00:00


Acoustic Releases.

All the releases were wire tested on the CTD prior to deployment.

Build sheets below, except for # AR861 325, settings as below.

Wire test 2200m, diagnostics and release checked.

12KHz CAF

Arm ranging  14D5

RELEASE  ARM + 1455

RELEASE WITH PING  ARM + 1456

PING ON  ARM + 1447

PING OFF  ARM + 1448

DIAGNOSTIC  ARM + 1449
RECEIVER MODE  B=12KHZ

A=8KHZ (OLD)
**Ocean Engineering Division**  
**UKORS**  
**MORS SYSTEMS**  
**Operational Sheet**

**CRUISE**  
D312  
**DATE**  
23 Oct 06

**TYPE**  
RT 661 B1S

**FUNCTION**  
RELEASE TRANSPONDER RT661 - B

**SERIAL No.**  
183

**Delivery**  
JULY 2001

<table>
<thead>
<tr>
<th>Function / Code</th>
<th>TT301</th>
<th>Reply</th>
<th>Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td>WINDOW</td>
<td>EC2A</td>
<td>FT0</td>
<td>Wait time sec. Active sec</td>
</tr>
<tr>
<td>ON FR1 -FR2</td>
<td>EC2B</td>
<td>FT0</td>
<td></td>
</tr>
<tr>
<td>OFF FR1 -FR2 - PINGER EC2C</td>
<td>FT0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>RELEASE 1 (W)</td>
<td>EC85</td>
<td>FT0-FT5</td>
<td></td>
</tr>
<tr>
<td>RELEASE 2 (W)</td>
<td>EC86</td>
<td>FT0-FT6</td>
<td></td>
</tr>
<tr>
<td>DIAGNOSTIC(W)</td>
<td>EC87</td>
<td>FT0-FT7</td>
<td>Measure delay sec Vert offset sec</td>
</tr>
<tr>
<td>PYROTECHNIC(W)</td>
<td>EC91</td>
<td>FT0-FT11</td>
<td>Wait time sec Pulse s</td>
</tr>
<tr>
<td>PINGER (W)</td>
<td>EC94</td>
<td>FT0-FT4</td>
<td>Pulse width Ms Recur sec</td>
</tr>
<tr>
<td>2 SEC PINGER</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Power Configuration**  
3 banks of 6 Lithium D installed for  
1 bank of 1 Alkaline PP3 installed for

**Power partition**  
Standby - power motor

**Diagnostic Measure**  
t(FT7) - t(FT0) - 3s (13 s in horizontal position)

**Cells voltage (V)**  
Diagnostic measure x 4.1

**Batteries fitted**  
YES - ALKALINE - 30TH JULY 06

**Wire test**  
:Tested to 2200m

**Functions check**  
:Diagnostics and release

**Deployed Mooring**  
: STS Discovery # 16140  
Date : 16 oct

**Recovery limit**  
: Date : 

**Recovered**  
: Date :

**COMMENTS ON CONDITION**  
Good condition, no problems

**ACTIONS REQUIRED AT LABORATORY**
Cruise D312  

Date 23 Oct 2006

Type RT 661 B2S
Function Release Transponder RT661 - B
Serial No. 321
Delivery FEB 96

Int Frequency  
FR1 = 9.0kHz  
FR2 = 13.0kHz  
FR3 = 10.5kHz  
FR4 = 14.5kHz  
FT0, FT5, FT6, FT7, FT8, FT9, FT10, FT11, FT15 = 08.0kHz

<table>
<thead>
<tr>
<th>Function / Code</th>
<th>TT301</th>
<th>Reply</th>
<th>Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td>WINDOW</td>
<td>C446</td>
<td>FT0</td>
<td>Wait time, sec, Active sec</td>
</tr>
<tr>
<td>ON FR1 - FR2</td>
<td>C447</td>
<td>FT0</td>
<td></td>
</tr>
<tr>
<td>OFF FR1 - PINGER</td>
<td>C448</td>
<td>FT0</td>
<td></td>
</tr>
<tr>
<td>RELEASE 1 (W)</td>
<td>C485</td>
<td>FT0</td>
<td>FT0 - FT5</td>
</tr>
<tr>
<td>RELEASE 2 (W)</td>
<td>C486</td>
<td>FT0</td>
<td>FT0 - FT6</td>
</tr>
<tr>
<td>DIAGNOSTIC (W)</td>
<td>C487</td>
<td>FT0</td>
<td>FT0 - FT7 Measure delay, sec, Vert offset sec</td>
</tr>
<tr>
<td>PYROTECHNIC (W)</td>
<td>C491</td>
<td>FT0</td>
<td>FT0 - FT11 Wait time, s, Pulse s</td>
</tr>
<tr>
<td>PINGER (W)</td>
<td>C470</td>
<td>FT0</td>
<td>FT0 - FT4 Pulse width, Ms, Recur sec</td>
</tr>
</tbody>
</table>

Power Configuration  
3 banks of 6 ALKALINE D installed for D312  
1 bank of 1 Alkaline PP3 installed for D312

Power partition  
Standby - power motor

Diagnostic Measure  
t(FT7) - t(FT0) - 3s (13 s in horizontal position)

Cells voltage (V)  
Diagnostic measure x 4.1

Batteries fitted  
YES 29TH JULY 2006

Wire test  
2200m

Functions check  
Diagnistics and Release

Deployed Mooring  
STNE Discovery # 16139  
Date: 16 Oct 06

Recovery limit  
Date:

Recovered  
Date:

Comments on condition

Actions required at laboratory

68
CRUISE: D312  DATE: 23 Oct 06

TYPE: RT 661 B2S-DDL
FUNCTION: RELEASER TRANSPONDER RT661 - B
SERIAL No.: 440
Delivery: FEB 2001

Int Frequency: Reply Frequency
FR1 = 9.0kHz
FR2 = 10.0kHz
FR3 = 14.5kHz
FR4 = 15.5kHz
FT0, FT5, FT6, FT7, FT8, FT9, FT10, FT11, FT15 = 12.0kHz

Function/Code | TT301 | Reply | Specifications
--- | --- | --- | ---
WINDOW | EC77 | FT0 | Wait time sec Alert sec
ON FR1- FR2 | EC78 | FT0 |
OFF FR1-PR2-PINGER | EC79 | FT0 |
RELEASE 1 (W) | EC85 | FT0 - FT5 |
RELEASE 2 (W) | EC86 | FT0 - FT6 |
DIAGNOSTIC (W) | EC87 | FT0 - FT7 Measure delay sec Vert offset sec |
PYROTECHNIC (W) | EC91 | FT0 - FT11 Wait time s Pulse s |
PINGER (W) | EC94 | FT0 - FT4 Pulse width Ms Recur sec |

Power Configuration: 3 banks of 6 ALKALINE D installed for D312
Standby - power motor

Power partition: 1 bank of 1 Alkaline PP3 installed for D312

Diagnostic Measure: t(FT7) - t(FT0) - 3s (13 s in horizontal position)
Cells voltage (V): Diagnostic measure x 4.1

Batteries fitted: YES - 29TH JULY 2006

Wire test: 2200m

Functions check: Diagnostics and Release
Deployed Mooring: STNW Discovery # 16137 Date: 16 Oct 06

Recovery limit: Date:
Recovered: Date:

COMMENTS ON CONDITION

ACTIONS REQUIRED AT LABORATORY
Wyville Thomson Ridge mooring turn-around - Paul Provost, Terry Edwards, Toby Sherwin, Mark Inall, Colin Griffiths

The LR-ADCP mooring was successfully serviced on the 29th October 2006. Recovery went very smoothly in calm conditions with a moderate swell. The mooring was released at 1047Z, diagnostic 5092, ascent speed was ~100m/min and the mooring was spotted on the surface at 1056Z. The mooring was recovered on the starboard side. The mooring had been deployed in the Ellett Gully, the first deployment was from CD176 in October 2005 and subsequently serviced from RV Scotia in May 2006. The mooring components were all in good condition. The LR-ADCP was removed from the S/S sphere, the instrument was still pinging and the data was downloaded. First look at the data indicated a good data set for the duration of the deployment over a range of ~500m. The batteries (4 packs) were changed and the instrument set for deployment. The batteries were also changed in the acoustic release, the release was wire tested on the CTD prior to deployment, diagnostic 5309. The mooring was deployed over the stern using both gantry cranes and a BOSS slip hook for the S/S sphere and then the 1000Kg anchor. The deployment took 4 minutes, (Speedy Applied Mooring Services Ltd); the anchor was released at 1601Z. The acoustic release was tracked during the descent. The anchor landed on the bottom at ~1608Z. The descent speed was ~240m/min.

All instruments were provided from the NMEP with mooring hardware from the S&M division, UKORS, NOCS, Southampton. Ancillary data from the LR_ADCP included temperature, pressure, pitch, roll and heading.
The highest currents measured were during the early part of the deployment in the early summer. These currents coincided with near zero temperatures. The highest speed measured was ~191 cm/s (269°M) from bin 11, ~127m above the seabed at 1047Z 10/6/2006.

The mooring performed very well in this high current regime. The maximum tilt measured by the LR-ADCP was ~20° from the vertical.
The flow was predominantly westward in the lower bins as can be clearly seen from the scatter plots. The top row is from bin 1 to bin 8, 2d row bin 9 to bin 16 etc…

The scale of each axis is -200cm/s to 200cm/s E-W & N-S, the bin length was 8m with a blanking distance of ~7m. The data return from the upper 6 bins is very patchy, bins 59 to 64.

Figure 6: Wyville Thomson gully LR-ADCP mooring, May to October 2006, tilt readings.

Figure 7: Wyville Thomson gully LR-ADCP mooring, May to October 2006, direction of flow.
Table 1: Wyville Thomson gully LR-ADCP mooring and instrument set-up details.

<table>
<thead>
<tr>
<th>Mooring deployment details</th>
<th>Instrument set-up for ADCP</th>
</tr>
</thead>
<tbody>
<tr>
<td>Position: 60º 15.00’ N 008º 54.99’ W</td>
<td>High power, long range mode Time of First Ping: 29th October 2006 15:00 GMT</td>
</tr>
<tr>
<td>Depth: 1218m</td>
<td>Ensemble interval: 30 mins</td>
</tr>
<tr>
<td>Date: 29th Oct 2006</td>
<td>Number of depth cells: 64</td>
</tr>
<tr>
<td>Time: 16:01 GMT</td>
<td>Pings per Ensemble: 23</td>
</tr>
<tr>
<td></td>
<td>Depth Cell Size: 8 m</td>
</tr>
<tr>
<td></td>
<td>Blank After Transmit: 7.04 cm</td>
</tr>
<tr>
<td></td>
<td>Frequency: 76.8 kHz</td>
</tr>
<tr>
<td></td>
<td>Expected battery life (4 packs): 180 days</td>
</tr>
</tbody>
</table>
Figure 8: Mooring components being moved into place prior to deployment of the mooring over the stern.

Table 2: Mooring set-up, equipment and chain lengths.

<table>
<thead>
<tr>
<th>Item</th>
<th>Details</th>
<th>Height above seabed</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rope (30mm 3-strand polyprop)</td>
<td>7.5m, soft eye splice, Taped to frame</td>
<td></td>
</tr>
<tr>
<td>5/8” oval link shackle</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Item</td>
<td>Manufacturer</td>
<td>Length</td>
</tr>
<tr>
<td>------------------------------------------</td>
<td>-----------------------</td>
<td>--------</td>
</tr>
<tr>
<td>RDI ADCP Workhorse</td>
<td>RD Instruments</td>
<td>17m</td>
</tr>
<tr>
<td>49” syntactic sphere</td>
<td>Floatation Technologies</td>
<td>16m</td>
</tr>
<tr>
<td>2 shackles</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Titanium swivel (SWL 3T)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>shackle</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5/8” oval link</td>
<td></td>
<td></td>
</tr>
<tr>
<td>shackle</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5/8” long link chain</td>
<td>Galvanised, 10m</td>
<td></td>
</tr>
<tr>
<td>shackle</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Acoustic release Oceano RT661 B2S</td>
<td></td>
<td>6m</td>
</tr>
<tr>
<td>20mm oval link</td>
<td></td>
<td></td>
</tr>
<tr>
<td>shackle</td>
<td></td>
<td></td>
</tr>
<tr>
<td>½” long link chain</td>
<td>Yellow, 5m</td>
<td></td>
</tr>
<tr>
<td>shackle</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Anchor clump 1000kg</td>
<td></td>
<td>0m</td>
</tr>
</tbody>
</table>
Figure 9: Final preparation of the sub-surface syntactic sphere housing the LR-ADCP.

Figure 10: Big Splash, then 6 minutes later some poor echinoderm is toast!
The ships on board data logging system recorded.

- Trimble DS4000 GPS navigation data
- Ashtech ADU5 attitude and navigation data
- Ashtech G12 GPS navigation data

These were all corrected with a differential GPS output from the Fugro SeaStar service. The em log, ships gyrocompass and winch data were also recorded, in addition to the surfmet package of metrology and surface sampling instruments.

Vessel Mounted RDI 150khz and 75khz ADCPs were recorded as stand alone logging instruments and data transferred to the networked work area. Data from the ships wave recorder was also handled in this way.

Scientific computing and data storage took place on networked systems with a data storage area served to all users. The on board systems were used for Pstar data processing with Matlab and Uniras licensed packages having been setup prior to the cruise.

Printing from the normally reliable networked colour laser printer failed roughly half was through the cruise. The fault was diagnosed as requiring a manufacturer repair. The fallback of using a networked monochrome laser printer and colour inkjet printer proved adequate, however a spare colour laser printer would be an advantage in the future, it was noted that the current printer has a total print usage in excess of seventy five thousand pages.

All instrumentation performed well with no data logging issues being apparent during the cruise. We suffered one interruption to the Ashtech ADU5 logging from 06:295:00:39:24 to 06:295:09:41:48, the system was eventually restarted and the problem did not reoccur again.
4. SCIENTIFIC INVESTIGATIONS

Lowered CTD Data - Colin Griffiths, Jane Read

**CTD Sensors**

The CTD used through cruise D312 was a SeaBird 9/11+ with 24-way rosette and additional oxygen, fluorometer, transmissometer, BBRTD, and altimeter sensors.

**SBE9/11+ CTD system with 24 10l OTE Bottles**

SBE9+ Underwater Unit 09P37898-0782

SBE11+ Deck Unit 11P-19817-0495

SBE32 24way Rosette 32-0344

SBE Pressure: 94756  Calibrated on: 15 Apr 2004

**Primary T & C Sensors (On Vane)**

SBE3 Temperature: 03P-2728 Calibrated on 15/03/06

SBE4 Conductivity: 04C-2851 Calibrated on 09/06/06

SBE5 Pump: 053962 (3K)

**Secondary T & C Sensors**

SBE3 Temperature: 03P-4490 Calibrated on 11/06/06

SBE4 Conductivity: 04C-2450 Calibrated on 15/06/06

SBE5 Pump: 054164 (3K)

**Additional Sensors**

SBE 43 Oxygen: 0612  Calibrated on 24/11/05

Chelsea Aqua 3 Fluorometer: 088108 Calibrated on 17/11/04

Transmissometer: 04-4223-001  Calibrated on 08/12/04
Data processing

CTD data processing followed standard paths used on previous hydrographic cruises. After each cast data were saved to the deck unit PC and transferred over the network to the unix data disk at /data32/d312/ctd. The logging software output four files per CTD cast named by Discovery station number with the following extensions: .dat (raw data file), .con (data configuration file), .BL (contained record of bottle firing locations), and .HDR (a header file).

The SBE Seasave Win32 V 5.35 software was used to perform initial processing and was followed by Pstar processing to clean and reduce the data to 2db. SeaBird CTD processing routines were used as follows.

**DatCnv**: converted raw CTD data in the .dat file from engineering units using the calibration information provided in the configuration file (.con). Files output consisted of binary .cnv files containing the 24hz down and up casts and .ros files containing values at the time each Niskin bottle was fired.

**AlignCTD**: used to shift the dissolved oxygen sensor output relative to the pressure data by 5 seconds to compensate for lags in the sensor response time. The routine overwrites the oxygen variable in the .cnv file.

**WildEdit**: de-spikes data by calculating the standard deviation of a set number of scans. Two passes through the data were made, both taking the mean of 500 scans. Values outside two standard deviations from the mean on the first pass and ten standard deviations from the mean on the second pass were flagged as bad. Output was written to the .cnv file.
**CellTM:** removes the effect of thermal ‘inertia’ on the conductivity cells using the algorithm:

\[
\begin{align*}
\Delta t &= t_i - t_{i-7} \\
ctm_i &= -b \cdot ctm_{i-7} + a \cdot \partial c \partial t \cdot \Delta t \\
c_{cor,i} &= c_{meas,i} + ctm_i \\
a &= \frac{2\alpha}{7\Delta \beta + 2} \\
b &= 1 - \frac{2a}{\alpha} \\
\partial c \partial t &= 0.8 \times (1 + 0.006 \times (t_i - 20))
\end{align*}
\]

where \(\alpha\), the thermal anomaly amplitude, was set at 0.03 and \(\beta\), the thermal anomaly time constant, was set at 1/7 (the SeaBird recommended values for SBE911+ pumped system). \(\Delta\) is the sample interval (1/24 second), \(\Delta t\) is the temperature (t) difference taken at a lag of 7 sample intervals. \(c_{cor,i}\) is the corrected conductivity at the current data cycle (i), \(c_{meas,i}\) the raw value as logged and \(ctm_i\) is the correction required at the current data cycle, \(\partial c \partial t\) is a correction factor that is a slowly varying function of temperature deviation from 20 °C.

**Translate:** converts the binary .cnv files into ASCII format .cnv files for conversion to Pstar binary format.

Pstar processes were incorporated into 3 scripts: ctd0, 1 and 2. These can be summarised as follows:

**ctd0:** transferred data from the .cnv ASCII file to Pstar binary format in file ctdnnnnn.24hz, where nnnnn is the 5 digit Discovery station number. The position at the bottom of the cast, obtained by the user from the rvs data stream ‘bestnav’, was entered into the header, together with other relevant information taken from the header of the .cnv file.

**ctd1:** converted cond & cond2 from S/m to mS/cm, smoothed press, temp, cond, temp2, cond2 with a running 5 point median deleting values greater than 5, 0.1, 0.1, 0.1, 0.1 respectively from the median. Results were output to the .24hz file and averaged to 1 second intervals in the file ctdnnnnnn.1hz
Processing continued using the .1hz file with interpolation on pressure and calculation of salinity, potential temperature and density. Data were further averaged to 10 second intervals in the file ctdnnnnn.10s

**ctd2**: truncated the start and end of the .1hz cast to the .ctu file using data cycles provided by the user after manual inspection of the .1hz file, the down cast was also extracted and averaged to 2db in the .2db file.

Data were then plotted manually for visual inspection of profile quality. On this cruise the data were clean and no further editing was necessary.

Files were created to compare CTD and bottle sample values for calibration of the CTD sensors and analysis of geochemical data using two scripts as follows.

**fir0**: imported the .ros file to Pstar file firnnnnn and merged relevant data from the .10s CTD file for each bottle fired. Data were also transferred from the RVS level C ‘winch’ data stream to Pstar file winnnnnn. Note that no winch data were available for the first six casts.

**sam0**: combined data from the fir file with bottle sample data in new file samnnnnnn

No samples were available for the first cast, 16126, because the rosette failed to fire. Otherwise sample values for salinity, dissolved oxygen and the nutrients nitrate+nitrite, phosphate and silicate were provided in various formats. Excel files were exported in .csv format: ‘strings’ was used to replace dos with unix characters in .txt files. Unique identifying sample numbers were generated for nutrient data (last three digits of the station number and a two digit Niskin bottle number). Data were then read into Pstar format using pascin. The sample number was used as a control variable to enter the sample values into the sam file using the program ppaste. The resulting sam files were then used to calibrate the CTD conductivity and dissolved oxygen sensors.

A total of 65 stations were worked, 17 on the Ellett Line extension, 21 on the Ellett Line, 15 on Line ‘G’, 3 at sediment trap sites, 1 after the turbulence experiment and 8 across the Ellett Gully in the Wyville Thomson Ridge (Table 3).
Table 3: *RRS Discovery* cruise 312 CTD Station List.

<table>
<thead>
<tr>
<th>Stn. No.</th>
<th>Name/ comment</th>
<th>jday</th>
<th>date</th>
<th>Start time hhmm</th>
<th>End time hhmm</th>
<th>Lat. ° N ' N</th>
<th>Lon. ° W ' W</th>
<th>Water depth (m)</th>
<th>Max. wire out (m)</th>
<th>Min. dist. off bot.</th>
<th>Max. press</th>
<th>Add. notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>16126</td>
<td>IB21s</td>
<td>285</td>
<td>12/10</td>
<td>1044</td>
<td>1144</td>
<td>63</td>
<td>8.28</td>
<td>19</td>
<td>54.76</td>
<td>-</td>
<td>1036</td>
<td>5</td>
</tr>
<tr>
<td>16127</td>
<td>IB22s</td>
<td>285</td>
<td>12/10</td>
<td>1840</td>
<td>1905</td>
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**mooring recovery**

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**mooring deployment**

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86
Notes: A = aluminium samples, P = POC and chl a samples, Z = zooplankton net. All CTDs were sampled for salinity, dissolved oxygen and macro-nutrients no2+3, po4, si02. IB = Iceland Basin, G = shelf line G, W = Wyville Thomson Ridge.

**CTD conductivity sensor calibration**

Salinity samples were used to calculate conductivity for each bottle value. Differences between bottle and CTD conductivity were plotted by station (Figure 11). There was a significant offset between the two CTD sensors, and only the primary sensor (on the fin) was calibrated. Figure 11 also shows offsets with time, with residuals varying from about -0.003 to +0.002. The sequence of stations was therefore divided into segments and, excluding outliers, the mean conductivity ratio (bottle/CTD) calculated for each segment. The resulting ratios (Table 4) were used to correct the CTD data. Following calibration the new bottle-CTD conductivity and salinity residuals were calculated and plotted against station (Figure 12) and pressure (Figure 13). Salinities are believed to be good to better than 0.002.

![Figure 11: Bottle-CTD conductivity residuals vs station no.](image_url)
Table 4: Conductivity ratio.

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<th>standard deviation</th>
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<tr>
<td>16188 - 16194</td>
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**Dissolved oxygen**

Differences between oxygen bottle samples and CTD sensor data were plotted against station (Figure 14). This showed a significant offset between the two and a noticeable drift with time. Unfortunately only two samples per cast were collected on the last 24 casts making it difficult to distinguish between scatter and drift. A simple straight line fit between bottle and CTD oxygen was estimated ignoring outliers and bias to shallow stations:

\[
\text{new oxygen} = \text{CTD oxygen} \times 0.63 + 51.6
\]

The resulting residuals were plotted against station (Figure 15) and a series of offsets estimated to make a final correction (Table 5). Final residuals were plotted against station (Figure 16) and pressure (Figure 17).
Figure 16: Final bottle-CTD oxygen residuals vs station no.

Figure 17: Final bottle-CTD oxygen residuals vs pressure.

Table 5: Oxygen correction.

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<td>16171 - 16194</td>
<td>8.</td>
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**Salinity Bottle Samples** - *Mark Barham and Phil Wallhead*

Salinity samples were drawn from Niskin bottles mounted on the CTD rosette at depths determined by the PSO or Watch Leader. The Niskin bottles were typically fired away from salinity gradients in an attempt to gain a stable measurement. The sampling process involved rinsing then filling the 200 ml sample bottles with their respective sample water, drying the inside of the bottle neck and plastic insert, then sealing the sample with both the insert and bottle screw top.

A Guildline Autosal salinometer (model 8400B, serial no. 60839) was installed in the controlled temperature laboratory maintained at 21°C. The manual quotes a successful operating temperature range between 4°C below and 2°C above the bath temperature, the preferred temperature being in the middle of this range. A thermometer attached to the side of the salinometer was used to measure temperature within the constant temperature (CT) lab, which varied between 21.5°C and 22°C. Salinity samples were stored in the CT lab. and left for at least 24 hours prior to analysis. The salinometer was stable and generally behaved well for the duration of the cruise.

OSIL’s Autosal software, Softsal, was used throughout. The software worked well and the stability achieved, determined by monitoring the standard deviation of salinity measurements, was good. With only a few exceptions, the bottle samples were determined to a precision greater than 0.001. There are a couple of points worth noting about using this software however; firstly the software encourages the operator to re-trim the salinometer after each standardisation to standard seawater. This is almost certainly because the measured salinity standard is not recorded in the output file (the second point to note), so no post measurement offset can be made. OSIL’s latest software appears to overcome this limitation and furthermore is designed to be directly compatible with spreadsheet packages like Excel. Standardisation of Autosal was performed using IAPSO Standard Seawater (batch no. P145, $K_{15}$ value 0.99981) and was done, as mentioned above, prior to the analysis of each crate. Standard seawater samples were also analysed at the end of every crate as a quality check. A minor problem in the form of a computer fault occurred while analysing sample 670 from station 16163. The computer was re-booted which appeared to rectify the problem. The sample was re-analysed and the crate completed under a different file name. On a couple of occasions the computer also shutdown by itself, a reason for which was not found. Analysis was automatically saved and the operators were able to start from last analysed sample.
Salinity values were transferred from the PC running Autosal in the CT lab. to a laptop where the salinity results were copied into an Excel spreadsheet. There is a slight drift in the data as well as a dip that occurs between stations 16143 and 16148 (Figure 11, in the previous section). This dip cannot be explained by operator error nor does it occur within a single crate suggesting the problem may lie in the CTD sensor calibration.

**Underway data - Jane Read**

The surfmet package worked uninterrupted throughout the cruise logging water temperature, conductivity, fluorescence, transmittance, air pressure, temperature and humidity, Photosynthetically active radiation (par) incoming irradiance (tir), wind speed and direction. Data were transferred from the RVS level C ‘surfmet’ data stream to Pstar and processed using a set of four scripts:

smtexec0: transferred data from the RVS level C ‘surfmet’ data stream to Pstar. Fluorescence and transmittance were scaled and data output to the file smt31201.raw

smtexec1a: edited data on time and pressure spikes, calibrated pressure, ppar, spar, ptir, humidity, air temperature and transmittance with the manufacturers coefficients. Spikes of 0.1, 0.1, 0.05, 0.005, 0.005, and 1 from a 5 point running median were deleted from temp_h, temp_m, cond, fluor, trans and airtemp respectively. GPS4000 position information was added and the data averaged to 2 minutes in file smt31201.av

smtexec1b: used the a-ghdg information to correct the wind direction for gyro error in file smt31201.hdg

smtexec2: corrected the wind speed and direction for vessel heading to obtain true wind speed and direction in the file smt31201.met.

Raw depth information logged by the precision echosounder (10 kHz) system was obtained from the RVS level C ‘ea500d1’ data stream using the script simexec0 and output to the Pstar file sim31201. Corrected depths were obtained from the RVS level C ‘pro_dep’ stream and output to the file sim31201.cal.
Figure 18: From top to bottom, wind speed (m/s), air pressure (mbar), PAR (raw mV) and echosounder depth (m) for the duration of the cruise.

150 kHz Vessel Mounted ADCP (VM-ADCP), ship’s attitude and position information
– Jane Read and Phil Wallhead

To obtain meaningful water velocities from the vessel-mounted acoustic Doppler current profiler, the ADCP data need to be corrected for the ship’s direction, speed and attitude. A number of parallel processes are run to combine the required information. Position, gyro-heading and attitude information were transferred from the RVS level C data streams to Pstar files daily and processed as described below.

Ship’s position and navigation data

The ship’s best determined position was calculated by the RVS process ‘bestnav’. The main data source was the ships GPS Trimble 4000 system, which provides the most accurate
position, determined on previous cruises to be ~1.0 m for the GPS4000 system compared to ~2.0 m for the G12 system.

Data were transferred daily from the RVS level C ‘bestnav’ file to the Pstar absolute navigation file ‘abnv3121’ for use in Pstar processing. Gps_4000 data were also transferred daily. The Pstar execs used were:

navexec0: transferred the RVS level C ‘bestnav’ data stream to Pstar format. Ship’s velocities were calculated from position and distance run calculated after appending to the master abnv3121 file.

gp4exec0: transferred the RVS level C ‘gps_4000) data stream to Pstar format. Data with pdop outside the range 0-7 was removed. Further edits were made to remove outliers and gaps interpolated before the file was appended to the master file gp431201 and distance run calculated. A 30 second average file gp431201.30sec was created.

**Ships heading and attitude**

Spot gyro heading data were fed into the 150 kHz ADCP transducer deck unit where they were incorporated into the individual ping profiles to correct the velocities to earth coordinates before being reduced to 2 minute ensembles. The gyro instrument is the most reliable direction indicator on the ship and applying the correction to individual profiles is more accurate than correcting averaged ensembles. However, the gyro suffers from drift when the ship manoeuvres and therefore needs correcting with the ships attitude. Ashtech data are not used directly for correcting the ship’s heading because the data stream is unreliable and suffers gaps and drop outs. Rather, they are used to correct the gyro heading.

Gyro data were transferred daily using the script gyroexec0.

gyroexec0: transferred data from the RVS level C ‘gyronmea’ stream to Pstar format. Headings outside the range 0-360° were deleted and the file appended to the master gyr31201 file.

The ship’s attitude was measured every second by the 3D GPS Ashtech ADU2 navigation system. Four antenna, two on the boat deck, two on the bridge top, measured the phase difference between incoming satellite signals from which the ship’s heading, pitch and roll
were determined. Configuration settings from previous calibrations (April 2001) were used throughout the cruise. These were:

Adjusted relative antenna positions (m), which require no pitch or roll offset angle.

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<th>Z(U)</th>
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<tr>
<td>1-4 vector</td>
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<td>6.431</td>
<td>-4.193</td>
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</table>

Ashtech data were read from the RVS level C binary stream ‘gps_ash’ into Pstar and used to calibrate the gyro heading information as follows.

ashexec0: transferred data from the RVS level C ‘gps_ash’ data stream to Pstar binary file ash312nn, where nn is incremented daily.

ashexec1: merged ashtech and gyro heading data and calculated the ashtech – gyro heading difference (a-ghdg). All values were set between -180 – 180°

ashexec2: edited the data outside the ranges

- heading 0 - 360
- pitch -5 - 5
- roll -7 - 7
- attitude flag -0.5 - 0.5
- measurement RMS error 0.00001 - 0.01
- baseline RMS error 0.00001, 0.1
- ashtech – gyro heading -7, 7

Heading differences greater than 1.0° from a 5 point running median were removed. Data were then averaged to 2 minute intervals and further edited to remove data cycles where
Results were merged with the gyro file and ships velocities calculated astoundingash3: appended the daily file to a master file ash312smt.ave for use in meteorological data processing.

During the cruise a number of short gaps (minutes) occurred, however, there was one long gap on 22 October (day295) when ashtech data were unavailable for a 9 hour period. Occasional spikes exist in the data. These have not been deleted and may give rise to spurious currents.

**Vessel mounted 150 kHz acoustic Doppler current profiler**

The 150 kHz vessel mounted acoustic Doppler profiler (VM-ADCP) was operated and logged throughout the cruise. The transducer unit, serial number 34 with frequency 153 kHz was installed in the hull 1.75 m to port of the keel, 33 m aft of the bow at the waterline and at an approximate depth of 5 m depending on the trim of the ship. Data were logged using IBM Data Acquisition Software (DAS) version 2.48 with profiler software 17.10. The instrument was configured to sample over 120 second intervals with 96 bins of 2² m depth, using pulse length 4 m and blank beyond transmit of 4 m. Two configuration files were set up, one for water tracking only, the other for bottom tracking in shallow water.

On setting sail from Reykjavik the ADCP logged in bottom track mode. At the shelf edge on day 286/02:18 this was switched to water tracking mode. On the Scottish continental shelf bottom tracking was switched back on, day 299/17:30. Water tracking mode was resumed for passage to the Wyville Thomson Ridge and returned to bottom tracking on day 301/05:00.

Data were recorded on an AP PC and like all PC’s the clock lost time steadily throughout the cruise at approximately 4 seconds per day. This was corrected during the data processing.

The ADCP data were logged continually by the RVS level C. From there they were transferred once a day to the Pstar processing system. Standard processing was used, thus; the
clock error was corrected, the gyro heading was corrected using the Ashtech heading information, the velocities were calibrated for misalignment angle and scaling and finally corrected for ships velocity and converted to absolute velocities using the ships position from the absolute navigation files. Scripts used were:

adpexec0: transferred data from the RVS level C "adcp" data stream to Pstar. The data were split into two; "gridded" depth dependant data were placed into "adp" files while "non-gridded" depth independent data were placed into "bot" files. Velocities were scaled to cm/s and amplitude by 0.42 to db. Nominal edits were made on all the velocity data to remove both bad data and to change the DAS defined absent data value to the Pstar value. The depth of each bin was determined from the user supplied information.

adpexec1: created a file of time corrections that was merged, linearly interpolated and added to time in (both) the adcp files. This corrected the clock drift problems caused by the pc logging of the ADCP data.

adpexec2: merged the adcp data (both files) with the ashtech a-ghdg created by ashexec2. The adcp velocities were converted to speed and direction so that the heading correction could be applied and then returned to east and north. Note the renaming and ordering of variables.

adpexec3: applied the misalignment angle, $\phi$, and scaling factor, $A$, to both adcp files. The adcp data were edited to delete all velocities where the percent good variable was 25% or less. Again, variables were renamed and re-ordered to preserve the original raw data.

adpexec4: merged the adcp data (both files) with the absolute navigation file created by navexec0. Ship's velocity was calculated from the 2 minute positions and applied to the adcp velocities. The end product was the absolute velocity of the water.

*Calibration for misalignment angle and scaling factor*

The weather at the beginning of the cruise was poor, so no particular attempt was made to calibrate the ADCP misalignment angle and scaling factor. The long passage across the Icelandic continental shelf was examined for periods of steady steaming. However, speed varied significantly and no sensible numbers could be obtained. In the end the mean was
taken of two previous calibrations obtained on cruises D306 and D309, giving a misalignment angle of 0.6610 and scaling factor of 1.000.

The weather during the cruise was fairly bad so the data were generally poor quality with characteristic large velocities in the direction of travel, believed to be caused by air bubbles beneath the hull. However some data appeared good, and the outstanding feature of the cruise was the presence of a large anticyclonic eddy in the Iceland basin in the location of the four sediment trap moorings. (Figure 19).

![Figure 19](image)

Figure 19: 150 KHz VM-ADCP vectors at a depth of ~149 m. The feint red dotted circle highlights a clear anticyclonic eddy signature in the region of the sediment trap mooring deployments.

Note that the depth of the mid-point of each bin is determined by the formula:

Distance from the surface to the centre of the first bin = [blank beyond transmit] + [depth cell] + ([transmit pulse length] – [depth cell]) / 2 + [transducer depth]
For [blank beyond transmit] = 4 m
[depth cell] = 4 m
[transmit pulse length] = 4 m
[transducer depth] = 5 m
giving a mid-bin depth range of 13-393 m.

75 kHz Vessel Mounted ADCP (VM-ADCP) data processing - Mark Inall

OS75 configuration

RRS Discovery is fitted with an RD Instruments 75kHz Ocean Surveyor ADCP (Transducer SN 2011). Positional and attitude information is provided via an Ashtech ADU5 multi-receiver GPS attitude sensor. Ship’s heading information from the vessel’s Gyro, though streamed to and saved by the OS75 logging PC, was not used in the processing steps described here. The RDI proprietary software VMDAS (V1.42) was used to configure the ADCP and perform velocity mapping to the reference frame of the vessel. Bottom tracking was not enabled. A suite of MATLAB routines were used to perform data screening and transformation to absolute velocities in Earth coordinates: A summary of configuration and the processing steps is given below.

OS75 VMADCP Configuration

- No bins = 60
- Bin size = 16 m
- Blank after transmit = 8 m
- Transducer depth = 5.3 m
- Bottom track (when on) maximum depth 1100m
- Time between pings = as fast as possible (typically 5s)
- Low-resolution long-range processing mode

MATLAB Processing Steps

1. RDI binary file with extension ENX (single-ping ADCP ship referenced data from VMDAS) and extension N2R (ASCII NMEA output from ADU5 saved by VMDAS)
read into MATLAB environment. NB: The N2R file consists of ADCP single ping time stamps ($PADCP string) and ADU5 pitch, roll and heading information ($PRDID string). The latter NMEA string is created from the raw ADU5 string ($PASHR,ATT) by a splitter box on board RSS Discovery. The reason for this is that early versions of VMDAS were unable to directly interpret the $PASHR,ATT NMEA string.)

2. Ensembles with no ADCP data removed
3. Ensembles with bad or missing ADU5 GPS heading data identified and adjusted GYRO heading substituted
4. Attitude information time-merged with single ping data
5. Heading data used to rotate single ping ADCP velocities from vessel centreline reference to True North reference
6. Transducer misalignment error corrected for (derived from the misalignment determination – see text below)
7. Ship velocity derived from ADU5 positional information
8. Further data screening performed:
   - Max heading change between pings (10 degrees per ping)
   - Max ship velocity change between pings (>2ms⁻¹pingrate⁻¹)
   - Error velocity greater than twice Stdev of error velocities of single ping profile
9. All data averaged into 600-second super-ensembles (user selectable)
10. Determine absolute water velocities from either bottom track derived ship velocity or ADU5 GPS derived ship velocity. ADU5 derived velocity was favoured during D312

Transducer misalignment and amplitude correction determination:

The misalignment angle of the transducer relative to the vessel ($\alpha$) and the velocity amplitude correction factor where determined as follows. A reference layer velocity between 100 and 300m is calculated from the super-ensembles ($u$ and $v$), and the ship velocity calculated for the corresponding super ensembles ($su$ and $sv$). First differences are taken ($du$, $dv$, $dsu$, and $dsv$) between all possible pair of super ensembles, then differences selected for when the ship speed exceeded 3 ms⁻¹ over the ground between ensembles not more than 5000m or 3600s
apart in space or time. Then the following function was minimised for $\alpha$ and $A$ using the Matlab function FMINSEARCH.m (a multidimensional minimization method).

$$f(A, \alpha) = (Adu \cos \alpha - Adv \sin \alpha + dsu)^2 + (Adu \sin \alpha + Adv \cos \alpha + dsy)^2$$

An initial guess at $A$ and $\langle$ is made in order to perform the minimisation on the superensembles outlined above. The whole processing procedure is then repeated for the newly determined values for $A$ and $\langle$ to give the final absolute velocities. Values estimated by this method: $A=1.00100$, $\langle =59.3393$.

The instruments (ADCP and Ashtech ADU5) both functioned well during the cruise. With the exception of one period of several hours when the ADU5 crashed (00:40 – 09:46 on 22 October 2006), few GPS data dropouts occurred, and typically for no more than a few seconds at a time. Due to the rough weather and consequent frequent presence of air bubbles under the hull and across the transducer face, water profiles where often quite poor (less than 50% percent good at depth as shallow as 180m). An example figure of processed data is shown in Figure 20.

Raw data files in RDI format and processed data files in MATLAB format will be logged with BODC after the cruise, the approximate total quantity of data will be 3GB. Raw RDI data are divided into 22 series (series OSD312_0001 to OSD312_022). Within each series files are subdivided into files of maximum 10MB in size. Series number is incremented each time VMDAS is stopped and restarted; the number of sub-files per series is therefore variable.

Output file formats:

All processed output files are in MATLAB proprietary *.mat binary files, where N denotes the series number (N = 1 to 22 for D312):
Table 6: Contents of processed Matlab data files.

<table>
<thead>
<tr>
<th>File name</th>
<th>Structured array name</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>OSD31200N_00000Nd.mat</td>
<td>d</td>
<td>Single ping ADCP data</td>
</tr>
<tr>
<td>OSD31200N_00000Nd_ATT.mat</td>
<td>att</td>
<td>Heading data at each ADCP ping</td>
</tr>
<tr>
<td>OSD31200N_00000N_ATT.mat</td>
<td>att</td>
<td>Heading data for super ensembles</td>
</tr>
<tr>
<td>OSD31200N_00000N_M_HC.mat</td>
<td>b, c</td>
<td>Super ensembles</td>
</tr>
</tbody>
</table>

Figure 20: Processed OS75 VMADCP data covering approximately the CTD transect from Rockall to the UK shelf.
Generic Processing Procedure

1. Create a directory structure similar to that shown below

   ![Directory Structure]

2. Place all the MATLAB functions supplied from the directory “OS75functions” into the directory of the same name on your PC.
3. Place the file named “OS75_D312.m” in the directory named “m”.
4. Place raw VMDAS files with extensions ENX and N2R into a directory of your choice. The extract below reads data from the “reprocessed” directory, but also has a DVD data disk mounted as the D drive option commented out.
5. Edit (and rename) the file “OS75_D312.m” so the PATH and RAWPATH variables exactly match the full path of these directories on your PC – remember to end with a forward slash “\” character. Lines 24 and 26.
6. Edit the addpath command to the full path location of the OS75functions directory. Line 22.
7. Edit the VMDAS filename for your cruise. Line 4.
8. Choose which series (one or more) number(s) for your cruise you wish to processes (the sub-series files will be automatically loaded). More than one series at a time can be chosen (e.g. “files=[2 3 4 5 6]” is allowed). Line 19.
9. Choose how long the temporal average for the “super ensembles” should be (set to 600s for D312). Line 20.
10. If Bottom Track is on and you want to use it rather than GPS derived ship velocity, then edit the function named “ship_velocity_mei.m” at Line 43. There are comments in this function.
Lowered ADCP (LADCP) - Toby Sherwin, Emily Venables, Terry Edwards,

Two 300 kHz, RDI ‘Workhorse’, Lowered Acoustic Doppler Current Profilers (LADCP) were deployed on the CTD frame throughout the cruise. In general the instruments functioned well, although there were some timing anomalies and occasionally only one of the Master or Slave actually worked. The warning message ‘Beam 3 weak’ was reported for some profiles and needs further investigation. More information on the performance and set up of the LADCPs is provided in the UKORS instrumentation section of this report earlier.

The LADCP data were processed in Matlab using the ‘Visbeck’ v7 data processing suite as a ‘black box’, i.e. without fully understanding how it works and without tuning any parameters. Ship’s navigation and the CTD pressure sensor have both been used to improve the accuracy of the derived profiles. The majority of the profiles had been satisfactorily processed by the end of the cruise.
Figure 21 (previous page): LADCP profile 16185 from the centre of the Ellett gully showing a strong westward current exceeding 1 m s$^{-1}$ in the bottom 200 m, and relatively small error bars throughout the water column.

The overflow in the Wyville Thomson Ridge is a good test of the functionality of the LADCP data, as was demonstrated in CD176. The profile in Figure 21 shows a very realistic and typical velocity profile in the Ellett gully, which without being taken as conclusive evidence of good performance, is a strong indication that the instruments were working satisfactorily.

Figure 22: Eastward velocity section across the Ellett gully. Fast currents in excess of 0.8 m s$^{-1}$ are observed near the seabed. The warm inflow can be seen in the upper layers. The Färöe Bank is on the left and the Ymir Ridge is on the right.

An LADCP section across the gully (Figure 22) shows that a strong overflow was underway during the cruise (even if this was not reflected in the bottom currents). From earlier work (Sherwin and Turrell, 2006) it is suggested that this apparent anomaly may be because the flow had only just started. The apparent vertical oscillation in velocity indicates that a further
vertical low pass filtering is required. The section will be compared with geostrophic velocities derived from the CTD data.

**Inorganic Nutrient Data; Nitrate, Nitrite, Silicate, Phosphate** - Richard Sanders, Ian Rae, Margaret Marks, Stuart Painter

Inorganic nutrients were measured on every bottle from every CTD cast following Sanders and Jickells (2000) using a Skalar San Plus autoanalyser equipped with an all glass phosphate line purchased in 2002 and the integrator that was bought with this. All data was processed in flow access version 1.04.4. In total 634 niskin bottle and 25 underway samples were analysed. Samples were drawn directly from niskin bottles into 25ml sterilin polystyrene coulter counter vials, refrigerated in the dark at 4°C and analysed within 24 hours. Overall seventeen runs were carried out, detailed below in Table 7 with comments regarding significant events. Quite clearly the instrument did not perform well on this trip despite the usual precautions being taken (washing the lines with 10% Decon (N, Si) or Sodium Hydroxide (P), changing the tubes). Despite the various problems encountered all samples were analysed satisfactorily with the exception of phosphate from station 152.

<table>
<thead>
<tr>
<th>Name</th>
<th>Date</th>
<th>Comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>Stations 127-130</td>
<td>13/10/06</td>
<td>New standards and reagents, bulb for P and Si changed</td>
</tr>
<tr>
<td>Stations 131-133</td>
<td>14/10/06</td>
<td></td>
</tr>
<tr>
<td>Stations 134-137</td>
<td>15/10/06</td>
<td>New Standards</td>
</tr>
<tr>
<td>Stations 138-140</td>
<td>16/10/06</td>
<td>Nitrate drift very bad</td>
</tr>
<tr>
<td>Stations 138-140 repeat</td>
<td>16/10/06</td>
<td>Change bulb and redo nitrates from previous station</td>
</tr>
<tr>
<td>Stations 141-142</td>
<td>17/10/06</td>
<td></td>
</tr>
<tr>
<td>Stations 143-144</td>
<td>21/10/06</td>
<td>New Standards, All tubes changed</td>
</tr>
<tr>
<td>Stations 145-147</td>
<td>22/10/06</td>
<td>New nitrate reagents</td>
</tr>
<tr>
<td>------------------</td>
<td>----------</td>
<td>----------------------</td>
</tr>
<tr>
<td>Stations 148-152</td>
<td>23/10/06</td>
<td>P peaks on 152 poor</td>
</tr>
<tr>
<td>Stations 152-157</td>
<td>25/10/06</td>
<td>New standards, New Si ascorbic and Oxalic reagents</td>
</tr>
<tr>
<td>Stations 158-165</td>
<td>26/10/06</td>
<td>Nitrate baseline large drift after station 160, New bulb Si and P, New Si molybdate reagent</td>
</tr>
<tr>
<td>Stations 160-169</td>
<td>26/10/06</td>
<td>New nitrate bulb, large shift in nitrate baseline after standards, new standards placed in run</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Phosphate stations 165-169 poor</td>
</tr>
<tr>
<td>Stations 166-176</td>
<td>27/10/06</td>
<td>Disintegration of nitrate baseline for stations 166-168, solved by shaking flow cell. Phosphate 173-176 poor</td>
</tr>
<tr>
<td>Stations 173-183</td>
<td>28/10/06</td>
<td>New Standards</td>
</tr>
<tr>
<td>Stations 185-186</td>
<td>28/10/06</td>
<td>Nitrate baseline disintegrated</td>
</tr>
<tr>
<td>Stations 185-186 repeat</td>
<td>29/10/06</td>
<td>New nitrate reagents, new standard 3</td>
</tr>
<tr>
<td>Stations 187-194</td>
<td>30/10/06</td>
<td></td>
</tr>
</tbody>
</table>

There are three areas of concern when evaluating data quality. These are i) the reproducibility of measurements on a single day (precision), ii) the absolute accuracy of the measurements and iii) the internal consistency of the dataset. To evaluate these three factors we routinely monitor the performance of the analyser by constructing time series of 1) instrument baseline, 2) correlation coefficient of the calibration curve, 3) the slope of the calibration curve, 4) the concentration of a large volume water sample, 5) the duplicate analyses, 6) the concentration of a nitrite standard used to monitor the performance of the cadmium column and 7) the analysis of Ocean Scientific international nutrient standards. The following section of the
report discusses each of these quality control indices. The report then concludes with a preliminary statement regarding reproducibility, accuracy and internal consistency.

**Baselines**

Figure 23 shows time series of instrument baseline correlation coefficients for the instrument. Large discontinuities in N and Si baselines are associated with changes in bulbs as detailed earlier. However, the cause of the shift is not solely related to the act of changing the bulb for nitrate as it occurred midway through a run. Between these events, the baselines were essentially stable.

![Figure 23: Time series of instrument baselines.](image)

**Sensitivity**

Figure 24 shows time series of the instrument sensitivity in digital units per micromole. The slope of the phosphate calibration curve changed abruptly in response to the change in bulb detailed earlier. However, the silicate slope showed no such abrupt change, instead increasing quasi linearly over the course of the cruise. None of the three baselines showed any sensitivity to changes in reagents.
Figure 24: Instrument sensitivities.

Calibration curves

Figure 25 provides a time series of regression coefficients for the calibration curve. Occasional low values are apparent but generally the instrument behaved in a linear fashion.

Figure 25: Time series of calibration curves.
**Bulk sample**

Figure 26 provides a time series of bulk nutrient concentration. Some of the phosphate data from the bulk sample have been discarded due to the problems encountered with the analyzer or due to difficulties encountered in sampling the bulk standard. All three nutrients show a decline in concentration with time as usually found in bulk samples taken on previous cruises. The phosphate concentration changed radically over a very short period of time from about 1 micromolar to 0.76 micromolar. To evaluate the internal consistency of the dataset we fit a linear regression to the entire nitrate and silicate datasets and in two parts to the phosphate dataset. We then use these regressions to calculate modelled values for each day and then calculate residuals for each point. The size of the residual, when compared to the mean value, is an estimate of the internal consistency. These values were 2.39%, 2.83% and 1.15% for N, P and Si.

![Figure 26: Time series of bulk nutrient concentrations.](image)

**Duplicates**

Some 100 samples were run in duplicate over the course of the cruise. The mean percentage difference between duplicate pairs was 0.7% for nitrate, 1.2% for phosphate and 0.6% for silicate. These values are satisfactory.
Cadmium column efficiency

The efficiency of the cadmium column was highly variable with a mean value of 106 +/- 5%. Column efficiency was not correlated with the residual of the nitrate bulk concentration from the interpolated bulk nitrate concentration or with the slope of the nitrate calibration curve. However it declined over time implying that it may have contributed in some way to the variability in N/P ratio seen.

Standards

Analysis of ocean scientific international solutions with nominal concentrations of N 10 uM, P 1 uM and Si 10 uM produced the following results. N 9.97 +/- 0.03, P 0.99 +/- 0.04, Si, 10.2 +/- 0.07. On the basis of these determinations the Nitrate and Phosphate data is considered to be accurate to within the limits of the instrument whereas the silicate data is considered to be approximately 2% too low. No correction was applied for this.

Conclusions

The dataset obtained is internally consistent to within about 2%, precise to about 0.7% and accurate within these analytical uncertainties. The instrument was extremely problematic. The cause of the problems was never traced however with hindsight an obvious factor that was not evaluated was the integrator.

Dissolved Oxygen Concentration - Stuart Painter, Ian Rae, Richard Sanders

Dissolved oxygen concentrations were determined using the Winkler whole bottle titration method with the aim of providing 1) accurate measurements of in-situ dissolved oxygen concentrations, 2) a calibration tool for the oxygen sensor deployed on the CTD and 3) and an extension to the time series of oxygen measurements obtained from previous Ellett Line cruises.

All seawater samples were drawn through short pieces of silicone tubing from the Niskin bottles into clear, pre-calibrated borosilicate glass bottles (approx 100 ml in volume). The temperature of each sample was measured with a handheld digital thermometer prior to the addition of 1 ml manganous chloride and 1 ml of alkaline iodide (reagents made following Dickson 1994). Glass stoppers were then inserted taking care to avoid bubbles and/or
headspaces in each bottle and the bottle was shaken vigorously for 30 seconds. All Niskin bottles were sampled from every CTD cast (table 1). Samples were taken back to the chemistry lab and left for at least 1 hour before analysis. If time permitted, bottles were left for 1-2 hours before being given a second shaking and then left allowing the precipitate to settle.

Analysis of all samples used the Winkler whole bottle titration method with spectrophotometric end-point and started with the addition of 1 ml of dilute sulphuric acid (280 ml concentrated $\text{H}_2\text{SO}_4$ made up to 1 L with Milli-Q water) to each sample bottle. A small magnetic bar was added to each bottle to facilitate the dissolution of the precipitate, which was aided by placing each bottle onto a magnetic stirring plate. Each bottle was then titrated with sodium thiosulphate until clear. The titration volume (ml) was recorded and used with the initial fixing temperature in the calculations of Dickson (1994) to calculate the dissolved oxygen concentration.

One batch of sodium thiosulphate was made up during the cruise (25g L$^{-1}$) and was tested daily for stability. This was achieved by titrating the sodium thiosulphate against 5 ml of certified potassium iodate standard. The daily mean ($n=5$) volume of thiosulphate required to titrate the iodate standard was then used in the calculation of dissolved oxygen concentration for all samples collected on that day. Thiosulphate stability during the cruise is shown in figure 27.

At each station a number of replicates were taken. Replicate reproducibility improved during the cruise with experience and the cruise mean percentage difference between replicate samples was 1 ± 1%.

Table 8: Stations sampled and problems encountered.

<table>
<thead>
<tr>
<th>Station Number</th>
<th>Number of Depths Sampled</th>
<th>Depth Range (m)</th>
<th>Notes</th>
<th>Failed Titrations (Niskin Number)</th>
</tr>
</thead>
<tbody>
<tr>
<td>16127</td>
<td>13</td>
<td>0 - 626</td>
<td>1st station, multiple replicates, multiple samplers</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>---</td>
<td>---</td>
<td>---</td>
<td>---</td>
<td></td>
</tr>
<tr>
<td>16128</td>
<td>6</td>
<td>0 -114</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16129</td>
<td>12</td>
<td>0 -1400</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16130</td>
<td>12</td>
<td>0 -1663</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16131</td>
<td>12</td>
<td>0 – 1790</td>
<td>2 failed titrations</td>
<td>8, 9</td>
</tr>
<tr>
<td>16132</td>
<td>12</td>
<td>0 -1790</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16133</td>
<td>20</td>
<td>0 -2195</td>
<td>Bottle 15 did not fire, 2 failed titrations</td>
<td>4, 14</td>
</tr>
<tr>
<td>16134</td>
<td>19</td>
<td>0 -2364</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16135</td>
<td>18</td>
<td>0 – 2390</td>
<td>3 failed titrations</td>
<td>1, 5 (rep), 18 (rep)</td>
</tr>
<tr>
<td>16136</td>
<td>20</td>
<td>0 – 2511</td>
<td>7 failed titrations</td>
<td>5, 14, 15, 16, 17, 18, 19</td>
</tr>
<tr>
<td>16137</td>
<td>16</td>
<td>0 – 2756</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16138</td>
<td>16</td>
<td>0 – 2749</td>
<td>2 failed titrations</td>
<td>4, 9</td>
</tr>
<tr>
<td>16140</td>
<td>20</td>
<td>0 – 2826</td>
<td>1 failed titration</td>
<td>8</td>
</tr>
<tr>
<td>16141</td>
<td>19</td>
<td>0 -2705</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16142</td>
<td>18</td>
<td>0 – 2640</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16143</td>
<td>15</td>
<td>0 – 1200</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16144</td>
<td>12</td>
<td>0 – 660</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16145</td>
<td>11</td>
<td>0 – 430</td>
<td>1 failed titration</td>
<td>5</td>
</tr>
<tr>
<td>16146</td>
<td>4</td>
<td>0 – 135</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16147</td>
<td>5</td>
<td>0 – 163</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Run Number</td>
<td>Time</td>
<td>Duration</td>
<td>Notes</td>
<td></td>
</tr>
<tr>
<td>------------</td>
<td>------</td>
<td>----------</td>
<td>-------</td>
<td></td>
</tr>
<tr>
<td>16148</td>
<td>6</td>
<td>0 – 280</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16149</td>
<td>12</td>
<td>0 – 1060</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16150</td>
<td>16</td>
<td>0 – 1440</td>
<td>Bottle 15 did not fire</td>
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<td>29/10/2006</td>
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</table>

Figure 27: Sodium thiosulphate stability tests. Mean titration volumes are shown (n = 5) with error bars representing ±1 standard deviation of the mean.

**Problems**

Several problems occurred during the cruise, including poorly closed Niskin bottles and failed titrations. Niskin bottles failing to close properly happened four times (bottle 15 in all cases) and as a precaution a duplicate Niskin bottle was fired at the same depth from station 16151 onwards if bottle 15 was to be used. Titration failures accounted for a loss of ~5% of all samples (excluding replicates) and were a persistent problem during the early stages of the
cruise. These failures seemed to be systematic with two primary causes, one was attributed to the roll of the ship in high seas and the second was the placement of the sample bottles within the spectrophotometer beam. The first cause could not be anticipated, and neither could it be definitively identified but may actually have resulted from minor movements of the sample bottle in a manner similar to problem two. Although by no means a definitive statement solving the second problem seems to have eliminated the first problem as well.

The second problem of poor placement was resolved by ensuring that all sample bottles were located as far forward as possible on the magnetic stirrer plate. This positioned the sample bottles in direct alignment with the photometer beam and would suggest that the photometer is slightly skewed with respect to the stirrer plate. Taking such precautions reduced, but did not eliminate further titration failures.

A third minor problem was also encountered with bottles that had a frosted labelling section on them as this would obscure the spectrophotometer beam and produced poor titration values. This was resolved by simply ensuring that the frosted section was pointing towards the back of the stirrer plate and at 90° to the photometer beam. In future such bottles should be avoided.

Results

The results were processed during the cruise and will be available from BODC in due course. Dissolved oxygen concentrations along transects ranged from 215 – 300 µmol O₂ L⁻¹ and were higher at depth than in surface waters (Figure 28). N.B. Figure 28 also shows outlier data which will be removed from the final submitted dataset). Vertical profiles reveal, as expected, the presence of an oxygen minimum at ~800m depth (Figure 29). Surface dissolved oxygen concentrations were variable depending upon the sampling location. Concentrations below 800m were more uniform but a distinct separation in the data can be observed when stations from west of Rockall are compared to stations east of Rockall, particularly in the depth range 800 – 1400m.

Preliminary contoured sections of the dataset, with outliers removed (contoured in Pstar) are shown in Figure 29 (Iceland Basin) and Figure 30 (Rockall Trough).
Figure 28: Vertical profiles from all sampled stations. N.B. this figure includes all results including outlier values that will be removed from the final dataset. Data shown is from stations 16127 to 16186.

Figure 29: Preliminary contoured section of dissolved oxygen concentrations for the Iceland Basin (data contoured in Pstar).
Particulate Organic Carbon (POC), chlorophyll and HPLC sampling – Katie Evans, Maria Pöllüü, Richard Sanders

Samples were taken from 12 stations during the cruise for POC, chlorophyll and HPLC analyses, with the aim of relating the depth penetration of POC to the upper ocean biological community. Stations were selected through consideration of water depth, and topographic influence. Deep-water stations, with minimal influence from bottom topography were favoured. Time constraints also played a role, as the need to re-use each bottle to take the samples, meant that adequate time to complete filtering between POC stations was necessary; consequently it was rarely feasible to take samples from two consecutive stations.

Typically the depth of samples ranged from 5m to 350m, with 3 litres of water taken at eight depths for POC analyses, and 5 litres taken from surface (5-10m) for HPLC analyses. In addition chlorophyll samples were taken at each depth from 5 – 350m. Replicates were also taken for both POC and chlorophyll, although a limited supply of filters meant this was not possible for all twelve stations.

**POC analyses:**

Water samples from CTD bottles (3 litres) were taken from each depth, and filtered onto MF filters, 25mm, (pre-combusted at 400°C). They were then stored at -80°C, to be analysed at NOCS.
**Pigments: chlorophyll**

For each POC and underway station, chlorophyll samples were obtained by filtering 250 ml of sea water onto Whatman 25 mm GF/F filters to yield total chlorophyll. Filters were then placed in the -80°C freezer for analyses at NOCS.

**Pigments: HPLC**

For each of the POC stations HPLC samples were taken from the surface (5-10m), by filtering 5 litres of seawater onto 25mm Whatman GF/F filters that were then frozen at -80 °C for later HPLC analyses at NOCS.

**Underway Chlorophyll samples:**

Table 9: The underway Chlorophyll samples.

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</tr>
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### POC / Chlorophyll stations:

**Table 10:** Discovery Station: 16133, Station: IB16.

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</tr>
<tr>
<td>19</td>
<td>7.4</td>
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<tr>
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<td>POC /chl</td>
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<td>14</td>
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**Table 11:** Discovery Station: 16134, Station: IB15.

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<td>17</td>
<td>54</td>
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<td>Niskin Bottle</td>
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<td>Samples taken</td>
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<td>-------------</td>
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Table 13: Discovery Station: 16137, Station: STNW.
Table 14: Discovery Station: 16140, Station: STNC.

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Table 17: Discovery Station: 16144, Station: IB3.

<table>
<thead>
<tr>
<th>Niskin Bottle</th>
<th>fpress dbar</th>
<th>Samples taken</th>
</tr>
</thead>
<tbody>
<tr>
<td>12</td>
<td>12.2</td>
<td>HPLC</td>
</tr>
<tr>
<td>11</td>
<td>12.6</td>
<td>POC / chl</td>
</tr>
<tr>
<td>10</td>
<td>51.7</td>
<td>POC / chl</td>
</tr>
<tr>
<td>9</td>
<td>104.5</td>
<td>POC / chl</td>
</tr>
<tr>
<td>8</td>
<td>152.3</td>
<td>POC / chl</td>
</tr>
<tr>
<td>7</td>
<td>203.8</td>
<td>POC / chl</td>
</tr>
<tr>
<td>6</td>
<td>252.9</td>
<td>POC / chl</td>
</tr>
<tr>
<td>5</td>
<td>306</td>
<td>POC / chl</td>
</tr>
<tr>
<td>4</td>
<td>354.5</td>
<td>POC / chl</td>
</tr>
</tbody>
</table>
Table 18: Discovery Station: 16153, Station: F.

<table>
<thead>
<tr>
<th>Niskin Bottle</th>
<th>fpress dbar</th>
<th>Samples taken</th>
</tr>
</thead>
<tbody>
<tr>
<td>20</td>
<td>7.9</td>
<td>HPLC</td>
</tr>
<tr>
<td>19</td>
<td>7.4</td>
<td>POC / chl</td>
</tr>
<tr>
<td>18</td>
<td>54.5</td>
<td>POC / chl</td>
</tr>
<tr>
<td>17</td>
<td>104.6</td>
<td>POC / chl</td>
</tr>
<tr>
<td>16</td>
<td>154.5</td>
<td>POC / chl</td>
</tr>
<tr>
<td>14</td>
<td>205.4</td>
<td>POC / chl</td>
</tr>
<tr>
<td>13</td>
<td>256.7</td>
<td>POC / chl</td>
</tr>
<tr>
<td>12</td>
<td>305</td>
<td>POC / chl</td>
</tr>
<tr>
<td>11</td>
<td>406</td>
<td>POC / chl</td>
</tr>
</tbody>
</table>

Table 19: Discovery Station: 16155, Station: H.

<table>
<thead>
<tr>
<th>Niskin Bottle</th>
<th>fpress dbar</th>
<th>Samples taken</th>
</tr>
</thead>
<tbody>
<tr>
<td>20</td>
<td>12.4</td>
<td>HPLC</td>
</tr>
<tr>
<td>19</td>
<td>12.8</td>
<td>POC / chl</td>
</tr>
<tr>
<td>18</td>
<td>53</td>
<td>POC / chl</td>
</tr>
<tr>
<td>17</td>
<td>103.9</td>
<td>POC / chl</td>
</tr>
<tr>
<td>16</td>
<td>154.3</td>
<td>POC / chl</td>
</tr>
<tr>
<td>14</td>
<td>204.7</td>
<td>POC / chl</td>
</tr>
<tr>
<td>13</td>
<td>255.1</td>
<td>POC / chl</td>
</tr>
<tr>
<td>12</td>
<td>305</td>
<td>POC / chl</td>
</tr>
<tr>
<td>11</td>
<td>357.2</td>
<td>POC / chl</td>
</tr>
</tbody>
</table>
Table 20: Discovery Station: 16159, Station: L.

<table>
<thead>
<tr>
<th>Niskin Bottle</th>
<th>fpress dbar</th>
<th>Samples taken</th>
</tr>
</thead>
<tbody>
<tr>
<td>19</td>
<td>6.4</td>
<td>HPLC</td>
</tr>
<tr>
<td>18</td>
<td>6.4</td>
<td>POC / chl</td>
</tr>
<tr>
<td>17</td>
<td>51.7</td>
<td>POC / chl</td>
</tr>
<tr>
<td>14</td>
<td>102.5</td>
<td>POC / chl</td>
</tr>
<tr>
<td>13</td>
<td>152.3</td>
<td>POC / chl</td>
</tr>
<tr>
<td>12</td>
<td>203</td>
<td>POC / chl</td>
</tr>
<tr>
<td>11</td>
<td>253.1</td>
<td>POC / chl</td>
</tr>
<tr>
<td>10</td>
<td>304.5</td>
<td>POC / chl</td>
</tr>
<tr>
<td>9</td>
<td>355.8</td>
<td>POC / chl</td>
</tr>
</tbody>
</table>

Table 21: Discovery Station: 16161, Station: N.

<table>
<thead>
<tr>
<th>Niskin Bottle</th>
<th>fpress dbar</th>
<th>Samples taken</th>
</tr>
</thead>
<tbody>
<tr>
<td>18</td>
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<tr>
<td>17</td>
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<td>POC / chl</td>
</tr>
<tr>
<td>16</td>
<td>52.8</td>
<td>POC / chl</td>
</tr>
<tr>
<td>14</td>
<td>103.6</td>
<td>POC / chl</td>
</tr>
<tr>
<td>13</td>
<td>154</td>
<td>POC / chl</td>
</tr>
<tr>
<td>12</td>
<td>205.6</td>
<td>POC / chl</td>
</tr>
<tr>
<td>11</td>
<td>255.5</td>
<td>POC / chl</td>
</tr>
</tbody>
</table>
Trace Aluminium sampling - Toby Sherwin, Emily Venables

Samples were taken from the Rosette sampler at 19 CTD stations, which were located on the Ellett Line (15), on the southern side of the Wyville Thomson Ridge (3, including 1 precision sample) along with a sedimentary trap mooring (1 precision sample). A procedural blank was taken from Sta 1G at the end of the cruise. Typically 10 Niskin bottles were sampled per CTD station, following the strategy discussed before the cruise, and from each bottle one filtered and one unfiltered sample was taken. Towards the end of the cruise, when it became apparent that there was going to be a surplus of sample bottles, the number of Niskin bottles sampled per cast was increased to 14. The sampling strategy aimed to provide a fairly even distribution of aluminium samples over the water column along the deep water of the Ellett line. At the edge of the Rockall and Iceland shelves samples were concentrated near the bottom. On the Wyville Thomson Ridge gully the emphasis was on sampling the bottom waters that were crossing the ridge, in an attempt to identify the source waters to the north of the Rockall Trough.

The sampling procedure followed the protocol prepared by Clare Johnson before the cruise and all samples had either Emily Venables or Toby Sherwin leading the sample taking.

After trial and error the filling protocol was adapted to make it as efficient as possible whilst also conforming to Clare’s requirements. One person held the syringe and tube and stayed at the frame, whilst the other ferried bottles back and forth from under cover to the Niskin bottles. The procedure worked along these lines: The syringe holder attached the tube to the tap of a Niskin bottle and flushed the syringe twice, whilst the bottle carrier took the sample bottles from the last Niskin to the under cover store and returned with new ones and a new filter. The bottle carrier handed the filter to the syringe holder who then filled the syringe a third time whilst the bottle holder opened the unfiltered sample bottle. Then whilst the bottle carrier collected the unfiltered sample, the syringe holder stood to one side and flushed the filter with the water in the syringe. Then while the bottle carrier opened the unfiltered bottle, the syringe holder refilled the syringe and reattached the filter ready to deliver the filtered sample. The bottle carrier then flushed the sample bottle, which was subsequently filled with the filtered sampled.

To further speed up the sampling procedure a ‘scribe’ was employed to write down the numbers of the sample bottles which, sometimes randomly and sometimes in order, were
selected from a 20 bottle bag. These numbers can be found on the aluminium sampling sheets.

At nearly all stations, the filter was placed in a bag with the filtered sample, whilst the unfiltered sample was placed in a bag on its own. Both filtered and unfiltered bottles were then placed together in a large aluminium bag marked with the cruise identification (D132), station name and CTD number and stored in a chest freezer.

A few further points should be noted. i) although the talcum free plastic ‘gloves’ were slippery and it was often quite difficult to open the sample bottle bags with them. ii) whilst the plastic tube fitted the Niskin tap, it was too large for the syringe. Using a blower drier to warm it we had to reshape the nozzle end of the tube to fit the syringe intake; iii) unlike on CD176 the crew did not always pay close attention to the no smoking request. The door to the ‘coffee shop’ rest room was situated close to the CTD access area and, whilst there is no real reason to believe that samples have been compromised, it is necessary to report this situation. iv) no incineration was undertaken during sampling.

These data will be analysed by Clare Johnson, a PhD student at SAMS.

Table 22: Stations at which Aluminium sampling occurred.

<table>
<thead>
<tr>
<th>Discovery no.</th>
<th>Station name</th>
<th>No of Niskin bottles sample</th>
</tr>
</thead>
<tbody>
<tr>
<td>16129</td>
<td>IB20S</td>
<td>10</td>
</tr>
<tr>
<td>16131</td>
<td>IB18S</td>
<td>10</td>
</tr>
<tr>
<td>16133</td>
<td>IB16</td>
<td>10</td>
</tr>
<tr>
<td>16138</td>
<td>STC</td>
<td>1 (Precision protocol)</td>
</tr>
<tr>
<td>16143</td>
<td>IB4A</td>
<td>10</td>
</tr>
<tr>
<td>16145</td>
<td>IB2</td>
<td>9</td>
</tr>
<tr>
<td>16148</td>
<td>C</td>
<td>6</td>
</tr>
<tr>
<td>16149</td>
<td>D</td>
<td>10</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
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<tr>
<td>---</td>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td>16150</td>
<td>D1</td>
<td>10</td>
</tr>
<tr>
<td>16151</td>
<td>E</td>
<td>10</td>
</tr>
<tr>
<td>16152</td>
<td>E1</td>
<td>10</td>
</tr>
<tr>
<td>16153</td>
<td>F</td>
<td>10</td>
</tr>
<tr>
<td>16154</td>
<td>G</td>
<td>14</td>
</tr>
<tr>
<td>16155</td>
<td>H</td>
<td>14</td>
</tr>
<tr>
<td>16156</td>
<td>I</td>
<td>10</td>
</tr>
<tr>
<td>16172</td>
<td>9G</td>
<td>5*</td>
</tr>
<tr>
<td>16183</td>
<td>W6</td>
<td>14</td>
</tr>
<tr>
<td>16185</td>
<td>W8</td>
<td>14</td>
</tr>
<tr>
<td>16186</td>
<td>W9</td>
<td>1 (Precision protocol)</td>
</tr>
<tr>
<td>16194</td>
<td>1G</td>
<td>Procedural blank</td>
</tr>
</tbody>
</table>

*Double samples from each bottle*
Figure 31: The CTD frame in its sampling position in relation to i) the door to the coffee shop (to the left of the white steps) and ii) the entrance to the ship (beneath the green steps) where bottles were stored during sampling.

**Shear Microstructure profiler measurements - Mark Inall**

Unfortunately after only 6 casts the MSS90 microstructure profiler was lost. Here follows the Captain’s Incident and Investigation report pertaining to the loss.
RRS DISCOVERY INCIDENT & INVESTIGATION REPORT

INCIDENT Report No: 053

<table>
<thead>
<tr>
<th><strong>Type</strong></th>
<th>Loss of SAMS Turbulence Probe</th>
<th><strong>Date:</strong> 26/10/06</th>
<th><strong>Time:</strong> 2025 (UT)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Geographical Position:</strong></td>
<td></td>
<td><strong>Geographical Location:</strong></td>
<td></td>
</tr>
<tr>
<td>56 40.05N 007 34.80W</td>
<td>7nm SSE of Barra Head</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Location on Ship:</strong> Small winch mounted on bulwarks, stbd aft.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Weather:</strong> Wind NNE 15 knots. Slt sea; low swell.</td>
<td><strong>Course:</strong> 060 (G), 095 CMG</td>
<td><strong>Speed:</strong> 1.2 knots (thro’ water; approx 1.0 knot over ground)</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Activity:</strong> Tide cycle measurements of turbulence through water column.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Nature of Incident:</strong> Profiler fouled on seabed @ extremity of freefall. V/l could not be stopped over ground in sufficient time, or cable veered sufficiently quickly, to prevent parting of cable at seabed. All cable - bar possibly last few metres - recovered.</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Investigation:**

A standard procedure - undertaken many times by SAMS scientists with this type of instrument at many different shelf-break locations - was taking place.

The procedure involved allowing the instrument to free-fall via just sufficient slack cable until a levelling-off of pressure indicated that the instrument was at the seabed. (It is standard practice to allow the instrument to land on the seabed). Heaving then started immediately.

On this occasion, after hauling for about 10 seconds, the cable tension indicated fouling. A call from the Deck to the Bridge requested the vessel to heave-to, and the cable was veered.

Unfortunately the subsequent v/l manoeuvres allied with an inability to allow the cable to free-run caused increased tension on - and ultimately parting of - the cable.
Scratch marks on the cable were consistent with a cut caused possibly by coral.

Proper procedures were being followed both on deck and on the Bridge. Communications were good and operating conditions were normal. Best efforts were made to rectify the problem once it occurred.

**Conclusion & Recommendations:**

A meeting between M. Inall (SAMS), T. Edwards (OED TLO) – both operating the equipment on the aft deck at the time of the incident – and P. Sarjeant (Master) – conning the vessel – concluded the following:

Ideally a pre-survey of bottom topography and improved knowledge of bottom type should be available prior to profiling on a new location.

A winch system that facilitated ‘free-wheel’ pay out of up to 400m of cable in the event of seabed fouling would be beneficial.

**Completed By:**

Peter Sarjeant - Master

---

**Mesozooplankton net sampling** – Maria Pöllupüü, Timo Arula, Toby Sherwin

**Sample collection**

The plankton net was attached to the deck winch and lowered to a max depth of 100 m and retrieved at a speed of about 0.5 to 1m per second. When the net was back on deck, the net was rinsed down using the ships hose so that animals attached to the net mesh were washed into the cod end, the mesh windows of the cod end were also rinsed down. The contents were drained into the bucket. The sample was concentrated by pouring it through a sieve and then washed into a sample bottle.

**Sample preservation**

Depending of the sample volume the appropriate size (250 or 500 ml) sample containers were used. Formaldehyde (40%) was poured into the sample to create a final concentration in the
A sample of about 5% formalin. For example, for a sample volume of about 100 ml about 5 ml of formaldehyde was added.

A waterproof sample label was put in the sample container with the following details: sample station, date, time, sample depth, cruise no, collector name + container was labelled outside with the sample station.

Table 23: Zooplankton sampling stations on the Ellett Line October 2006.

<table>
<thead>
<tr>
<th>Sample</th>
<th>Station</th>
<th>Date</th>
<th>Time</th>
<th>Sample depth (m)</th>
<th>Latitude</th>
<th>Longitude</th>
<th>Bottom depth (m)</th>
<th>Collector</th>
</tr>
</thead>
<tbody>
<tr>
<td>ZOO 001</td>
<td>16153 (F)</td>
<td>24/10</td>
<td>10.46</td>
<td>100</td>
<td>57 30.99 N</td>
<td>12 14.963 W</td>
<td>1804</td>
<td>M. Põllupüü</td>
</tr>
<tr>
<td>ZOO 002</td>
<td>16155 (H)</td>
<td>24/10</td>
<td>21.25</td>
<td>100</td>
<td>57 30.114 N</td>
<td>11 31.519 W</td>
<td>2025</td>
<td>M. Põllupüü</td>
</tr>
<tr>
<td>ZOO 003</td>
<td>16157 (J)</td>
<td>25/10</td>
<td>05.35</td>
<td>100</td>
<td>57 27.220 N</td>
<td>11 05.404 W</td>
<td>582</td>
<td>T. Arula</td>
</tr>
<tr>
<td>ZOO 004</td>
<td>16159 (L)</td>
<td>25/10</td>
<td>12.29</td>
<td>100</td>
<td>57 22.0816 N</td>
<td>10 39.6299 W</td>
<td>2138</td>
<td>T. Arula</td>
</tr>
<tr>
<td>ZOO 005</td>
<td>16160 (M)</td>
<td>25/10</td>
<td>17.30</td>
<td>100</td>
<td>57 18.563 N</td>
<td>10 22.415 W</td>
<td>2207</td>
<td>M. Põllupüü</td>
</tr>
<tr>
<td>ZOO 006</td>
<td>16164 (Q)</td>
<td>26/10</td>
<td>06.10</td>
<td>100</td>
<td>57 03.236 N</td>
<td>09 13.729 W</td>
<td>355</td>
<td>T. Arula</td>
</tr>
<tr>
<td>ZOO 007</td>
<td>16165 (R)</td>
<td>26/10</td>
<td>08.00</td>
<td>100</td>
<td>56 59.899 N</td>
<td>09 00.321 W</td>
<td>137</td>
<td>M. Põllupüü</td>
</tr>
</tbody>
</table>
Nets were not deployed at stations A, C, D and E due to rough weather conditions.

**Wyville Thomson Ridge bathymetry** - *Toby Sherwin*

The bathymetric data collected during the brief survey of the Ellett gully have been used in conjunction with data collected during Scotia cruise SC0804 to produce a new bathymetry for the gully. These data have been added to previous data collected by Dave Ellett, during CD176 and during previous Scotia cruises. In addition all data from the Scotia cruises have undergone additional de-sping. All data were pooled into squares of 0.005° latitude and 0.01° longitude (i.e. about 500 m square) before being gridded with a Krigging technique and plotted with Surfer. A full data check is required before this chart can be considered definitive.

The new bathymetry removes a small ridge across the gully that appeared in the previous version at about 8.93° W. A secondary gully that was previously present on the northern side of the gully at 8.75° W has also disappeared.
Figure 32: A draft version of the revised bathymetry of the Ellett gully, also showing CTD stations on the W line (‘+’, not all of which were sampled). The moored SC-ADCP was deployed along this line at the deepest part of the gully.

**Artist’s report – Margaret Marks**

I am one of 20 artists from Artel; a professional contemporary art group based in Chichester, who are involved in an art/science collaboration with NOCS, the National Oceanography Centre, Southampton. The ensuing outcome of art from this association, will be an exhibition entitled The Oceanography Project at the Bargate Monument Gallery and the medieval city vaults in Southampton, in June 2007. As part of the collaboration I have been able to join this cruise both as an artist and also to be part of a watch assisting the scientists in their data collection.

I work in digital media and in textiles, often the techniques and imagery of one informing the other. I like to produce patterns, repeating movements, text and sound to express my ideas. My area of artistic research has usually been in the study of facial expression and the thoughts that that may exist behind them.
My aim was to visually study the scientists and crew in their activities during the cruise and to get an insight into their work. To this end I have collected several hours of video and about 500 photographs.

Figure 33: Visual studies of scientists at work.

I also provided mobile phones for each watch to photograph images of their interest over a 12 hour period. I have collected scientists’ rough notes, weather charts, ship’s plans, chart readings, acronyms, nomenclature, statistics and ‘plans of action’ with the intention of amalgamating these into film or into textiles. The final films will be produced after extensive editing, image manipulation, drawing into the film and additional animation.

An opportunist project, completed on board, was the production of 19 sketches of each scientist onto polystyrene cups. These were sent to 2000 metres on a CTD thus pressurising them to miniatures.
Thorpe scale analysis is a technique that allows measurements of fine scale temperature or density structure to be converted into estimates of vertical diffusion in the ocean. Although the method was originally developed for measurements made in freshwater lakes, it has been adapted to the ocean in particular using tethered free falling floats (Inall, pers. comm.) and sub-surface drifters. Other investigations have demonstrated that under certain conditions realistic vertical diffusion coefficients can be derived from a conventional fast sampling CTD (see e.g. Stansfield et al., 2001 and Sherwin and Turrell, 2005). During D312 we have undertaken a further investigation with a CTD combined with a full rosette of 24 water bottles.
Figure 35: Detail of the CTD frame and rosette sampler system. The primary CTD sensors are attached to the bottom of the vane on the right. The secondary sensors are strapped to the top of the right hand horizontal cylinder beneath the bottles.

**Methodology**

On D312 observations were made with two Seabird 911 plus CTDs, which sample at 24 Hz and use a pumped system on the conductivity sensor to derive very accurate measurements of conductivity. Two CTDs were used, the primary one was located on a stabilising fin on the outside of the frame, whilst a secondary one was placed near the bottom on the inside of the frame (see Figure 35).

In the present exercise we have tackled three things that complicate the problem of performing a Thorpe scale analysis on data from a conventional CTD rosette system carried by a ship at sea. These problems are over and above those that might be expected with measurements made from a stable platform in a freshwater lake. The principle problems at sea are:

1. Ship motion, in particular rolling in heavy seas when the winch mechanism does not compensate the movement and the CTD is periodically dragged back upwards during its descent phase.
2. A non-monotonic relationship between temperature and salinity, due to mixing of water masses, coupled to
3. A salinity signal that is significantly less stable than temperature
**Rolling**

The CTD on *Discovery* is deployed a little aft of amidships on the starboard side from a hydrographic winch that projects about 2 m from the hull, and is normally lowered at about 1 m s\(^{-1}\). Since *Discovery* itself is about 14 m wide this means that the hydrographic wire is positioned about 9 m from the centre of motion rolling. (*Discovery* is sufficiently long (90.25 m) and the wire sufficiently close to midships that pitching is not a significant problem.) Thus typical roll of 5° results in a potential vertical movement of the wire of about 0.8 m. During much of D312 the swell was often large, with on many occasions a range of about 5 m and period of 8 to 10 s. Under these conditions, the pressure record indicates that the motion of the ship was directly transferred to the CTD frame. The problem might have been reduced had the heave compensation mechanism on the winch been working during the cruise.
Figure 36: Detailed presentation of primary sensor data at 24 Hz during a roll.

The effect of ship movement was to cause the CTD to periodically oscillate and often reverse its descent, rising through the water column by up to 2 m. The precise motion of the frame varied from one roll to another, but a good example is shown in Fig. 2, taken from Sta. 16127. The pressure sensor initially descended to 309.5 dbar, but then rose back to 308.2 dbar before continuing its descent. During the first phase of the roll the primary thermistor (located on a vane attached to the side of the frame) detected a potential temperature of about 8.274 °C at 309.5 dbar, but on its second pass this water appeared to have cooled by about 3 millidegrees. A little later, at 310.3 dbar, the thermistor passed through a patch of warm water, about 0.5 m thick, with a maximum temperature of 8.287 °C. The sensors were finally clear of the mixing region at 311 m. At the same time the conductivity sensor observed a
similar effect, and a TS plot showed that the temperature and salinity compensated each other.

The secondary sensors located inside the frame were also disrupted. During a normal descent these sensors measured very similar temperatures to the primary ones. However, the initial reversal resulted in a larger temperature rise (0.03 °C), and the secondary pulse (observed at 311 m) whilst less severe (a rise of 0.015 °C) lasted longer so that the sensors were not fully clear of the mixing zone until about 313 m.

An interpretation of these effects is summarised in Figure 37. Normally when the CTD descends undisturbed water beneath it flows through the frame and past both sensors in a satisfactory manner (Figure 37a). However, if its descent is suddenly reversed then as it rises the motion draws in undisturbed water from beneath the frame and ejects water that was previously trapped inside it (Figure 37b). As a result when the CTD starts to descend again (Figure 37c) it passes through the ejected warm water that now lies in a pool beneath it.

![Figure 37](image)

Figure 37: Schematic representation of the effects of ship rolling on the performance of a CTD frame. 1 and 2 are the primary and secondary sensors. LH panel: normal operation of descent – water sweeps up past the sensors. Middle panel: temporary upward movement of frame – water trapped in frame is ejected from the base. RH panel. Return to descent – sensors now pass through ejected water.
Rolls have been detected and eliminated using the Seabird post-processing suite LOOPEDIT, which flags bad data, combined with some additional analysis. The Seabird manual does not explain precisely how LOOPEDIT works but tests suggest that it is more sophisticated than simply eliminating all velocities below the user set minimum speed (20 cm s⁻¹). However, it does not eliminate the unwanted secondary effects of a roll on the high frequency density profile. To do this it has been necessary to ignore all measurements made from the start of a reversal until the CTD had travelled 2 m below the previous maximum depth. However, as no two rolls were the same and to minimise the loss of data, observations were accepted from 2.5 s after the roll has ended even if the frame has not descended the necessary 2 m.

**Salinity related problems**

Ideally Thorpe length scales should be based on potential density, ρ₀, and in theory this should not be difficult since the Seabird CTD makes very accurate measurements. However, previous tests and analysis of another Seabird system has demonstrated that the conductivity signal has a significant noise level that can only be eliminated to the level that we require by averaging over large periods of time (see appendix and Sherwin and Lichtman, 2004). By contrast the temperature signal was very stable. This means that a straightforward conversion of temperature, conductivity and pressure to the stable accuracy required here is not possible, even after low pass filtering to 1 second intervals. On the Wyville Thomson Ridge this problem was easily overcome because potential temperature, θ, is mapped monotonically onto salinity, S, and so could be treated as a tracer (Sherwin and Turrell, 2005). In the Iceland Basin this is not always the case.

A single routine has been written to overcome these two problems. The method is simply to divide the profile into typically 9 m bins, and apply a least squares linear fit, such that for each bin, i,

\[ S_i = a_i + b_i \theta_i. \]  

(1)

Then at each data point the original salinity, \( S_i \), is replaced with a new one, \( s_i \) mapped from the observed \( \theta_i \) using (1). Using \( s_i \) should thus result in a less noisy potential density profile than using \( S_i \). In order to reduce any mismatches at the join between two bins a low pass filter was subsequently applied to each of the two series of linear coefficients, \( a_i \) and \( b_i \).
Potential density can then be calculated as $\rho_o = f(p, s, \theta)$, where $p$ is pressure, instead of the more noisy $\rho_o = f(p, S, \theta)$.

**Results**

Estimates of the spatial distribution of the vertical diffusion coefficient, $K_Z$, have been made during the cruise. Preliminary results suggest that the method may have some merit to it with indications of larger mixing rates near the Icelandic shelf edge than in the basin itself. The results are being compared with Richardson number estimates and the turbulence probe data.

**Appendix**

**Thorpe scale calculations**

Temperature profiles in lakes, when resolved to fine scales, reveal dynamic instabilities that Thorpe (1977) showed could be indicative of vertical mixing. Subsequent workers (e.g. Dillon, 1982, Crawford, 1986, Stansfield et al., 2001) have confirmed that in the ocean such instabilities can be related to turbulent dissipation, and hence used to estimate vertical diffusion coefficients, $K_Z$.

The derived density and pressure data were averaged over 0.1 dbar segments, and then reordered in the water column so that density increased monotonically with depth to give a dynamically stable profile. The distances that each segment moved up or down, $d$, were then used to compute the Thorpe scale from $L_T = \sqrt{\langle d^2 \rangle}$, where the angle brackets indicate an averaging process. On D312 case $d^2$ was smoothed with a filter width of about 30 m. The diffusion coefficient was then found from a semi-empirical formula (see Dillon, 1982)

$$K_Z = 0.128 L_T^2 N$$

(A.1)

where $N^2 = -\frac{g d\rho}{\rho d\bar{\rho}}$ is the local buoyancy frequency derived from the reordered profile.

A detailed investigation has previously been made of the performance of the Seabird 911plus, both under laboratory conditions and at sea, the latter by taking data from the bottom of a cast in the Färö-Shetland Channel where the state variables were almost uniform. The temperature sensor appeared to perform to the manufacturer’s specification (resolution of...
0.0002 °C), but in any case was averaged over 0.1 dbar. There was a small amount of high
frequency electrical and vibration noise in the pressure signal, which had a standard deviation
of 0.046 dbar in the laboratory and 0.01 dbar at sea. However, this noise is insignificant -
using worst-case values of $L_T = 0.046$, and $N = 1 \times 10^{-5}$, (A.1) gives $K_Z = 2.9 \times 10^{-9}$ m$^2$ s$^{-1}$, which
is several orders smaller than values quoted here. The salinity signal had a significant
oscillation at 4.3 Hz with an amplitude that varied between 0.01 units in the laboratory and
0.001 units at sea. Values of $N^2$ were smoothed using a Hamming filter with a 5 to 50 m half
width (depending on the water depth) to remove any small density inversions that still
remained.

Acknowledgements

The weather experienced during this autumnal cruise was not particularly memorable for its
extremes, however it was remarkable for its consistency and that its consistent state was
‘marginal’ regarding any deck work. I think the Scots word ‘dreich’ sums up the conditions
rather well! Nonetheless, D312 achieved 80-85 % of its objectives and this is testament to
the exemplary teamwork achieved by the Master, officers, crew, engineers and scientists
involved in the cruise. Their enthusiasm, patience and professionalism enabled me to remain
focussed on the job in hand - many thanks.

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